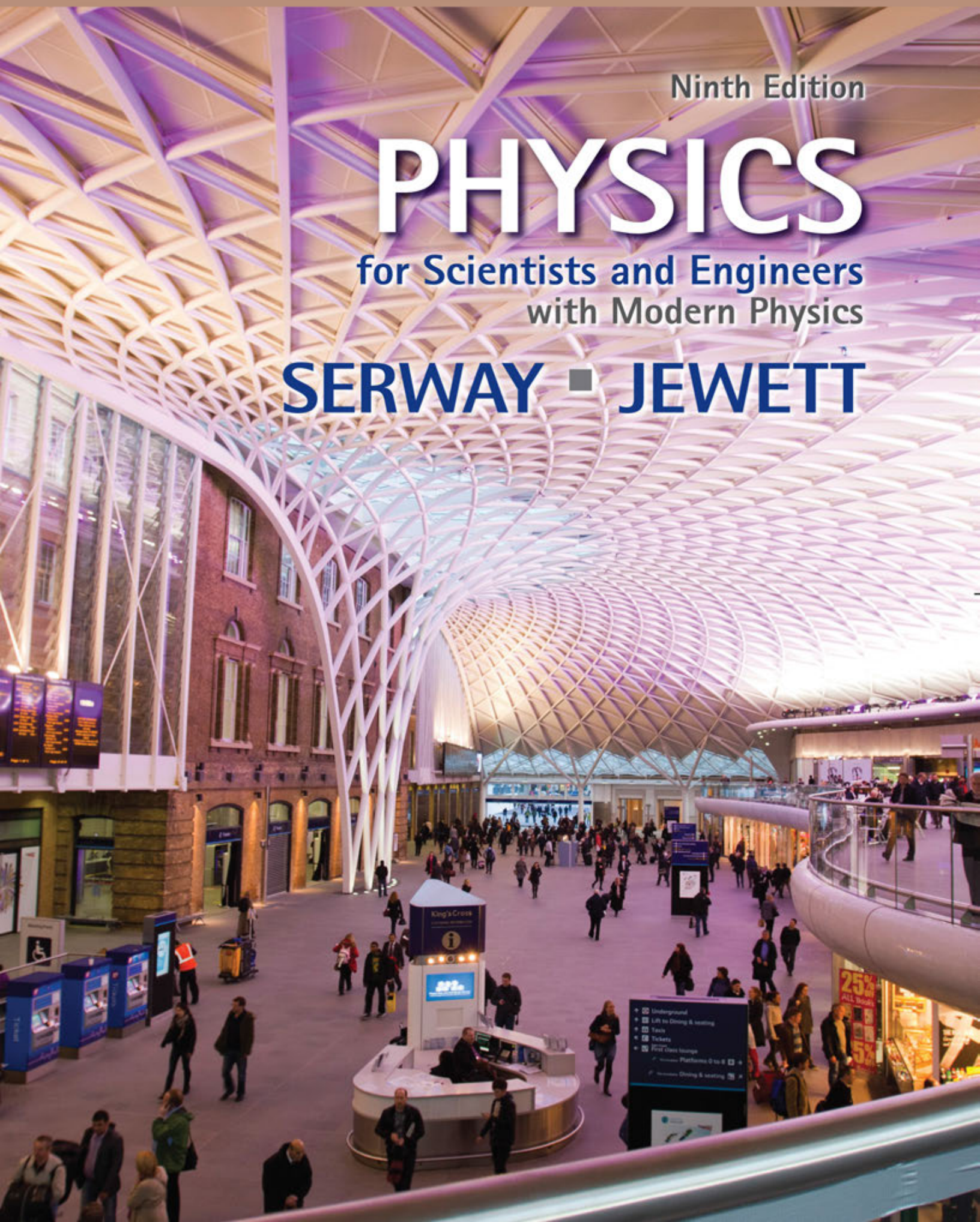


Ninth Edition

PHYSICS

for Scientists and Engineers
with Modern Physics

SERWAY ■ JEWETT



Pedagogical Color Chart

Mechanics and Thermodynamics

Displacement and position vectors



Displacement and position component vectors



Linear (\vec{v}) and angular ($\vec{\omega}$) velocity vectors



Velocity component vectors



Force vectors (\vec{F})



Force component vectors



Acceleration vectors (\vec{a})



Acceleration component vectors



Energy transfer arrows



Process arrow



Linear (\vec{p}) and angular (\vec{L}) momentum vectors



Linear and angular momentum component vectors



Torque vectors ($\vec{\tau}$)



Torque component vectors



Schematic linear or rotational motion directions



Dimensional rotational arrow



Enlargement arrow



Springs



Pulleys



Electricity and Magnetism

Electric fields



Electric field vectors



Electric field component vectors



Magnetic fields



Magnetic field vectors



Magnetic field component vectors



Positive charges



Negative charges



Resistors



Batteries and other DC power supplies



Switches



Capacitors



Inductors (coils)



Voltmeters



Ammeters



AC Sources



Lightbulbs



Ground symbol



Current



Light and Optics

Light ray



Focal light ray



Central light ray



Converging lens



Diverging lens



Mirror



Curved mirror



Objects



Images



Some Physical Constants

Quantity	Symbol	Value ^a
Atomic mass unit	u	$1.660\,538\,782\,(83) \times 10^{-27} \text{ kg}$ $931.494\,028\,(23) \text{ MeV}/c^2$
Avogadro's number	N_A	$6.022\,141\,79\,(30) \times 10^{23} \text{ particles/mol}$
Bohr magneton	$\mu_B = \frac{e\hbar}{2m_e}$	$9.274\,009\,15\,(23) \times 10^{-24} \text{ J/T}$
Bohr radius	$a_0 = \frac{\hbar^2}{m_e e^2 k_e}$	$5.291\,772\,085\,9\,(36) \times 10^{-11} \text{ m}$
Boltzmann's constant	$k_B = \frac{R}{N_A}$	$1.380\,650\,4\,(24) \times 10^{-23} \text{ J/K}$
Compton wavelength	$\lambda_C = \frac{h}{m_e c}$	$2.426\,310\,217\,5\,(33) \times 10^{-12} \text{ m}$
Coulomb constant	$k_e = \frac{1}{4\pi\epsilon_0}$	$8.987\,551\,788 \dots \times 10^9 \text{ N}\cdot\text{m}^2/\text{C}^2 \text{ (exact)}$
Deuteron mass	m_d	$3.343\,583\,20\,(17) \times 10^{-27} \text{ kg}$ $2.013\,553\,212\,724\,(78) \text{ u}$
Electron mass	m_e	$9.109\,382\,15\,(45) \times 10^{-31} \text{ kg}$ $5.485\,799\,094\,3\,(23) \times 10^{-4} \text{ u}$ $0.510\,998\,910\,(13) \text{ MeV}/c^2$
Electron volt	eV	$1.602\,176\,487\,(40) \times 10^{-19} \text{ J}$
Elementary charge	e	$1.602\,176\,487\,(40) \times 10^{-19} \text{ C}$
Gas constant	R	$8.314\,472\,(15) \text{ J/mol}\cdot\text{K}$
Gravitational constant	G	$6.674\,28\,(67) \times 10^{-11} \text{ N}\cdot\text{m}^2/\text{kg}^2$
Neutron mass	m_n	$1.674\,927\,211\,(84) \times 10^{-27} \text{ kg}$ $1.008\,664\,915\,97\,(43) \text{ u}$ $939.565\,346\,(23) \text{ MeV}/c^2$
Nuclear magneton	$\mu_n = \frac{e\hbar}{2m_p}$	$5.050\,783\,24\,(13) \times 10^{-27} \text{ J/T}$
Permeability of free space	μ_0	$4\pi \times 10^{-7} \text{ T}\cdot\text{m/A} \text{ (exact)}$
Permittivity of free space	$\epsilon_0 = \frac{1}{\mu_0 c^2}$	$8.854\,187\,817 \dots \times 10^{-12} \text{ C}^2/\text{N}\cdot\text{m}^2 \text{ (exact)}$
Planck's constant	h	$6.626\,068\,96\,(33) \times 10^{-34} \text{ J}\cdot\text{s}$
	$\hbar = \frac{h}{2\pi}$	$1.054\,571\,628\,(53) \times 10^{-34} \text{ J}\cdot\text{s}$
Proton mass	m_p	$1.672\,621\,637\,(83) \times 10^{-27} \text{ kg}$ $1.007\,276\,466\,77\,(10) \text{ u}$ $938.272\,013\,(23) \text{ MeV}/c^2$
Rydberg constant	R_H	$1.097\,373\,156\,852\,7\,(73) \times 10^7 \text{ m}^{-1}$
Speed of light in vacuum	c	$2.997\,924\,58 \times 10^8 \text{ m/s} \text{ (exact)}$

Note: These constants are the values recommended in 2006 by CODATA, based on a least-squares adjustment of data from different measurements. For a more complete list, see P. J. Mohr, B. N. Taylor, and D. B. Newell, "CODATA Recommended Values of the Fundamental Physical Constants: 2006." *Rev. Mod. Phys.* **80**:2, 633–730, 2008.

^aThe numbers in parentheses for the values represent the uncertainties of the last two digits.

Solar System Data

Body	Mass (kg)	Mean Radius (m)	Period (s)	Mean Distance from the Sun (m)
Mercury	3.30×10^{23}	2.44×10^6	7.60×10^6	5.79×10^{10}
Venus	4.87×10^{24}	6.05×10^6	1.94×10^7	1.08×10^{11}
Earth	5.97×10^{24}	6.37×10^6	3.156×10^7	1.496×10^{11}
Mars	6.42×10^{23}	3.39×10^6	5.94×10^7	2.28×10^{11}
Jupiter	1.90×10^{27}	6.99×10^7	3.74×10^8	7.78×10^{11}
Saturn	5.68×10^{26}	5.82×10^7	9.29×10^8	1.43×10^{12}
Uranus	8.68×10^{25}	2.54×10^7	2.65×10^9	2.87×10^{12}
Neptune	1.02×10^{26}	2.46×10^7	5.18×10^9	4.50×10^{12}
Pluto ^a	1.25×10^{22}	1.20×10^6	7.82×10^9	5.91×10^{12}
Moon	7.35×10^{22}	1.74×10^6	—	—
Sun	1.989×10^{30}	6.96×10^8	—	—

^aIn August 2006, the International Astronomical Union adopted a definition of a planet that separates Pluto from the other eight planets. Pluto is now defined as a “dwarf planet” (like the asteroid Ceres).

Physical Data Often Used

Average Earth–Moon distance	3.84×10^8 m
Average Earth–Sun distance	1.496×10^{11} m
Average radius of the Earth	6.37×10^6 m
Density of air (20°C and 1 atm)	1.20 kg/m ³
Density of air (0°C and 1 atm)	1.29 kg/m ³
Density of water (20°C and 1 atm)	1.00×10^3 kg/m ³
Free-fall acceleration	9.80 m/s ²
Mass of the Earth	5.97×10^{24} kg
Mass of the Moon	7.35×10^{22} kg
Mass of the Sun	1.99×10^{30} kg
Standard atmospheric pressure	1.013×10^5 Pa

Note: These values are the ones used in the text.

Some Prefixes for Powers of Ten

Power	Prefix	Abbreviation	Power	Prefix	Abbreviation
10^{-24}	yocto	y	10^1	deka	da
10^{-21}	zepto	z	10^2	hecto	h
10^{-18}	atto	a	10^3	kilo	k
10^{-15}	femto	f	10^6	mega	M
10^{-12}	pico	p	10^9	giga	G
10^{-9}	nano	n	10^{12}	tera	T
10^{-6}	micro	μ	10^{15}	peta	P
10^{-3}	milli	m	10^{18}	exa	E
10^{-2}	centi	c	10^{21}	zetta	Z
10^{-1}	deci	d	10^{24}	yotta	Y

Physics

for Scientists and Engineers
with Modern Physics

NINTH
EDITION

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University of California at Los Angeles

About the Cover

The cover shows a view inside the new railway departures concourse opened in March 2012 at the Kings Cross Station in London. The wall of the older structure (completed in 1852) is visible at the left. The sweeping shell-like roof is claimed by the architect to be the largest single-span station structure in Europe. Many principles of physics are required to design and construct such an open semicircular roof with a radius of 74 meters and containing over 2 000 triangular panels. Other principles of physics are necessary to develop the lighting design, optimize the acoustics, and integrate the new structure with existing infrastructure, historic buildings, and railway platforms.



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We dedicate this book to our wives,
Elizabeth and Lisa, and all our children and
grandchildren for their loving understanding
when we spent time on writing
instead of being with them.

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About the Authors



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John W. Jewett, Jr. earned his undergraduate degree in physics at Drexel University and his doctorate at Ohio State University, specializing in optical and magnetic properties of condensed matter. Dr. Jewett began his academic career at Richard Stockton College of New Jersey, where he taught from 1974 to 1984. He is currently Emeritus Professor of Physics at California State Polytechnic University, Pomona. Through his teaching career, Dr. Jewett has been active in promoting effective physics education. In addition to receiving four National Science Foundation grants in physics education, he helped found and direct the Southern California Area Modern Physics Institute (SCAMPI) and Science IMPACT (Institute for Modern Pedagogy and Creative Teaching). Dr. Jewett's honors include the Stockton Merit Award at Richard Stockton College in 1980, selection as Outstanding Professor at California State Polytechnic University for 1991–1992, and the Excellence in Undergraduate Physics Teaching Award from the American Association of Physics Teachers

(AAPT) in 1998. In 2010, he received an Alumni Lifetime Achievement Award from Drexel University in recognition of his contributions in physics education. He has given more than 100 presentations both domestically and abroad, including multiple presentations at national meetings of the AAPT. He has also published 25 research papers in condensed matter physics and physics education research. Dr. Jewett is the author of *The World of Physics: Mysteries, Magic, and Myth*, which provides many connections between physics and everyday experiences. In addition to his work as the coauthor for *Physics for Scientists and Engineers*, he is also the coauthor on *Principles of Physics*, Fifth Edition, as well as *Global Issues*, a four-volume set of instruction manuals in integrated science for high school. Dr. Jewett enjoys playing keyboard with his all-physicist band, traveling, underwater photography, learning foreign languages, and collecting antique quack medical devices that can be used as demonstration apparatus in physics lectures. Most importantly, he relishes spending time with his wife, Lisa, and their children and grandchildren.

Preface

In writing this Ninth Edition of *Physics for Scientists and Engineers*, we continue our ongoing efforts to improve the clarity of presentation and include new pedagogical features that help support the learning and teaching processes. Drawing on positive feedback from users of the Eighth Edition, data gathered from both professors and students who use Enhanced WebAssign, as well as reviewers' suggestions, we have refined the text to better meet the needs of students and teachers.

This textbook is intended for a course in introductory physics for students majoring in science or engineering. The entire contents of the book in its extended version could be covered in a three-semester course, but it is possible to use the material in shorter sequences with the omission of selected chapters and sections. The mathematical background of the student taking this course should ideally include one semester of calculus. If that is not possible, the student should be enrolled in a concurrent course in introductory calculus.

Content

The material in this book covers fundamental topics in classical physics and provides an introduction to modern physics. The book is divided into six parts. Part 1 (Chapters 1 to 14) deals with the fundamentals of Newtonian mechanics and the physics of fluids; Part 2 (Chapters 15 to 18) covers oscillations, mechanical waves, and sound; Part 3 (Chapters 19 to 22) addresses heat and thermodynamics; Part 4 (Chapters 23 to 34) treats electricity and magnetism; Part 5 (Chapters 35 to 38) covers light and optics; and Part 6 (Chapters 39 to 46) deals with relativity and modern physics.

Objectives

This introductory physics textbook has three main objectives: to provide the student with a clear and logical presentation of the basic concepts and principles of physics, to strengthen an understanding of the concepts and principles through a broad range of interesting real-world applications, and to develop strong problem-solving skills through an effectively organized approach. To meet these objectives, we emphasize well-organized physical arguments and a focused problem-solving strategy. At the same time, we attempt to motivate the student through practical examples that demonstrate the role of physics in other disciplines, including engineering, chemistry, and medicine.

Changes in the Ninth Edition

A large number of changes and improvements were made for the Ninth Edition of this text. Some of the new features are based on our experiences and on current trends in science education. Other changes were incorporated in response to comments and suggestions offered by users of the Eighth Edition and by reviewers of the manuscript. The features listed here represent the major changes in the Ninth Edition.

Enhanced Integration of the Analysis Model Approach to Problem Solving. Students are faced with hundreds of problems during their physics courses. A relatively small number of fundamental principles form the basis of these problems. When faced with a new problem, a physicist forms a *model* of the problem that can be solved in a simple way by identifying the fundamental principle that is applicable in the problem. For example, many problems involve conservation of energy, Newton's second law, or kinematic equations. Because the physicist has studied these principles and their applications extensively, he or she can apply this knowledge as a model for solving a new problem. Although it would be ideal for students to follow this same process, most students have difficulty becoming familiar with the entire palette of fundamental principles that are available. It is easier for students to identify a *situation* rather than a fundamental principle.

The *Analysis Model approach* we focus on in this revision lays out a standard set of situations that appear in most physics problems. These situations are based on an entity in one of four simplification models: particle, system, rigid object, and wave. Once the simplification model is identified, the student thinks about what the entity is doing or how it interacts with its environment. This leads the student to identify a particular Analysis Model for the problem. For example, if an object is falling, the object is recognized as a particle experiencing an acceleration due to gravity that is constant. The student has learned that the Analysis Model of a *particle under constant acceleration* describes this situation. Furthermore, this model has a small number of equations associated with it for use in starting problems, the kinematic equations presented in Chapter 2. Therefore, an understanding of the situation has led to an Analysis Model, which then identifies a very small number of equations to start the problem, rather than the myriad equations that students see in the text. In this way, the use of Analysis Models leads the student to identify the fundamental principle. As the student gains more experience, he or she will lean less on the Analysis Model approach and begin to identify fundamental principles directly.

To better integrate the Analysis Model approach for this edition, **Analysis Model descriptive boxes** have been added at the end of any section that introduces a new Analysis Model. This feature recaps the Analysis Model introduced in the section and provides examples of the types of problems that a student could solve using the Analysis Model. These boxes function as a “refresher” before students see the Analysis Models in use in the worked examples for a given section.

Worked examples in the text that utilize Analysis Models are now designated with an **AM** icon for ease of reference. The solutions of these examples integrate the Analysis Model approach to problem solving. The approach is further reinforced in the end-of-chapter summary under the heading *Analysis Models for Problem Solving*, and through the new **Analysis Model Tutorials** that are based on selected end-of-chapter problems and appear in Enhanced WebAssign.

Analysis Model Tutorials. John Jewett developed 165 tutorials (indicated in each chapter’s problem set with an **AMT** icon) that strengthen students’ problem-solving skills by guiding them through the steps in the problem-solving process. Important first steps include making predictions and focusing on physics concepts before solving the problem quantitatively. A critical component of these tutorials is the selection of an appropriate Analysis Model to describe what is going on in the problem. This step allows students to make the important link between the situation in the problem and the mathematical representation of the situation. Analysis Model tutorials include meaningful feedback at each step to help students practice the problem-solving process and improve their skills. In addition, the feedback addresses student misconceptions and helps them to catch algebraic and other mathematical errors. Solutions are carried out symbolically as long as possible, with numerical values substituted at the end. This feature helps students understand the effects of changing the values of each variable in the problem, avoids unnecessary repetitive substitution of the same numbers, and eliminates round-off errors. Feedback at the end of the tutorial encourages students to compare the final answer with their original predictions.

Annotated Instructor’s Edition. New for this edition, the Annotated Instructor’s Edition provides instructors with teaching tips and other notes on how to utilize the textbook in the classroom, via cyan annotations. Additionally, the full complement of icons describing the various types of problems will be included in the questions/problems sets (the Student Edition contains only those icons needed by students).

PreLecture Explorations. The Active Figure questions in WebAssign from the Eighth Edition have been completely revised. The simulations have been updated, with additional parameters to enhance investigation of a physical phenomenon. Students can make predictions, change the parameters, and then observe the results. Each new PreLecture Exploration comes with conceptual and analytical questions that guide students to a deeper understanding and help promote a robust physical intuition.

New Master Its Added in Enhanced WebAssign. Approximately 50 new Master Its in Enhanced WebAssign have been added for this edition to the end-of-chapter problem sets.



Chapter-by-Chapter Changes

The list below highlights some of the major changes for the Ninth Edition.

Chapter 1

- Two new Master Its were added to the end-of-chapter problems set.
- Three new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 2

- A new introduction to the concept of Analysis Models has been included in Section 2.3.
- Three Analysis Model descriptive boxes have been added, in Sections 2.3 and 2.6.
- Several textual sections have been revised to make more explicit references to analysis models.
- Three new Master Its were added to the end-of-chapter problems set.
- Five new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 3

- Three new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 4

- An Analysis Model descriptive box has been added, in Section 4.6.
- Several textual sections have been revised to make more explicit references to analysis models.
- Three new Master Its were added to the end-of-chapter problems set.
- Five new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 5

- Two Analysis Model descriptive boxes have been added, in Section 5.7.
- Several examples have been modified so that numerical values are put in only at the end of the solution.
- Several textual sections have been revised to make more explicit references to analysis models.
- Four new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 6

- An Analysis Model descriptive box has been added, in Section 6.1.
- Several examples have been modified so that numerical values are put in only at the end of the solution.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 7

- The notation for work done on a system externally and internally within a system has been clarified.
- The equations and discussions in several sections have been modified to more clearly show the comparisons of similar potential energy equations among different situations.

- One new Master It was added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 8

- Two Analysis Model descriptive boxes have been added, in Sections 8.1 and 8.2.
- The problem-solving strategy in Section 8.2 has been reworded to account for a more general application to both isolated and nonisolated systems.
- As a result of a suggestion from a PER team at University of Washington and Pennsylvania State University, Example 8.1 has been rewritten to demonstrate to students the effect of choosing different systems on the development of the solution.
- All examples in the chapter have been rewritten to begin with Equation 8.2 directly rather than beginning with the format $E_i = E_f$.
- Several examples have been modified so that numerical values are put in only at the end of the solution.
- The problem-solving strategy in Section 8.4 has been deleted and the text material revised to incorporate these ideas on handling energy changes when nonconservative forces act.
- Several textual sections have been revised to make more explicit references to analysis models.
- One new Master It was added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 9

- Two Analysis Model descriptive boxes have been added, in Section 9.3.
- Several examples have been modified so that numerical values are put in only at the end of the solution.
- Five new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 10

- The order of four sections (10.4–10.7) has been modified so as to introduce moment of inertia through torque (rather than energy) and to place the two sections on energy together. The sections have been revised accordingly to account for the revised development of concepts. This revision makes the order of approach similar to the order of approach students have already seen in translational motion.
- New introductory paragraphs have been added to several sections to show how the development of our analysis of rotational motion parallels that followed earlier for translational motion.
- Two Analysis Model descriptive boxes have been added, in Sections 10.2 and 10.5.
- Several textual sections have been revised to make more explicit references to analysis models.

- Two new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 11

- Two Analysis Model descriptive boxes have been added, in Sections 11.2 and 11.4.
- Angular momentum conservation equations have been revised so as to be presented as $\Delta L = (0 \text{ or } \tau dt)$ in order to be consistent with the approach in Chapter 8 for energy conservation and Chapter 9 for linear momentum conservation.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 12

- One Analysis Model descriptive box has been added, in Section 12.1.
- Several examples have been modified so that numerical values are put in only at the end of the solution.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 13

- Sections 13.3 and 13.4 have been interchanged to provide a better flow of concepts.
- A new analysis model has been introduced: *Particle in a Field (Gravitational)*. This model is introduced because it represents a physical situation that occurs often. In addition, the model is introduced to anticipate the importance of versions of this model later in electricity and magnetism, where it is even more critical. An Analysis Model descriptive box has been added in Section 13.3. In addition, a new summary flash card has been added at the end of the chapter, and textual material has been revised to make reference to the new model.
- The description of the historical goals of the Cavendish experiment in 1798 has been revised to be more consistent with Cavendish's original intent and the knowledge available at the time of the experiment.
- Newly discovered Kuiper belt objects have been added, in Section 13.4.
- Textual material has been modified to make a stronger tie-in to Analysis Models, especially in the energy sections 13.5 and 13.6.
- All conservation equations have been revised so as to be presented with the change in the system on the left and the transfer across the boundary of the system on the right, in order to be consistent with the approach in earlier chapters for energy conservation, linear momentum conservation, and angular momentum conservation.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 14

- Several textual sections have been revised to make more explicit references to Analysis Models.
- Several examples have been modified so that numerical values are put in only at the end of the solution.

- One new Master It was added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 15

- An Analysis Model descriptive box has been added, in Section 15.2.
- Several textual sections have been revised to make more explicit references to Analysis Models.
- Four new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 16

- A new Analysis Model descriptive box has been added, in Section 16.2.
- Section 16.3, on the derivation of the speed of a wave on a string, has been completely rewritten to improve the logical development.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 17

- One new Master It was added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 18

- Two Analysis Model descriptive boxes have been added, in Sections 18.1 and 18.3.
- Two new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 19

- Several examples have been modified so that numerical values are put in only at the end of the solution.
- One new Master It was added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 20

- Section 20.3 was revised to emphasize the focus on *systems*.
- Five new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 21

- A new introduction to Section 21.1 sets up the notion of *structural models* to be used in this chapter and future chapters for describing systems that are too large or too small to observe directly.
- Fifteen new equations have been numbered, and all equations in the chapter have been renumbered. This

new program of equation numbers allows easier and more efficient referencing to equations in the development of kinetic theory.

- The order of Sections 21.3 and 21.4 has been reversed to provide a more continuous discussion of specific heats of gases.
- One new Master It was added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 22

- In Section 22.4, the discussion of Carnot's theorem has been rewritten and expanded, with a new figure added that is connected to the proof of the theorem.
- The material in Sections 22.6, 22.7, and 22.8 has been completely reorganized, reordered, and rewritten. The notion of entropy as a measure of disorder has been removed in favor of more contemporary ideas from the physics education literature on entropy and its relationship to notions such as uncertainty, missing information, and energy spreading.
- Two new Pitfall Preventions have been added in Section 22.6 to help students with their understanding of entropy.
- There is a newly added argument for the equivalence of the entropy statement of the second law and the Clausius and Kelvin–Planck statements in Section 22.8.
- Two new summary flashcards have been added relating to the revised entropy discussion.
- Three new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 23

- A new analysis model has been introduced: *Particle in a Field (Electrical)*. This model follows on the introduction of the Particle in a Field (Gravitational) model introduced in Chapter 13. An Analysis Model descriptive box has been added, in Section 23.4. In addition, a new summary flash card has been added at the end of the chapter, and textual material has been revised to make reference to the new model.
- A new What If? has been added to Example 23.9 in order to make a connection to infinite planes of charge, to be further studied in later chapters.
- Several textual sections and worked examples have been revised to make more explicit references to analysis models.
- One new Master It was added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 24

- Section 24.1 has been significantly revised to clarify the geometry of area elements through which electric field lines pass to generate an electric flux.
- Two new figures have been added to Example 24.5 to further explore the electric fields due to single and paired infinite planes of charge.

- Two new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 25

- Sections 25.1 and 25.2 have been significantly revised to make connections to the new particle in a field analysis models introduced in Chapters 13 and 23.
- Example 25.4 has been moved so as to appear after the Problem-Solving Strategy in Section 25.5, allowing students to compare electric fields due to a small number of charges and a continuous charge distribution.
- Two new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 26

- The discussion of series and parallel capacitors in Section 26.3 has been revised for clarity.
- The discussion of potential energy associated with an electric dipole in an electric field in Section 26.6 has been revised for clarity.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 27

- The discussion of the Drude model for electrical conduction in Section 27.3 has been revised to follow the outline of structural models introduced in Chapter 21.
- Several textual sections have been revised to make more explicit references to analysis models.
- Five new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 28

- The discussion of series and parallel resistors in Section 28.2 has been revised for clarity.
- Time-varying charge, current, and voltage have been represented with lowercase letters for clarity in distinguishing them from constant values.
- Five new Master Its were added to the end-of-chapter problems set.
- Two new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 29

- A new analysis model has been introduced: *Particle in a Field (Magnetic)*. This model follows on the introduction of the Particle in a Field (Gravitational) model introduced in Chapter 13 and the Particle in a Field (Electrical) model in Chapter 23. An Analysis Model descriptive box has been added, in Section 29.1. In addition, a new summary flash card has been added at the end of the chapter, and textual material has been revised to make reference to the new model.

- One new Master It was added to the end-of-chapter problems set.
- Six new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 30

- Several textual sections have been revised to make more explicit references to analysis models.
- One new Master It was added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 31

- Several textual sections have been revised to make more explicit references to analysis models.
- One new Master It was added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 32

- Several textual sections have been revised to make more explicit references to analysis models.
- Time-varying charge, current, and voltage have been represented with lowercase letters for clarity in distinguishing them from constant values.
- Two new Master Its were added to the end-of-chapter problems set.
- Three new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 33

- Phasor colors have been revised in many figures to improve clarity of presentation.
- Three new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 34

- Several textual sections have been revised to make more explicit references to analysis models.
- The status of spacecraft related to solar sailing has been updated in Section 34.5.
- Six new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 35

- Two new Analysis Model descriptive boxes have been added, in Sections 35.4 and 35.5.
- Several textual sections and worked examples have been revised to make more explicit references to analysis models.
- Five new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 36

- The discussion of the Keck Telescope in Section 36.10 has been updated, and a new figure from the Keck has

been included, representing the first-ever direct optical image of a solar system beyond ours.

- Five new Master Its were added to the end-of-chapter problems set.
- Three new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 37

- An Analysis Model descriptive box has been added, in Section 37.2.
- The discussion of the Laser Interferometer Gravitational-Wave Observatory (LIGO) in Section 37.6 has been updated.
- Three new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 38

- Four new Master Its were added to the end-of-chapter problems set.
- Three new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 39

- Several textual sections have been revised to make more explicit references to analysis models.
- Sections 39.8 and 39.9 from the Eighth Edition have been combined into one section.
- Five new Master Its were added to the end-of-chapter problems set.
- Four new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 40

- The discussion of the Planck model for blackbody radiation in Section 40.1 has been revised to follow the outline of structural models introduced in Chapter 21.
- The discussion of the Einstein model for the photoelectric effect in Section 40.2 has been revised to follow the outline of structural models introduced in Chapter 21.
- Several textual sections have been revised to make more explicit references to analysis models.
- Two new Master Its were added to the end-of-chapter problems set.
- Two new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 41

- An Analysis Model descriptive box has been added, in Section 41.2.
- One new Analysis Model Tutorial was added for this chapter in Enhanced WebAssign.

Chapter 42

- The discussion of the Bohr model for the hydrogen atom in Section 42.3 has been revised to follow the outline of structural models introduced in Chapter 21.
- In Section 42.7, the tendency for atomic systems to drop to their lowest energy levels is related to the new discus-

sion of the second law of thermodynamics appearing in Chapter 22.

- The discussion of the applications of lasers in Section 42.10 has been updated to include laser diodes, carbon dioxide lasers, and excimer lasers.
- Several textual sections have been revised to make more explicit references to analysis models.
- Five new Master Its were added to the end-of-chapter problems set.
- Three new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 43

- A new discussion of the contribution of carbon dioxide molecules in the atmosphere to global warming has been added to Section 43.2. A new figure has been added, showing the increasing concentration of carbon dioxide in the past decades.
- A new discussion of graphene (Nobel Prize in Physics, 2010) and its properties has been added to Section 43.4.
- The discussion of worldwide photovoltaic power plants in Section 43.7 has been updated.
- The discussion of transistor density on microchips in Section 43.7 has been updated.
- Several textual sections and worked examples have been revised to make more explicit references to analysis models.
- One new Analysis Model Tutorial was added for this chapter in Enhanced WebAssign.

Chapter 44

- Data for the helium-4 atom were added to Table 44.1.
- Several textual sections have been revised to make more explicit references to analysis models.
- Three new Master Its were added to the end-of-chapter problems set.
- Two new Analysis Model Tutorials were added for this chapter in Enhanced WebAssign.

Chapter 45

- Discussion of the March 2011 nuclear disaster after the earthquake and tsunami in Japan was added to Section 45.3.
- The discussion of the International Thermonuclear Experimental Reactor (ITER) in Section 45.4 has been updated.
- The discussion of the National Ignition Facility (NIF) in Section 45.4 has been updated.
- The discussion of radiation dosage in Section 45.5 has been cast in terms of SI units grays and sieverts.
- Section 45.6 from the Eighth Edition has been deleted.
- Four new Master Its were added to the end-of-chapter problems set.
- One new Analysis Model Tutorial was added for this chapter in Enhanced WebAssign.

Chapter 46

- A discussion of the ALICE (A Large Ion Collider Experiment) project searching for a quark–gluon plasma at the Large Hadron Collider (LHC) has been added to Section 46.9.
- A discussion of the July 2012 announcement of the discovery of a Higgs-like particle from the ATLAS (A Toroidal LHC Apparatus) and CMS (Compact Muon Solenoid) projects at the Large Hadron Collider (LHC) has been added to Section 46.10.
- A discussion of closures of colliders due to the beginning of operations at the Large Hadron Collider (LHC) has been added to Section 46.10.
- A discussion of recent missions and the new Planck mission to study the cosmic background radiation has been added to Section 46.11.
- Several textual sections have been revised to make more explicit references to analysis models.
- One new Master It was added to the end-of-chapter problems set.
- One new Analysis Model Tutorial was added for this chapter in Enhanced WebAssign.

Text Features

Most instructors believe that the textbook selected for a course should be the student's primary guide for understanding and learning the subject matter. Furthermore, the textbook should be easily accessible and should be styled and written to facilitate instruction and learning. With these points in mind, we have included many pedagogical features, listed below, that are intended to enhance its usefulness to both students and instructors.

Problem Solving and Conceptual Understanding

General Problem-Solving Strategy. A general strategy outlined at the end of Chapter 2 (pages 45–47) provides students with a structured process for solving problems. In all remaining chapters, the strategy is employed explicitly in every example so that students learn how it is applied. Students are encouraged to follow this strategy when working end-of-chapter problems.

Worked Examples. All in-text worked examples are presented in a two-column format to better reinforce physical concepts. The left column shows textual information

that describes the steps for solving the problem. The right column shows the mathematical manipulations and results of taking these steps. This layout facilitates matching the concept with its mathematical execution and helps students organize their work. The examples closely follow the General Problem-Solving Strategy introduced in Chapter 2 to reinforce effective problem-solving habits. All worked examples in the text may be assigned for homework in Enhanced WebAssign. A sample of a worked example can be found on the next page.

Examples consist of two types. The first (and most common) example type presents a problem and numerical answer. The second type of example is conceptual in nature. To accommodate increased emphasis on understanding physical concepts, the many conceptual examples are labeled as such and are designed to help students focus on the physical situation in the problem. Worked examples in the text that utilize Analysis Models are now designated with an **AM** icon for ease of reference, and the solutions of these examples now more thoroughly integrate the Analysis Model approach to problem solving.

Based on reviewer feedback from the Eighth Edition, we have made careful revisions to the worked examples so that the solutions are presented symbolically as far as possible, with numerical values substituted at the end. This approach will help students think symbolically when they solve problems instead of unnecessarily inserting numbers into intermediate equations.

What If? Approximately one-third of the worked examples in the text contain a What If? feature. At the completion of the example solution, a What If? question offers a variation on the situation posed in the text of the example. This feature encourages students to think about the results of the example, and it also assists in conceptual understanding of the principles. What If? questions also prepare students to encounter novel problems that may be included on exams. Some of the end-of-chapter problems also include this feature.

Quick Quizzes. Students are provided an opportunity to test their understanding of the physical concepts presented through Quick Quizzes. The questions require students to make decisions on the basis of sound reasoning, and some of the questions have been written to help students overcome common misconceptions. Quick Quizzes have been cast in an objective format, including multiple-choice, true-false, and ranking. Answers to all Quick Quiz questions are found at the end of the text. Many instructors choose to use such questions in a “peer instruction” teaching style or with the use of personal response system “clickers,” but they can be used in standard quiz format as well. An example of a Quick Quiz follows below.

- Quick Quiz 7.5** A dart is inserted into a spring-loaded dart gun by pushing the spring in by a distance x . For the next loading, the spring is compressed a distance $2x$. How much faster does the second dart leave the gun compared with the first? (a) four times as fast (b) two times as fast (c) the same (d) half as fast (e) one-fourth as fast

Pitfall Prevention 16.2

Two Kinds of Speed/Velocity

Do not confuse v , the speed of the wave as it propagates along the string, with v_y , the transverse velocity of a point on the string. The speed v is constant for a uniform medium, whereas v_y varies sinusoidally.

Pitfall Preventions. More than two hundred Pitfall Preventions (such as the one to the left) are provided to help students avoid common mistakes and misunderstandings. These features, which are placed in the margins of the text, address both common student misconceptions and situations in which students often follow unproductive paths.

Summaries. Each chapter contains a summary that reviews the important concepts and equations discussed in that chapter. The summary is divided into three sections: Definitions, Concepts and Principles, and Analysis Models for Problem Solving. In each section, flash card-type boxes focus on each separate definition, concept, principle, or analysis model.

ENHANCED

WebAssign All worked examples are also available to be assigned as interactive examples in the Enhanced WebAssign homework management system.

Example 3.2 A Vacation Trip

A car travels 20.0 km due north and then 35.0 km in a direction 60.0° west of north as shown in Figure 3.11a. Find the magnitude and direction of the car's resultant displacement.

SOLUTION

Conceptualize The vectors and drawn in Figure 3.11a help us conceptualize the problem. The resultant vector has also been drawn. We expect its magnitude to be a few tens of kilometers. The angle that the resultant vector makes with the axis is expected to be less than 60° , the angle that vector makes with the axis.

Categorize We can categorize this example as a simple analysis problem in vector addition. The displacement is the resultant when the two individual displacements and are added. We can further categorize it as a problem about the analysis of triangles, so we appeal to our expertise in geometry and trigonometry.

Analyze In this example, we show two ways to analyze the problem of finding the resultant of two vectors. The first way is to solve the problem geometrically, using graph paper and a protractor to measure the magnitude of and its direction in Figure 3.11a. (In fact, even when you know you are going to be carrying out a calculation, you should sketch the vectors to check your results.) With an ordinary ruler and protractor, a large diagram typically gives answers to two-digit but not to three-digit precision. Try using these tools on in Figure 3.11a and compare to the trigonometric analysis below!

The second way to solve the problem is to analyze it using algebra and trigonometry. The magnitude of can be obtained from the law of cosines as applied to the triangle in Figure 3.11a (see Appendix B.4).

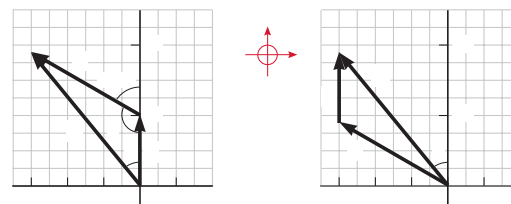


Figure 3.11 (Example 3.2) (a) Graphical method for finding the resultant displacement vector (b) Adding the vectors in reverse order gives the same result for

Use \cos from the law of cosines to find

Substitute numerical values, noting that $180^\circ - 60^\circ = 120^\circ$:

$$R = \sqrt{(20.0 \text{ km})^2 + (35.0 \text{ km})^2 - 2(20.0 \text{ km})(35.0 \text{ km}) \cos 120^\circ} = 48.2 \text{ km}$$

Use the law of sines (Appendix B.4) to find the direction measured from the northerly direction:

$$\frac{\sin \beta}{35.0 \text{ km}} = \frac{\sin 120^\circ}{48.2 \text{ km}} \quad \sin \beta = \frac{35.0 \text{ km}}{48.2 \text{ km}} \sin 120^\circ = 0.629$$

$$\beta = 38.9^\circ$$

The resultant displacement of the car is 48.2 km in a direction 38.9° west of north.

Finalize Does the angle that we calculated agree with an estimate made by looking at Figure 3.11a or with an actual angle measured from the diagram using the graphical method? Is it reasonable that the magnitude of is larger than that of both and ? Are the units of correct?

Although the head to tail method of adding vectors works well, it suffers from two disadvantages. First, some

people find using the laws of cosines and sines to be awkward. Second, a triangle only results if you are adding two vectors. If you are adding three or more vectors, the resulting geometric shape is usually not a triangle. In Section 3.4, we explore a new method of adding vectors that will address both of these disadvantages.

WHAT Suppose the trip were taken with the two vectors in reverse order: 35.0 km at 60.0° west of north first and then 20.0 km due north. How would the magnitude and the direction of the resultant vector change?

Answer They would not change. The commutative law for vector addition tells us that the order of vectors in an addition is irrelevant. Graphically, Figure 3.11b shows that the vectors added in the reverse order give us the same resultant vector.

What If? statements appear in about one-third of the worked examples and offer a variation on the situation posed in the text of the example. For instance, this feature might explore the effects of changing the conditions of the situation, determine what happens when a quantity is taken to a particular limiting value, or question whether additional information can be determined about the problem situation. This feature encourages students to think about the results of the example and assists in conceptual understanding of the principles.

Each solution has been written to closely follow the General Problem-Solving Strategy as outlined on pages 45–47 in Chapter 2, so as to reinforce good problem-solving habits.

Each step of the solution is detailed in a two-column format. The left column provides an explanation for each mathematical step in the right column, to better reinforce the physical concepts.

Questions and Problems Sets. For the Ninth Edition, the authors reviewed each question and problem and incorporated revisions designed to improve both readability and assignability. More than 10% of the problems are new to this edition.

Questions. The Questions section is divided into two sections: *Objective Questions* and *Conceptual Questions*. The instructor may select items to assign as homework or use in the classroom, possibly with “peer instruction” methods and possibly with personal response systems. More than 900 Objective and Conceptual Questions are included in this edition. Answers for selected questions are included in the *Student Solutions Manual/Study Guide*, and answers for all questions are found in the *Instructor’s Solutions Manual*.

Objective Questions are multiple-choice, true–false, ranking, or other multiple guess–type questions. Some require calculations designed to facilitate students’ familiarity with the equations, the variables used, the concepts the variables represent, and the relationships between the concepts. Others are more conceptual in nature and are designed to encourage conceptual thinking. Objective Questions are also written with the personal response system user in mind, and most of the questions could easily be used in these systems.

Conceptual Questions are more traditional short-answer and essay-type questions that require students to think conceptually about a physical situation.

Problems. An extensive set of problems is included at the end of each chapter; in all, this edition contains more than 3 700 problems. Answers for odd-numbered problems are provided at the end of the book. Full solutions for approximately 20% of the problems are included in the *Student Solutions Manual/Study Guide*, and solutions for all problems are found in the *Instructor’s Solutions Manual*.

The end-of-chapter problems are organized by the sections in each chapter (about two-thirds of the problems are keyed to specific sections of the chapter). Within each section, the problems now “platform” students to higher-order thinking by presenting all the straightforward problems in the section first, followed by the intermediate problems. (The problem numbers for straightforward problems are printed in **black**; intermediate-level problems are in **blue**.) The *Additional Problems* section contains problems that are not keyed to specific sections. At the end of each chapter is the *Challenge Problems* section, which gathers the most difficult problems for a given chapter in one place. (Challenge Problems have problem numbers marked in **red**.)

There are several kinds of problems featured in this text:

Quantitative/Conceptual problems (indicated in the Annotated Instructor’s Edition) contain parts that ask students to think both quantitatively and conceptually. An example of a Quantitative/Conceptual problem appears here:

The problem is identified in the Annotated Instructor’s Edition with a **blue** icon.

Parts (a)–(c) of the problem ask for quantitative calculations.

- 59.** A horizontal spring attached to a wall has a force constant of 850 N/m . A block of mass 1.00 kg is attached to the spring and rests on a frictionless, horizontal surface as in Figure P8.59. (a) The block is pulled to a position 6.00 cm from equilibrium and released. Find the elastic potential energy stored in the spring when the block is 6.00 cm from equilibrium and when the block passes through equilibrium. (b) Find the speed of the block as it passes through the equilibrium point. (c) What is the speed of the block when it is at a position $\frac{1}{2} 3.00 \text{ cm}$? (d) Why isn’t the answer to part (c) half the answer to part (b)?

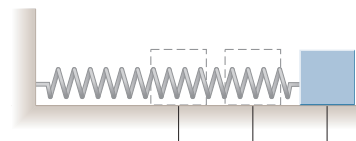



Figure P8.59

Part (d) asks a conceptual question about the situation.

Symbolic problems (indicated in the Annotated Instructor's Edition) ask students to solve a problem using only symbolic manipulation. Reviewers of the Eighth Edition (as well as the majority of respondents to a large survey) asked specifically for an increase in the number of symbolic problems found in the text because it better reflects the way instructors want their students to think when solving physics problems. An example of a Symbolic problem appears here:

The problem is identified in the Annotated Instructor's Edition with a  icon.

No numbers appear in the problem statement.

51. A truck is moving with constant acceleration up a hill that makes an angle with the horizontal as in Figure P6.51. A small sphere of mass is suspended from the ceiling of the truck by a light cord. If the pendulum makes a constant angle with the perpendicular to the ceiling, what is

51. $(\cos \tan \sin$

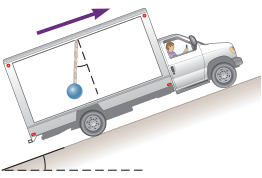



Figure P6.51

The figure shows only symbolic quantities.

The answer to the problem is purely symbolic.

Guided Problems help students break problems into steps. A physics problem typically asks for one physical quantity in a given context. Often, however, several concepts must be used and a number of calculations are required to obtain that final answer. Many students are not accustomed to this level of complexity and often don't know where to start. A Guided Problem breaks a standard problem into smaller steps, enabling students to grasp all the concepts and strategies required to arrive at a correct solution. Unlike standard physics problems, guidance is often built into the problem statement. Guided Problems are reminiscent of how a student might interact with a professor in an office visit. These problems (there is one in every chapter of the text) help train students to break down complex problems into a series of simpler problems, an essential problem-solving skill. An example of a Guided Problem appears here:

38. A uniform beam resting on two pivots has a length 6.00 m and mass 90.0 kg. The pivot under the left end exerts a normal force on the beam, and the second pivot located a distance 4.00 m from the left end exerts a normal force. A woman of mass 55.0 kg steps onto the left end of the beam and begins walking to the right as in Figure P12.38. The goal is to find the woman's position when the beam begins to tip. (a) What is the appropriate analysis model for the beam before it begins to tip? (b) Sketch a force diagram for the beam, labeling the gravitational and normal forces acting on the beam and placing the woman a distance to the right of the first pivot, which is the origin. (c) Where is the woman when the normal force is the greatest? (d) What is when the beam is about to tip? (e) Use Equation 12.1 to find the value of when the beam is about to tip. (f) Using the result of part (d) and Equation 12.2, with torques computed around the second pivot, find the woman's position when the beam is about to tip. (g) Check the answer to part (e) by computing torques around the first pivot point.

The problem is identified with a  icon.

The goal of the problem is identified.

Analysis begins by identifying the appropriate analysis model.

Students are provided with suggestions for steps to solve the problem.

The calculation associated with the goal is requested.

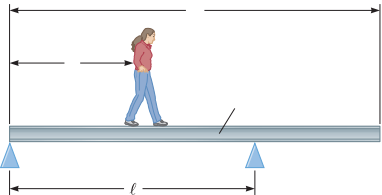


Figure P12.38

Impossibility problems. Physics education research has focused heavily on the problem-solving skills of students. Although most problems in this text are structured in the form of providing data and asking for a result of computation, two problems in each chapter, on average, are structured as impossibility problems. They begin with the phrase *Why is the following situation impossible?* That is followed by the description of a situation. The striking aspect of these problems is that no question is asked of the students, other than that in the initial italics. The student must determine what questions need to be asked and what calculations need to be performed. Based on the results of these calculations, the student must determine why the situation described is not possible. This determination may require information from personal experience, common sense, Internet or print research, measurement, mathematical skills, knowledge of human norms, or scientific thinking.

These problems can be assigned to build critical thinking skills in students. They are also fun, having the aspect of physics “mysteries” to be solved by students individually or in groups. An example of an impossibility problem appears here:


The initial phrase in italics signals an impossibility problem.

67. *Why is the following situation impossible?* Albert Pujols hits a home run so that the baseball just clears the top row of bleachers, 24.0 m high, located 130 m from home plate. The ball is hit at 41.7 m/s at an angle of 35.0° to the horizontal, and air resistance is negligible.

A situation is described.

No question is asked. The student must determine what needs to be calculated and why the situation is impossible.

Paired problems. These problems are otherwise identical, one asking for a numerical solution and one asking for a symbolic derivation. There are now three pairs of these problems in most chapters, indicated in the Annotated Instructor’s Edition by cyan shading in the end-of-chapter problems set.



Biomedical problems. These problems (indicated in the Annotated Instructor’s Edition with a  icon) highlight the relevance of physics principles to those students taking this course who are majoring in one of the life sciences.

Review problems. Many chapters include review problems requiring the student to combine concepts covered in the chapter with those discussed in previous chapters. These problems (marked **Review**) reflect the cohesive nature of the principles in the text and verify that physics is not a scattered set of ideas. When facing a real-world issue such as global warming or nuclear weapons, it may be necessary to call on ideas in physics from several parts of a textbook such as this one.

“Fermi problems.” One or more problems in most chapters ask the student to reason in order-of-magnitude terms.

Design problems. Several chapters contain problems that ask the student to determine design parameters for a practical device so that it can function as required.

Calculus-based problems. Every chapter contains at least one problem applying ideas and methods from differential calculus and one problem using integral calculus.

Integration with Enhanced WebAssign. The textbook's tight integration with Enhanced WebAssign content facilitates an online learning environment that helps students improve their problem-solving skills and gives them a variety of tools to meet their individual learning styles. Extensive user data gathered by WebAssign were used to ensure that the problems most often assigned were retained for this new edition. In each chapter's problems set, the top quartile of problems assigned in Enhanced WebAssign have cyan-shaded problem numbers in the Annotated Instructor's Edition for easy identification, allowing professors to quickly and easily find the most popular problems assigned in Enhanced WebAssign. New Analysis Model tutorials added for this edition have already been discussed (see page x). Master It tutorials help students solve problems by having them work through a stepped-out solution. Problems with Master It tutorials are indicated in each chapter's problem set with a  icon. In addition, Watch It solution videos are indicated in each chapter's problem set with a  icon and explain fundamental problem-solving strategies to help students step through the problem.

Artwork. Every piece of artwork in the Ninth Edition is in a modern style that helps express the physics principles at work in a clear and precise fashion. *Focus pointers* are included with many figures in the text; these either point out important aspects of a figure or guide students through a process illustrated by the artwork or photo. This format helps those students who are more visual learners. An example of a figure with a focus pointer appears below.

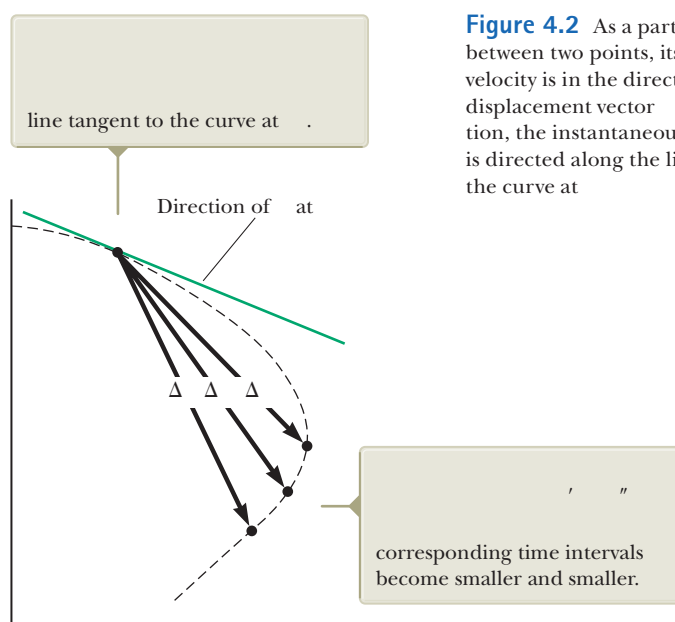


Figure 4.2 As a particle moves between two points, its average velocity is in the direction of the displacement vector . By definition, the instantaneous velocity at is directed along the line tangent to the curve at

Math Appendix. The math appendix (Appendix B), a valuable tool for students, shows the math tools in a physics context. This resource is ideal for students who need a quick review on topics such as algebra, trigonometry, and calculus.

Helpful Features

Style. To facilitate rapid comprehension, we have written the book in a clear, logical, and engaging style. We have chosen a writing style that is somewhat informal and relaxed so that students will find the text appealing and enjoyable to read. New terms are carefully defined, and we have avoided the use of jargon.

Important Definitions and Equations. Most important definitions are set in **bold-face** or are highlighted with a **background screen** for added emphasis and ease of review. Similarly, important equations are also highlighted with a background screen to facilitate location.

Marginal Notes. Comments and notes appearing in the margin with a ► icon can be used to locate important statements, equations, and concepts in the text.

Pedagogical Use of Color. Readers should consult the **pedagogical color chart** (inside the front cover) for a listing of the color-coded symbols used in the text diagrams. This system is followed consistently throughout the text.

Mathematical Level. We have introduced calculus gradually, keeping in mind that students often take introductory courses in calculus and physics concurrently. Most steps are shown when basic equations are developed, and reference is often made to mathematical appendices near the end of the textbook. Although vectors are discussed in detail in Chapter 3, vector products are introduced later in the text, where they are needed in physical applications. The dot product is introduced in Chapter 7, which addresses energy of a system; the cross product is introduced in Chapter 11, which deals with angular momentum.

Significant Figures. In both worked examples and end-of-chapter problems, significant figures have been handled with care. Most numerical examples are worked to either two or three significant figures, depending on the precision of the data provided. End-of-chapter problems regularly state data and answers to three-digit precision. When carrying out estimation calculations, we shall typically work with a single significant figure. (More discussion of significant figures can be found in Chapter 1, pages 11–13.)

Units. The international system of units (SI) is used throughout the text. The U.S. customary system of units is used only to a limited extent in the chapters on mechanics and thermodynamics.

Appendices and Endpapers. Several appendices are provided near the end of the textbook. Most of the appendix material represents a review of mathematical concepts and techniques used in the text, including scientific notation, algebra, geometry, trigonometry, differential calculus, and integral calculus. Reference to these appendices is made throughout the text. Most mathematical review sections in the appendices include worked examples and exercises with answers. In addition to the mathematical reviews, the appendices contain tables of physical data, conversion factors, and the SI units of physical quantities as well as a periodic table of the elements. Other useful information—fundamental constants and physical data, planetary data, a list of standard prefixes, mathematical symbols, the Greek alphabet, and standard abbreviations of units of measure—appears on the endpapers.



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All of the quantitative end-of-chapter problems

Selected problems enhanced with targeted feedback. An example of targeted feedback appears below:

Selected problems include feedback to address common mistakes that students make. This feedback was developed by professors with years of classroom experience.

A fish swimming in a horizontal plane has velocity $\vec{v}_i = (4\hat{i} + 1\hat{j})$ m/s at a point in the ocean where the position relative to a certain rock is $\vec{r}_i = (10\hat{i} - 4\hat{j})$ m. After the fish swims with constant acceleration for 20 s, its velocity is $\vec{v}_f = (20\hat{i} - 4\hat{j})$ m/s.

(a) What are the components of the acceleration?

$a_x = \boxed{3}$ m/s^2 ✗

You appear to have interchanged the position and velocity values.

$a_y = \boxed{05}$ m/s^2 ✗

Acceleration is determined from the change in velocity in this time interval.

(b) What is the direction of the acceleration with respect to unit vector \hat{i} ?

-368.5 $^\circ$ ✗ (counterclockwise from the $+\hat{x}$ -axis is positive)

You appear to have correctly calculated the angle using your incorrect values from part (a).

(c) If the fish maintains constant acceleration, where is it at $t = 20$ s?

$x = \boxed{}$ m ✗

$y = \boxed{}$ m ✗

In what direction is it moving?

$\boxed{}$ $^\circ$ ✗ (counterclockwise from the $+\hat{x}$ -axis is positive)

Need Help? [Read It](#) [Watch It](#) [Master It](#) [Chat About It](#)

Master It tutorials (indicated in the text by a M icon), to help students work through the problem one step at a time. An example of a Master It tutorial appears on page xxiv:

Master It

A fish swimming in a horizontal plane has velocity $\vec{v}_i = (3.00 \hat{i} + 1.00 \hat{j})$ m/s at a point in the ocean where the position relative to a certain rock is $\vec{r}_i = (6.00 \hat{i} - 3.7 \hat{j})$ m. After the fish swims with constant acceleration for 12.0 s, its velocity is $\vec{v} = (22.0 \hat{i} - 15 \hat{j})$ m/s.

(a) What are the components of the acceleration?
 (b) What is the direction of the acceleration with respect to unit vector \hat{i} ?
 (c) If the fish maintains constant acceleration, where is it at $t = 21.0$ s?

Part 1 of 7 - Conceptualize

The fish is speeding up and changing direction. We choose to write separate equations about the x and y components of its motion.

Part 2 of 7 - Categorize

Model the fish as a particle under constant acceleration. We use our old standard equations for constant-acceleration straight line motion, with x and y subscripts to make them apply to parts of the whole motion.

Part 3 of 7 - Analyze (a)

At $t = 0$, the initial velocity $\vec{v} = (3.00 \hat{i} + 1.00 \hat{j})$ m/s and the initial position vector $\vec{r}_i = (6.00 \hat{i} - 3.7 \hat{j})$ m


At the first 'final' point we consider, 12.0 s later, $\vec{v} = (22.0 \hat{i} - 15 \hat{j})$ m/s

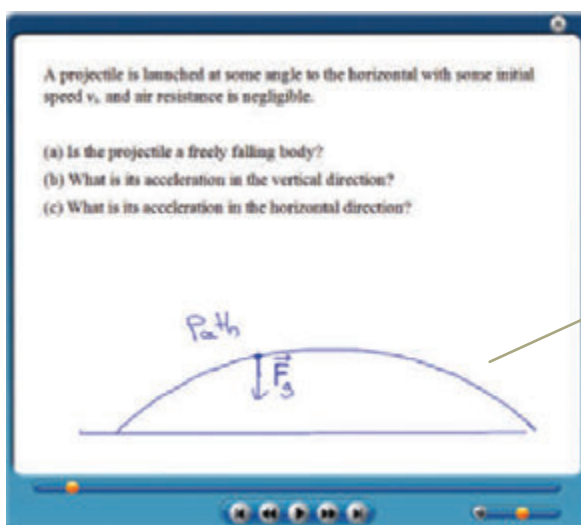
$a_x = \frac{\Delta v_x}{\Delta t} = \frac{22.0 \text{ m/s} - 3}{12.0 \text{ s}} = 1.1 \text{ m/s}^2$

$a_y = \frac{\Delta v_y}{\Delta t} = \frac{-15 \text{ m/s} - 1.00 \text{ s}}{12.0 \text{ s}} = -1.4 \text{ m/s}^2$

Master It tutorials help students organize what they need to solve a problem with *Conceptualize* and *Categorize* sections before they work through each step.

Master It tutorials help students work through each step of the problem.

Watch It solution videos (indicated in the text by a  icon) that explain fundamental problem-solving strategies, to help students step through the problem. In addition, instructors can choose to include video hints of problem-solving strategies. A screen shot from a Watch It solution video appears below:



Watch It solution videos help students visualize the steps needed to solve a problem.

Concept Checks

PhET simulations

Most worked examples, enhanced with hints and feedback, to help strengthen students' problem-solving skills

Every Quick Quiz, giving your students ample opportunity to test their conceptual understanding

PreLecture Explorations. The Active Figure questions in WebAssign have been completely revised. The simulations have been updated, with additional parameters to enhance investigation of a physical phenomenon. Students can make predictions, change the parameters, and then observe the results. Each new PreLecture Exploration comes with conceptual and analytical questions, which guide students to a deeper understanding and help promote a robust physical intuition.

Analysis Model tutorials. John Jewett developed 165 tutorials (indicated in each chapter's problem set with an  icon) that strengthen students' problem-solving skills by guiding them through the steps in the problem-solving process.

Important first steps include making predictions and focusing strategy on physics concepts before starting to solve the problem quantitatively. A critical component of these tutorials is the selection of an appropriate Analysis Model to describe what is going on in the problem. This step allows students to make the important link between the situation in the problem and the mathematical representation of the situation. Analysis Model tutorials include meaningful feedback at each step to help students practice the problem-solving process and improve their skills. In addition, the feedback addresses student misconceptions and helps them to catch algebraic and other mathematical errors. Solutions are carried out symbolically as long as possible, with numerical values substituted at the end. This feature helps students to understand the effects of changing the values of each variable in the problem, avoids unnecessary repetitive substitution of the same numbers, and eliminates round-off errors. Feedback at the end of the tutorial encourages students to think about how the final answer compares to their original predictions.

- **Personalized Study Plan.** The Personal Study Plan in Enhanced WebAssign provides chapter and section assessments that show students what material they know and what areas require more work. For items that they answer incorrectly, students can click on links to related study resources such as videos, tutorials, or reading materials. Color-coded progress indicators let them see how well they are doing on different topics. You decide what chapters and sections to include—and whether to include the plan as part of the final grade or as a study guide with no scoring involved.
- **The Cengage YouBook.** WebAssign has a customizable and interactive eBook, the **Cengage YouBook**, that lets you tailor the textbook to fit your course and connect with your students. You can remove and rearrange chapters in the table of contents and tailor assigned readings that match your syllabus exactly. Powerful editing tools let you change as much as you'd like—or leave it just like it is. You can highlight key passages or add sticky notes to pages to comment on a concept in the reading, and then share any of these individual notes and highlights with your students, or keep them personal. You can also edit narrative content in the textbook by adding a text box or striking out text. With a handy link tool, you can drop in an icon at any point in the eBook that lets you link to your own lecture notes, audio summaries, video lectures, or other files on a personal Web site or anywhere on the Web. A simple YouTube widget lets you easily find and embed videos from YouTube directly into eBook pages. The Cengage YouBook helps students go beyond just reading the textbook. Students can also highlight the text, add their own notes, and bookmark the text. Animations play right on the page at the point of learning so that they're not speed bumps to reading but true enhancements. Please visit www.webassign.net/brookscole to view an interactive demonstration of Enhanced WebAssign.
- Offered exclusively in WebAssign, **Quick Prep** for physics is algebra and trigonometry math remediation within the context of physics applications and principles. Quick Prep helps students succeed by using narratives illustrated throughout with video examples. The Master It tutorial problems allow students to assess and retune their understanding of the material. The Practice Problems that go along with each tutorial allow both the student and the instructor to test the student's understanding of the material.

Quick Prep includes the following features:

- 67 interactive tutorials
- 67 additional practice problems
- A thorough overview of each topic, including video examples
- Can be taken before the semester begins or during the first few weeks of the course
- Can also be assigned alongside each chapter for “just in time” remediation

Topics include units, scientific notation, and significant figures; the motion of objects along a line; functions; approximation and graphing; probability and error; vectors, displacement, and velocity; spheres; force and vector projections.



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Lecture Presentation Resources

PowerLecture with ExamView® and JoinIn for *Physics for Scientists and Engineers*, Ninth Edition. Bringing physics principles and concepts to life in your lectures has never been easier! The full-featured, two-volume **PowerLecture** Instructor’s Resource DVD-ROM (Volume 1: Chapters 1–22; Volume 2: Chapters 23–46) provides everything you need for *Physics for Scientists and Engineers*, Ninth Edition. Key content includes the *Instructor’s Solutions Manual*, art and images from the text, pre-made chapter-specific PowerPoint lectures, ExamView test generator software with pre-loaded test questions, JoinIn response-system “clickers,” Active Figures animations, and a physics movie library.



JoinIn. *Assessing to Learn in the Classroom* questions developed at the University of Massachusetts Amherst. This collection of 250 advanced conceptual questions has been tested in the classroom for more than ten years and takes peer learning to a new level. JoinIn helps you turn your lectures into an interactive learning environment that promotes conceptual understanding. Available exclusively for higher education from our partnership with Turning Technologies, JoinIn™ is the easiest way to turn your lecture hall into a personal, fully interactive experience for your students!

Assessment and Course Preparation Resources

A number of resources listed below will assist with your assessment and preparation processes.

Instructor’s Solutions Manual by Vahé Peroomian (University of California at Los Angeles). Thoroughly revised for this edition, the *Instructor’s Solutions Manual* contains complete worked solutions to all end-of-chapter problems in the textbook as well as answers to the even-numbered problems and all the questions. The solutions to problems new to the Ninth Edition are marked for easy identification. Volume 1 contains Chapters 1 through 22; Volume 2 contains Chapters 23 through 46. Electronic files of the *Instructor’s Solutions Manual* are available on the PowerLecture™ DVD-ROM.

Test Bank by Ed Oberhofer (University of North Carolina at Charlotte and Lake Sumter Community College). The test bank is available on the two-volume PowerLecture™ DVD-ROM via the ExamView® test software. This two-volume test bank contains approximately 2 000 multiple-choice questions. Instructors may print and duplicate pages for distribution to students. Volume 1 contains Chapters 1 through 22, and Volume 2 contains Chapters 23 through 46. WebCT and Blackboard versions of the test bank are available on the instructor's companion site at **www.CengageBrain.com**.

Instructor's Companion Web Site. Consult the instructor's site by pointing your browser to **www.CengageBrain.com** for a problem correlation guide, PowerPoint lectures, and JoinIn audience response content. Instructors adopting the Ninth Edition of *Physics for Scientists and Engineers* may download these materials after securing the appropriate password from their local sales representative.

Supporting Materials for the Instructor

Supporting instructor materials are available to qualified adopters. Please consult your local Cengage Learning, Brooks/Cole representative for details. Visit **www.CengageBrain.com** to

- request a desk copy
- locate your local representative
- download electronic files of select support materials

Student Resources

Visit the *Physics for Scientists and Engineers* Web site at **www.cengagebrain.com/shop/ISBN/9781133954156** to see samples of select student supplements. Go to **CengageBrain.com** to purchase and access this product at Cengage Learning's preferred online store.



Student Solutions Manual/Study Guide by John R. Gordon, Vahé Perroomian, Raymond A. Serway, and John W. Jewett, Jr. This two-volume manual features detailed solutions to 20% of the end-of-chapter problems from the text. The manual also features a list of important equations, concepts, and notes from key sections of the text in addition to answers to selected end-of-chapter questions. Volume 1 contains Chapters 1 through 22; and Volume 2 contains Chapters 23 through 46.

Physics Laboratory Manual, Third Edition by David Loyd (Angelo State University) supplements the learning of basic physical principles while introducing laboratory procedures and equipment. Each chapter includes a prelaboratory assignment, objectives, an equipment list, the theory behind the experiment, experimental procedures, graphing exercises, and questions. A laboratory report form is included with each experiment so that the student can record data, calculations, and experimental results. Students are encouraged to apply statistical analysis to their data. A complete *Instructor's Manual* is also available to facilitate use of this lab manual.

Physics Laboratory Experiments, Seventh Edition by Jerry D. Wilson (Lander College) and Cecilia A. Hernández (American River College). This market-leading manual for the first-year physics laboratory course offers a wide range of class-tested experiments designed specifically for use in small to midsize lab programs. A series of integrated experiments emphasizes the use of computerized instrumentation and includes a set of "computer-assisted experiments" to allow students and instructors to gain experience with modern equipment. This option also enables instructors to determine the appropriate balance between traditional and computer-based experiments for their courses. By analyzing data through two different methods, students gain a greater understanding of the concepts behind the experiments. The Seventh Edition is updated with the latest information and techniques involving state-of-the-art equipment and a new Guided Learning feature addresses

the growing interest in guided-inquiry pedagogy. Fourteen additional experiments are also available through custom printing.

Teaching Options

The topics in this textbook are presented in the following sequence: classical mechanics, oscillations and mechanical waves, and heat and thermodynamics, followed by electricity and magnetism, electromagnetic waves, optics, relativity, and modern physics. This presentation represents a traditional sequence, with the subject of mechanical waves being presented before electricity and magnetism. Some instructors may prefer to discuss both mechanical and electromagnetic waves together after completing electricity and magnetism. In this case, Chapters 16 through 18 could be covered along with Chapter 34. The chapter on relativity is placed near the end of the text because this topic often is treated as an introduction to the era of “modern physics.” If time permits, instructors may choose to cover Chapter 39 after completing Chapter 13 as a conclusion to the material on Newtonian mechanics. For those instructors teaching a two-semester sequence, some sections and chapters could be deleted without any loss of continuity. The following sections can be considered optional for this purpose:

- | | |
|--|--|
| 2.8 Kinematic Equations Derived from Calculus | 31.6 Eddy Currents |
| 4.6 Relative Velocity and Relative Acceleration | 33.9 Rectifiers and Filters |
| 6.3 Motion in Accelerated Frames | 34.6 Production of Electromagnetic Waves by an Antenna |
| 6.4 Motion in the Presence of Resistive Forces | 36.5 Lens Aberrations |
| 7.9 Energy Diagrams and Equilibrium of a System | 36.6 The Camera |
| 9.9 Rocket Propulsion | 36.7 The Eye |
| 11.5 The Motion of Gyroscopes and Tops | 36.8 The Simple Magnifier |
| 14.7 Other Applications of Fluid Dynamics | 36.9 The Compound Microscope |
| 15.6 Damped Oscillations | 36.10 The Telescope |
| 15.7 Forced Oscillations | 38.5 Diffraction of X-Rays by Crystals |
| 18.6 Standing Waves in Rods and Membranes | 39.9 The General Theory of Relativity |
| 18.8 Nonsinusoidal Wave Patterns | 41.6 Applications of Tunneling |
| 25.7 The Millikan Oil-Drop Experiment | 42.9 Spontaneous and Stimulated Transitions |
| 25.8 Applications of Electrostatics | 42.10 Lasers |
| 26.7 An Atomic Description of Dielectrics | 43.7 Semiconductor Devices |
| 27.5 Superconductors | 43.8 Superconductivity |
| 28.5 Household Wiring and Electrical Safety | 44.8 Nuclear Magnetic Resonance and Magnetic Resonance Imaging |
| 29.3 Applications Involving Charged Particles Moving in a Magnetic Field | 45.5 Radiation Damage |
| 29.6 The Hall Effect | 45.6 Uses of Radiation |
| 30.6 Magnetism in Matter | |

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Raymond A. Serway
St. Petersburg, Florida

John W. Jewett, Jr.
Anaheim, California

To the Student

It is appropriate to offer some words of advice that should be of benefit to you, the student. Before doing so, we assume you have read the Preface, which describes the various features of the text and support materials that will help you through the course.

How to Study

Instructors are often asked, “How should I study physics and prepare for examinations?” There is no simple answer to this question, but we can offer some suggestions based on our own experiences in learning and teaching over the years.

First and foremost, maintain a positive attitude toward the subject matter, keeping in mind that physics is the most fundamental of all natural sciences. Other science courses that follow will use the same physical principles, so it is important that you understand and are able to apply the various concepts and theories discussed in the text.

Concepts and Principles

It is essential that you understand the basic concepts and principles before attempting to solve assigned problems. You can best accomplish this goal by carefully reading the textbook before you attend your lecture on the covered material. When reading the text, you should jot down those points that are not clear to you. Also be sure to make a diligent attempt at answering the questions in the **Quick Quizzes** as you come to them in your reading. We have worked hard to prepare questions that help you judge for yourself how well you understand the material. Study the **What If?** features that appear in many of the worked examples carefully. They will help you extend your understanding beyond the simple act of arriving at a numerical result. The Pitfall Preventions will also help guide you away from common misunderstandings about physics. During class, take careful notes and ask questions about those ideas that are unclear to you. Keep in mind that few people are able to absorb the full meaning of scientific material after only one reading; several readings of the text and your notes may be necessary. Your lectures and laboratory work supplement the textbook and should clarify some of the more difficult material. You should minimize your memorization of material. Successful memorization of passages from the text, equations, and derivations does not necessarily indicate that you understand the material. Your understanding of the material will be enhanced through a combination of efficient study habits, discussions with other students and with instructors, and your ability to solve the problems presented in the textbook. Ask questions whenever you believe that clarification of a concept is necessary.

Study Schedule

It is important that you set up a regular study schedule, preferably a daily one. Make sure that you read the syllabus for the course and adhere to the schedule set by your instructor. The lectures will make much more sense if you read the corresponding text material *before* attending them. As a general rule, you should devote about two hours of study time for each hour you are in class. If you are having trouble with the

course, seek the advice of the instructor or other students who have taken the course. You may find it necessary to seek further instruction from experienced students. Very often, instructors offer review sessions in addition to regular class periods. Avoid the practice of delaying study until a day or two before an exam. More often than not, this approach has disastrous results. Rather than undertake an all-night study session before a test, briefly review the basic concepts and equations, and then get a good night's rest. If you believe that you need additional help in understanding the concepts, in preparing for exams, or in problem solving, we suggest that you acquire a copy of the *Student Solutions Manual/Study Guide* that accompanies this textbook.

Visit the *Physics for Scientists and Engineers* Web site at www.cengagebrain.com/shop/ISBN/9781133954156 to see samples of select student supplements. You can purchase any Cengage Learning product at your local college store or at our preferred online store **CengageBrain.com**.

Use the Features

You should make full use of the various features of the text discussed in the Preface. For example, marginal notes are useful for locating and describing important equations and concepts, and **boldface** indicates important definitions. Many useful tables are contained in the appendices, but most are incorporated in the text where they are most often referenced. Appendix B is a convenient review of mathematical tools used in the text.

Answers to Quick Quizzes and odd-numbered problems are given at the end of the textbook, and solutions to selected end-of-chapter questions and problems are provided in the *Student Solutions Manual/Study Guide*. The table of contents provides an overview of the entire text, and the index enables you to locate specific material quickly. Footnotes are sometimes used to supplement the text or to cite other references on the subject discussed.

After reading a chapter, you should be able to define any new quantities introduced in that chapter and discuss the principles and assumptions that were used to arrive at certain key relations. The chapter summaries and the review sections of the *Student Solutions Manual/Study Guide* should help you in this regard. In some cases, you may find it necessary to refer to the textbook's index to locate certain topics. You should be able to associate with each physical quantity the correct symbol used to represent that quantity and the unit in which the quantity is specified. Furthermore, you should be able to express each important equation in concise and accurate prose.

Problem Solving

R. P. Feynman, Nobel laureate in physics, once said, "You do not know anything until you have practiced." In keeping with this statement, we strongly advise you to develop the skills necessary to solve a wide range of problems. Your ability to solve problems will be one of the main tests of your knowledge of physics; therefore, you should try to solve as many problems as possible. It is essential that you understand basic concepts and principles before attempting to solve problems. It is good practice to try to find alternate solutions to the same problem. For example, you can solve problems in mechanics using Newton's laws, but very often an alternative method that draws on energy considerations is more direct. You should not deceive yourself into thinking that you understand a problem merely because you have seen it solved in class. You must be able to solve the problem and similar problems on your own.

The approach to solving problems should be carefully planned. A systematic plan is especially important when a problem involves several concepts. First, read the problem several times until you are confident you understand what is being asked. Look for any key words that will help you interpret the problem and perhaps allow you to make certain assumptions. Your ability to interpret a question properly is

an integral part of problem solving. Second, you should acquire the habit of writing down the information given in a problem and those quantities that need to be found; for example, you might construct a table listing both the quantities given and the quantities to be found. This procedure is sometimes used in the worked examples of the textbook. Finally, after you have decided on the method you believe is appropriate for a given problem, proceed with your solution. The General Problem-Solving Strategy will guide you through complex problems. If you follow the steps of this procedure (*Conceptualize, Categorize, Analyze, Finalize*), you will find it easier to come up with a solution and gain more from your efforts. This strategy, located at the end of Chapter 2 (pages 45–47), is used in all worked examples in the remaining chapters so that you can learn how to apply it. Specific problem-solving strategies for certain types of situations are included in the text and appear with a special heading. These specific strategies follow the outline of the General Problem-Solving Strategy.

Often, students fail to recognize the limitations of certain equations or physical laws in a particular situation. It is very important that you understand and remember the assumptions that underlie a particular theory or formalism. For example, certain equations in kinematics apply only to a particle moving with constant acceleration. These equations are not valid for describing motion whose acceleration is not constant, such as the motion of an object connected to a spring or the motion of an object through a fluid. Study the Analysis Models for Problem Solving in the chapter summaries carefully so that you know how each model can be applied to a specific situation. The analysis models provide you with a logical structure for solving problems and help you develop your thinking skills to become more like those of a physicist. Use the analysis model approach to save you hours of looking for the correct equation and to make you a faster and more efficient problem solver.

Experiments

Physics is a science based on experimental observations. Therefore, we recommend that you try to supplement the text by performing various types of “hands-on” experiments either at home or in the laboratory. These experiments can be used to test ideas and models discussed in class or in the textbook. For example, the common Slinky toy is excellent for studying traveling waves, a ball swinging on the end of a long string can be used to investigate pendulum motion, various masses attached to the end of a vertical spring or rubber band can be used to determine its elastic nature, an old pair of polarized sunglasses and some discarded lenses and a magnifying glass are the components of various experiments in optics, and an approximate measure of the free-fall acceleration can be determined simply by measuring with a stopwatch the time interval required for a ball to drop from a known height. The list of such experiments is endless. When physical models are not available, be imaginative and try to develop models of your own.

New Media

If available, we strongly encourage you to use the **Enhanced WebAssign** product that is available with this textbook. It is far easier to understand physics if you see it in action, and the materials available in Enhanced WebAssign will enable you to become a part of that action.

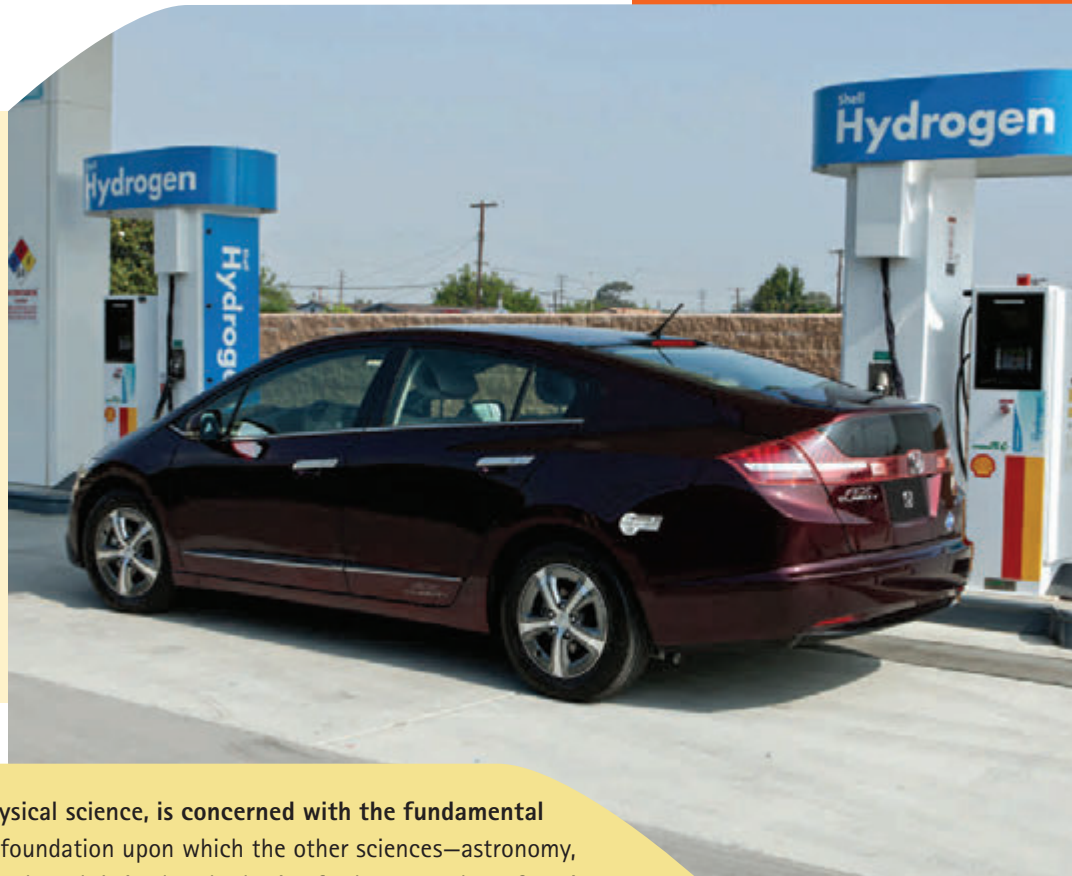
It is our sincere hope that you will find physics an exciting and enjoyable experience and that you will benefit from this experience, regardless of your chosen profession. Welcome to the exciting world of physics!

The scientist does not study nature because it is useful; he studies it because he delights in it, and he delights in it because it is beautiful. If nature were not beautiful, it would not be worth knowing, and if nature were not worth knowing, life would not be worth living.

—Henri Poincaré

The Honda FCX Clarity, a fuel-cell-powered automobile available to the public, albeit in limited quantities. A fuel cell converts hydrogen fuel into electricity to drive the motor attached to the wheels of the car. Automobiles, whether powered by fuel cells, gasoline engines, or batteries, use many of the concepts and principles of mechanics that we will study in this first part of the book. Quantities that we can use to describe the operation of vehicles include position, velocity, acceleration, force, energy, and momentum.

(PRNewsFoto/American Honda)



Physics, the most fundamental physical science, is concerned with the fundamental principles of the Universe. It is the foundation upon which the other sciences—astronomy, biology, chemistry, and geology—are based. It is also the basis of a large number of engineering applications. The beauty of physics lies in the simplicity of its fundamental principles and in the manner in which just a small number of concepts and models can alter and expand our view of the world around us.

The study of physics can be divided into six main areas:

1. *classical mechanics*, concerning the motion of objects that are large relative to atoms and move at speeds much slower than the speed of light
2. *relativity*, a theory describing objects moving at any speed, even speeds approaching the speed of light
3. *thermodynamics*, dealing with heat, work, temperature, and the statistical behavior of systems with large numbers of particles
4. *electromagnetism*, concerning electricity, magnetism, and electromagnetic fields
5. *optics*, the study of the behavior of light and its interaction with materials
6. *quantum mechanics*, a collection of theories connecting the behavior of matter at the submicroscopic level to macroscopic observations

The disciplines of mechanics and electromagnetism are basic to all other branches of classical physics (developed before 1900) and modern physics (c. 1900–present). The first part of this textbook deals with classical mechanics, sometimes referred to as *Newtonian mechanics* or simply *mechanics*. Many principles and models used to understand mechanical systems retain their importance in the theories of other areas of physics and can later be used to describe many natural phenomena. Therefore, classical mechanics is of vital importance to students from all disciplines. ■

Physics and Measurement

- 1.1 Standards of Length, Mass, and Time
- 1.2 Matter and Model Building
- 1.3 Dimensional Analysis
- 1.4 Conversion of Units
- 1.5 Estimates and Order-of-Magnitude Calculations
- 1.6 Significant Figures



Stonehenge, in southern England, was built thousands of years ago. Various theories have been proposed about its function, including a burial ground, a healing site, and a place for ancestor worship. One of the more intriguing theories suggests that Stonehenge was an observatory, allowing measurements of some of the quantities discussed in this chapter, such as position of objects in space and time intervals between repeating celestial events. (Stephen Inglis/Shutterstock.com)

ENHANCED

WebAssign Interactive content from this and other chapters may be assigned online in Enhanced WebAssign.

Like all other sciences, physics is based on experimental observations and quantitative measurements. The main objectives of physics are to identify a limited number of fundamental laws that govern natural phenomena and use them to develop theories that can predict the results of future experiments. The fundamental laws used in developing theories are expressed in the language of mathematics, the tool that provides a bridge between theory and experiment.

When there is a discrepancy between the prediction of a theory and experimental results, new or modified theories must be formulated to remove the discrepancy. Many times a theory is satisfactory only under limited conditions; a more general theory might be satisfactory without such limitations. For example, the laws of motion discovered by Isaac Newton (1642–1727) accurately describe the motion of objects moving at normal speeds but do not apply to objects moving at speeds comparable to the speed of light. In contrast, the special theory of relativity developed later by Albert Einstein (1879–1955) gives the same results as Newton's laws at low speeds but also correctly describes the motion of objects at speeds approaching the speed of light. Hence, Einstein's special theory of relativity is a more general theory of motion than that formed from Newton's laws.

Classical physics includes the principles of classical mechanics, thermodynamics, optics, and electromagnetism developed before 1900. Important contributions to classical physics

were provided by Newton, who was also one of the originators of calculus as a mathematical tool. Major developments in mechanics continued in the 18th century, but the fields of thermodynamics and electromagnetism were not developed until the latter part of the 19th century, principally because before that time the apparatus for controlled experiments in these disciplines was either too crude or unavailable.

A major revolution in physics, usually referred to as *modern physics*, began near the end of the 19th century. Modern physics developed mainly because many physical phenomena could not be explained by classical physics. The two most important developments in this modern era were the theories of relativity and quantum mechanics. Einstein's special theory of relativity not only correctly describes the motion of objects moving at speeds comparable to the speed of light; it also completely modifies the traditional concepts of space, time, and energy. The theory also shows that the speed of light is the upper limit of the speed of an object and that mass and energy are related. Quantum mechanics was formulated by a number of distinguished scientists to provide descriptions of physical phenomena at the atomic level. Many practical devices have been developed using the principles of quantum mechanics.

Scientists continually work at improving our understanding of fundamental laws. Numerous technological advances in recent times are the result of the efforts of many scientists, engineers, and technicians, such as unmanned planetary explorations, a variety of developments and potential applications in nanotechnology, microcircuitry and high-speed computers, sophisticated imaging techniques used in scientific research and medicine, and several remarkable results in genetic engineering. The effects of such developments and discoveries on our society have indeed been great, and it is very likely that future discoveries and developments will be exciting, challenging, and of great benefit to humanity.

1.1 Standards of Length, Mass, and Time

To describe natural phenomena, we must make measurements of various aspects of nature. Each measurement is associated with a physical quantity, such as the length of an object. The laws of physics are expressed as mathematical relationships among physical quantities that we will introduce and discuss throughout the book. In mechanics, the three fundamental quantities are length, mass, and time. All other quantities in mechanics can be expressed in terms of these three.

If we are to report the results of a measurement to someone who wishes to reproduce this measurement, a *standard* must be defined. It would be meaningless if a visitor from another planet were to talk to us about a length of 8 “glitches” if we do not know the meaning of the unit glitch. On the other hand, if someone familiar with our system of measurement reports that a wall is 2 meters high and our unit of length is defined to be 1 meter, we know that the height of the wall is twice our basic length unit. Whatever is chosen as a standard must be readily accessible and must possess some property that can be measured reliably. Measurement standards used by different people in different places—throughout the Universe—must yield the same result. In addition, standards used for measurements must not change with time.

In 1960, an international committee established a set of standards for the fundamental quantities of science. It is called the **SI** (Système International), and its fundamental units of length, mass, and time are the *meter*, *kilogram*, and *second*, respectively. Other standards for SI fundamental units established by the committee are those for temperature (the *kelvin*), electric current (the *ampere*), luminous intensity (the *candela*), and the amount of substance (the *mole*).

Length

We can identify **length** as the distance between two points in space. In 1120, the king of England decreed that the standard of length in his country would be named the *yard* and would be precisely equal to the distance from the tip of his nose to the end of his outstretched arm. Similarly, the original standard for the foot adopted by the French was the length of the royal foot of King Louis XIV. Neither of these standards is constant in time; when a new king took the throne, length measurements changed! The French standard prevailed until 1799, when the legal standard of length in France became the **meter** (m), defined as one ten-millionth of the distance from the equator to the North Pole along one particular longitudinal line that passes through Paris. Notice that this value is an Earth-based standard that does not satisfy the requirement that it can be used throughout the Universe.

As recently as 1960, the length of the meter was defined as the distance between two lines on a specific platinum–iridium bar stored under controlled conditions in France. Current requirements of science and technology, however, necessitate more accuracy than that with which the separation between the lines on the bar can be determined. In the 1960s and 1970s, the meter was defined as 1 650 763.73 wavelengths¹ of orange-red light emitted from a krypton-86 lamp. In October 1983, however, the meter was redefined as **the distance traveled by light in vacuum during a time of 1/299 792 458 second**. In effect, this latest definition establishes that the speed of light in vacuum is precisely 299 792 458 meters per second. This definition of the meter is valid throughout the Universe based on our assumption that light is the same everywhere.

Table 1.1 lists approximate values of some measured lengths. You should study this table as well as the next two tables and begin to generate an intuition for what is meant by, for example, a length of 20 centimeters, a mass of 100 kilograms, or a time interval of 3.2×10^7 seconds.

Mass

The SI fundamental unit of **mass**, the **kilogram** (kg), is defined as **the mass of a specific platinum–iridium alloy cylinder kept at the International Bureau of Weights and Measures at Sèvres, France**. This mass standard was established in 1887 and

Pitfall Prevention 1.1

Reasonable Values Generating intuition about typical values of quantities when solving problems is important because you must think about your end result and determine if it seems reasonable. For example, if you are calculating the mass of a housefly and arrive at a value of 100 kg, this answer is *unreasonable* and there is an error somewhere.

Table 1.1 Approximate Values of Some Measured Lengths

	Length (m)
Distance from the Earth to the most remote known quasar	1.4×10^{26}
Distance from the Earth to the most remote normal galaxies	9×10^{25}
Distance from the Earth to the nearest large galaxy (Andromeda)	2×10^{22}
Distance from the Sun to the nearest star (Proxima Centauri)	4×10^{16}
One light-year	9.46×10^{15}
Mean orbit radius of the Earth about the Sun	1.50×10^{11}
Mean distance from the Earth to the Moon	3.84×10^8
Distance from the equator to the North Pole	1.00×10^7
Mean radius of the Earth	6.37×10^6
Typical altitude (above the surface) of a satellite orbiting the Earth	2×10^5
Length of a football field	9.1×10^1
Length of a housefly	5×10^{-3}
Size of smallest dust particles	$\sim 10^{-4}$
Size of cells of most living organisms	$\sim 10^{-5}$
Diameter of a hydrogen atom	$\sim 10^{-10}$
Diameter of an atomic nucleus	$\sim 10^{-14}$
Diameter of a proton	$\sim 10^{-15}$

¹We will use the standard international notation for numbers with more than three digits, in which groups of three digits are separated by spaces rather than commas. Therefore, 10 000 is the same as the common American notation of 10,000. Similarly, $\pi = 3.14159265$ is written as 3.141 592 65.

Table 1.2

Approximate Masses of Various Objects

	Mass (kg)
Observable Universe	$\sim 10^{52}$
Milky Way galaxy	$\sim 10^{42}$
Sun	1.99×10^{30}
Earth	5.98×10^{24}
Moon	7.36×10^{22}
Shark	$\sim 10^3$
Human	$\sim 10^2$
Frog	$\sim 10^{-1}$
Mosquito	$\sim 10^{-5}$
Bacterium	$\sim 1 \times 10^{-15}$
Hydrogen atom	1.67×10^{-27}
Electron	9.11×10^{-31}

Table 1.3

Approximate Values of Some Time Intervals

	Time Interval (s)
Age of the Universe	4×10^{17}
Age of the Earth	1.3×10^{17}
Average age of a college student	6.3×10^8
One year	3.2×10^7
One day	8.6×10^4
One class period	3.0×10^3
Time interval between normal heartbeats	8×10^{-1}
Period of audible sound waves	$\sim 10^{-3}$
Period of typical radio waves	$\sim 10^{-6}$
Period of vibration of an atom in a solid	$\sim 10^{-13}$
Period of visible light waves	$\sim 10^{-15}$
Duration of a nuclear collision	$\sim 10^{-22}$
Time interval for light to cross a proton	$\sim 10^{-24}$

has not been changed since that time because platinum–iridium is an unusually stable alloy. A duplicate of the Sèvres cylinder is kept at the National Institute of Standards and Technology (NIST) in Gaithersburg, Maryland (Fig. 1.1a). Table 1.2 lists approximate values of the masses of various objects.

Time

Before 1967, the standard of **time** was defined in terms of the *mean solar day*. (A solar day is the time interval between successive appearances of the Sun at the highest point it reaches in the sky each day.) The fundamental unit of a **second** (s) was defined as $(\frac{1}{60})(\frac{1}{60})(\frac{1}{24})$ of a mean solar day. This definition is based on the rotation of one planet, the Earth. Therefore, this motion does not provide a time standard that is universal.

In 1967, the second was redefined to take advantage of the high precision attainable in a device known as an *atomic clock* (Fig. 1.1b), which measures vibrations of cesium atoms. One second is now defined as **9 192 631 770 times the period of vibration of radiation from the cesium-133 atom**.² Approximate values of time intervals are presented in Table 1.3.

In addition to SI, another system of units, the *U.S. customary system*, is still used in the United States despite acceptance of SI by the rest of the world. In this system, the units of length, mass, and time are the foot (ft), slug, and second, respectively. In this book, we shall use SI units because they are almost universally accepted in science and industry. We shall make some limited use of U.S. customary units in the study of classical mechanics.

In addition to the fundamental SI units of meter, kilogram, and second, we can also use other units, such as millimeters and nanoseconds, where the prefixes *milli-* and *nano-* denote multipliers of the basic units based on various powers of ten. Prefixes for the various powers of ten and their abbreviations are listed in Table 1.4 (page 6). For example, 10^{-3} m is equivalent to 1 millimeter (mm), and 10^3 m corresponds to 1 kilometer (km). Likewise, 1 kilogram (kg) is 10^3 grams (g), and 1 mega volt (MV) is 10^6 volts (V).

The variables length, time, and mass are examples of *fundamental quantities*. Most other variables are *derived quantities*, those that can be expressed as a mathematical combination of fundamental quantities. Common examples are *area* (a product of two lengths) and *speed* (a ratio of a length to a time interval).

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a



b

Figure 1.1 (a) The National Standard Kilogram No. 20, an accurate copy of the International Standard Kilogram kept at Sèvres, France, is housed under a double bell jar in a vault at the National Institute of Standards and Technology. (b) A cesium fountain atomic clock. The clock will neither gain nor lose a second in 20 million years.

²Period is defined as the time interval needed for one complete vibration.

Table 1.4 Prefixes for Powers of Ten

Power	Prefix	Abbreviation	Power	Prefix	Abbreviation
10^{-24}	yocto	y	10^3	kilo	k
10^{-21}	zepto	z	10^6	mega	M
10^{-18}	atto	a	10^9	giga	G
10^{-15}	femto	f	10^{12}	tera	T
10^{-12}	pico	p	10^{15}	peta	P
10^{-9}	nano	n	10^{18}	exa	E
10^{-6}	micro	μ	10^{21}	zetta	Z
10^{-3}	milli	m	10^{24}	yotta	Y
10^{-2}	centi	c			
10^{-1}	deci	d			

A table of the letters in the Greek alphabet is provided on the back endpaper of this book.

Another example of a derived quantity is **density**. The density ρ (Greek letter rho) of any substance is defined as its *mass per unit volume*:

$$\rho \equiv \frac{m}{V} \quad (1.1)$$

In terms of fundamental quantities, density is a ratio of a mass to a product of three lengths. Aluminum, for example, has a density of $2.70 \times 10^3 \text{ kg/m}^3$, and iron has a density of $7.86 \times 10^3 \text{ kg/m}^3$. An extreme difference in density can be imagined by thinking about holding a 10-centimeter (cm) cube of Styrofoam in one hand and a 10-cm cube of lead in the other. See Table 14.1 in Chapter 14 for densities of several materials.

Quick Quiz 1.1 In a machine shop, two cams are produced, one of aluminum and one of iron. Both cams have the same mass. Which cam is larger? (a) The aluminum cam is larger. (b) The iron cam is larger. (c) Both cams have the same size.

1.2 Matter and Model Building

If physicists cannot interact with some phenomenon directly, they often imagine a **model** for a physical system that is related to the phenomenon. For example, we cannot interact directly with atoms because they are too small. Therefore, we build a mental model of an atom based on a system of a nucleus and one or more electrons outside the nucleus. Once we have identified the physical components of the model, we make predictions about its behavior based on the interactions among the components of the system or the interaction between the system and the environment outside the system.

As an example, consider the behavior of *matter*. A sample of solid gold is shown at the top of Figure 1.2. Is this sample nothing but wall-to-wall gold, with no empty space? If the sample is cut in half, the two pieces still retain their chemical identity as solid gold. What if the pieces are cut again and again, indefinitely? Will the smaller and smaller pieces always be gold? Such questions can be traced to early Greek philosophers. Two of them—Leucippus and his student Democritus—could not accept the idea that such cuttings could go on forever. They developed a model for matter by speculating that the process ultimately must end when it produces a particle that can no longer be cut. In Greek, *atomos* means “not sliceable.” From this Greek term comes our English word *atom*.

The Greek model of the structure of matter was that all ordinary matter consists of atoms, as suggested in the middle of Figure 1.2. Beyond that, no additional structure was specified in the model; atoms acted as small particles that interacted with one another, but internal structure of the atom was not a part of the model.

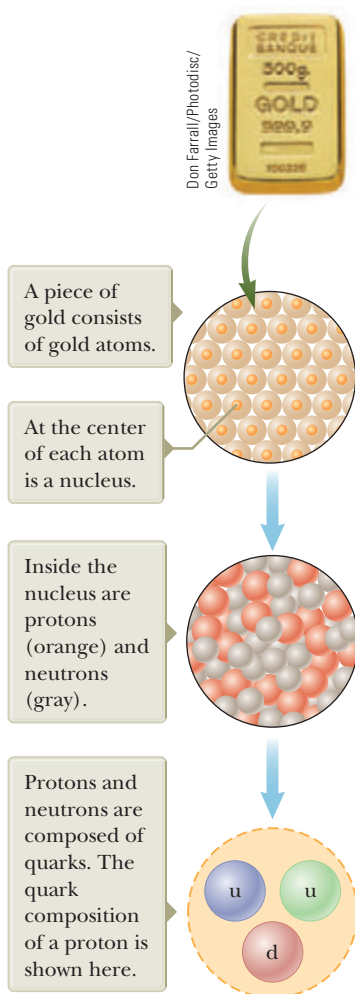


Figure 1.2 Levels of organization in matter.

In 1897, J. J. Thomson identified the electron as a charged particle and as a constituent of the atom. This led to the first atomic model that contained internal structure. We shall discuss this model in Chapter 42.

Following the discovery of the nucleus in 1911, an atomic model was developed in which each atom is made up of electrons surrounding a central nucleus. A nucleus of gold is shown in Figure 1.2. This model leads, however, to a new question: Does the nucleus have structure? That is, is the nucleus a single particle or a collection of particles? By the early 1930s, a model evolved that described two basic entities in the nucleus: protons and neutrons. The proton carries a positive electric charge, and a specific chemical element is identified by the number of protons in its nucleus. This number is called the **atomic number** of the element. For instance, the nucleus of a hydrogen atom contains one proton (so the atomic number of hydrogen is 1), the nucleus of a helium atom contains two protons (atomic number 2), and the nucleus of a uranium atom contains 92 protons (atomic number 92). In addition to atomic number, a second number—**mass number**, defined as the number of protons plus neutrons in a nucleus—characterizes atoms. The atomic number of a specific element never varies (i.e., the number of protons does not vary), but the mass number can vary (i.e., the number of neutrons varies).

Is that, however, where the process of breaking down stops? Protons, neutrons, and a host of other exotic particles are now known to be composed of six different varieties of particles called **quarks**, which have been given the names of *up*, *down*, *strange*, *charmed*, *bottom*, and *top*. The up, charmed, and top quarks have electric charges of $+\frac{2}{3}$ that of the proton, whereas the down, strange, and bottom quarks have charges of $-\frac{1}{3}$ that of the proton. The proton consists of two up quarks and one down quark as shown at the bottom of Figure 1.2 and labeled u and d. This structure predicts the correct charge for the proton. Likewise, the neutron consists of two down quarks and one up quark, giving a net charge of zero.

You should develop a process of building models as you study physics. In this study, you will be challenged with many mathematical problems to solve. One of the most important problem-solving techniques is to build a model for the problem: identify a system of physical components for the problem and make predictions of the behavior of the system based on the interactions among its components or the interaction between the system and its surrounding environment.

1.3 Dimensional Analysis

In physics, the word *dimension* denotes the physical nature of a quantity. The distance between two points, for example, can be measured in feet, meters, or furlongs, which are all different ways of expressing the dimension of length.

The symbols we use in this book to specify the dimensions of length, mass, and time are L, M, and T, respectively.³ We shall often use brackets [] to denote the dimensions of a physical quantity. For example, the symbol we use for speed in this book is v , and in our notation, the dimensions of speed are written $[v] = L/T$. As another example, the dimensions of area A are $[A] = L^2$. The dimensions and units of area, volume, speed, and acceleration are listed in Table 1.5. The dimensions of other quantities, such as force and energy, will be described as they are introduced in the text.

Table 1.5 Dimensions and Units of Four Derived Quantities

Quantity	Area (A)	Volume (V)	Speed (v)	Acceleration (a)
Dimensions	L^2	L^3	L/T	L/T^2
SI units	m^2	m^3	m/s	m/s^2
U.S. customary units	ft^2	ft^3	ft/s	ft/s^2

³The *dimensions* of a quantity will be symbolized by a capitalized, nonitalic letter such as L or T. The *algebraic symbol* for the quantity itself will be an italicized letter such as L for the length of an object or t for time.

In many situations, you may have to check a specific equation to see if it matches your expectations. A useful procedure for doing that, called **dimensional analysis**, can be used because dimensions can be treated as algebraic quantities. For example, quantities can be added or subtracted only if they have the same dimensions. Furthermore, the terms on both sides of an equation must have the same dimensions. By following these simple rules, you can use dimensional analysis to determine whether an expression has the correct form. Any relationship can be correct only if the dimensions on both sides of the equation are the same.

To illustrate this procedure, suppose you are interested in an equation for the position x of a car at a time t if the car starts from rest at $x = 0$ and moves with constant acceleration a . The correct expression for this situation is $x = \frac{1}{2}at^2$ as we show in Chapter 2. The quantity x on the left side has the dimension of length. For the equation to be dimensionally correct, the quantity on the right side must also have the dimension of length. We can perform a dimensional check by substituting the dimensions for acceleration, L/T^2 (Table 1.5), and time, T , into the equation. That is, the dimensional form of the equation $x = \frac{1}{2}at^2$ is

$$L = \frac{L}{T^2} \cdot T^2 = L$$

The dimensions of time cancel as shown, leaving the dimension of length on the right-hand side to match that on the left.

A more general procedure using dimensional analysis is to set up an expression of the form

$$x \propto a^n t^m$$

where n and m are exponents that must be determined and the symbol \propto indicates a proportionality. This relationship is correct only if the dimensions of both sides are the same. Because the dimension of the left side is length, the dimension of the right side must also be length. That is,

$$[a^n t^m] = L = L^1 T^0$$

Because the dimensions of acceleration are L/T^2 and the dimension of time is T , we have

$$(L/T^2)^n T^m = L^1 T^0 \rightarrow (L^n T^{m-2n}) = L^1 T^0$$

The exponents of L and T must be the same on both sides of the equation. From the exponents of L , we see immediately that $n = 1$. From the exponents of T , we see that $m - 2n = 0$, which, once we substitute for n , gives us $m = 2$. Returning to our original expression $x \propto a^n t^m$, we conclude that $x \propto at^2$.

Quick Quiz 1.2 True or False: Dimensional analysis can give you the numerical value of constants of proportionality that may appear in an algebraic expression.

Pitfall Prevention 1.2

Symbols for Quantities Some quantities have a small number of symbols that represent them. For example, the symbol for time is almost always t . Other quantities might have various symbols depending on the usage. Length may be described with symbols such as x , y , and z (for position); r (for radius); a , b , and c (for the legs of a right triangle); ℓ (for the length of an object); d (for a distance); h (for a height); and so forth.

Example 1.1 Analysis of an Equation

Show that the expression $v = at$, where v represents speed, a acceleration, and t an instant of time, is dimensionally correct.

SOLUTION

Identify the dimensions of v from Table 1.5:

$$[v] = \frac{L}{T}$$

► 1.1 continued

Identify the dimensions of a from Table 1.5 and multiply by the dimensions of t :

$$[at] = \frac{\text{L}}{\text{T}^2} \mathcal{T} = \frac{\text{L}}{\text{T}}$$

Therefore, $v = at$ is dimensionally correct because we have the same dimensions on both sides. (If the expression were given as $v = at^2$, it would be dimensionally *incorrect*. Try it and see!)

Example 1.2 Analysis of a Power Law

Suppose we are told that the acceleration a of a particle moving with uniform speed v in a circle of radius r is proportional to some power of r , say r^n , and some power of v , say v^m . Determine the values of n and m and write the simplest form of an equation for the acceleration.

SOLUTION

Write an expression for a with a dimensionless constant of proportionality k :

$$a = kr^n v^m$$

Substitute the dimensions of a , r , and v :

$$\frac{\text{L}}{\text{T}^2} = \text{L}^n \left(\frac{\text{L}}{\text{T}} \right)^m = \frac{\text{L}^{n+m}}{\text{T}^m}$$

Equate the exponents of L and T so that the dimensional equation is balanced:

$$n + m = 1 \text{ and } m = 2$$

Solve the two equations for n :

$$n = -1$$

Write the acceleration expression:

$$a = kr^{-1} v^2 = k \frac{v^2}{r}$$

In Section 4.4 on uniform circular motion, we show that $k = 1$ if a consistent set of units is used. The constant k would not equal 1 if, for example, v were in km/h and you wanted a in m/s².

1.4 Conversion of Units

Sometimes it is necessary to convert units from one measurement system to another or convert within a system (for example, from kilometers to meters). Conversion factors between SI and U.S. customary units of length are as follows:

$$\begin{array}{ll} 1 \text{ mile} = 1\,609 \text{ m} = 1.609 \text{ km} & 1 \text{ ft} = 0.3048 \text{ m} = 30.48 \text{ cm} \\ 1 \text{ m} = 39.37 \text{ in.} = 3.281 \text{ ft} & 1 \text{ in.} = 0.0254 \text{ m} = 2.54 \text{ cm (exactly)} \end{array}$$

A more complete list of conversion factors can be found in Appendix A.

Like dimensions, units can be treated as algebraic quantities that can cancel each other. For example, suppose we wish to convert 15.0 in. to centimeters. Because 1 in. is defined as exactly 2.54 cm, we find that

$$15.0 \text{ in.} = (15.0 \text{ in.}) \left(\frac{2.54 \text{ cm}}{1 \text{ in.}} \right) = 38.1 \text{ cm}$$

where the ratio in parentheses is equal to 1. We express 1 as 2.54 cm/1 in. (rather than 1 in./2.54 cm) so that the unit “inch” in the denominator cancels with the unit in the original quantity. The remaining unit is the centimeter, our desired result.

Pitfall Prevention 1.3

Always Include Units When performing calculations with numerical values, include the units for every quantity and carry the units through the entire calculation. Avoid the temptation to drop the units early and then attach the expected units once you have an answer. By including the units in every step, you can detect errors if the units for the answer turn out to be incorrect.

- Quick Quiz 1.3** The distance between two cities is 100 mi. What is the number of kilometers between the two cities? (a) smaller than 100 (b) larger than 100 (c) equal to 100

Example 1.3 Is He Speeding?

On an interstate highway in a rural region of Wyoming, a car is traveling at a speed of 38.0 m/s. Is the driver exceeding the speed limit of 75.0 mi/h?

SOLUTION

Convert meters in the speed to miles:

$$(38.0 \text{ m/s}) \left(\frac{1 \text{ mi}}{1609 \text{ m}} \right) = 2.36 \times 10^{-2} \text{ mi/s}$$

Convert seconds to hours:

$$(2.36 \times 10^{-2} \text{ mi/s}) \left(\frac{60 \text{ s}}{1 \text{ min}} \right) \left(\frac{60 \text{ min}}{1 \text{ h}} \right) = 85.0 \text{ mi/h}$$

The driver is indeed exceeding the speed limit and should slow down.

WHAT IF? What if the driver were from outside the United States and is familiar with speeds measured in kilometers per hour? What is the speed of the car in km/h?

Answer We can convert our final answer to the appropriate units:

$$(85.0 \text{ mi/h}) \left(\frac{1.609 \text{ km}}{1 \text{ mi}} \right) = 137 \text{ km/h}$$

Figure 1.3 shows an automobile speedometer displaying speeds in both mi/h and km/h. Can you check the conversion we just performed using this photograph?



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Figure 1.3 The speedometer of a vehicle that shows speeds in both miles per hour and kilometers per hour.

1.5 Estimates and Order-of-Magnitude Calculations

Suppose someone asks you the number of bits of data on a typical musical compact disc. In response, it is not generally expected that you would provide the exact number but rather an estimate, which may be expressed in scientific notation. The estimate may be made even more approximate by expressing it as an *order of magnitude*, which is a power of ten determined as follows:

1. Express the number in scientific notation, with the multiplier of the power of ten between 1 and 10 and a unit.
2. If the multiplier is less than 3.162 (the square root of 10), the order of magnitude of the number is the power of 10 in the scientific notation. If the multiplier is greater than 3.162, the order of magnitude is one larger than the power of 10 in the scientific notation.

We use the symbol \sim for “is on the order of.” Use the procedure above to verify the orders of magnitude for the following lengths:

$$0.0086 \text{ m} \sim 10^{-2} \text{ m} \quad 0.0021 \text{ m} \sim 10^{-3} \text{ m} \quad 720 \text{ m} \sim 10^3 \text{ m}$$

Usually, when an order-of-magnitude estimate is made, the results are reliable to within about a factor of 10. If a quantity increases in value by three orders of magnitude, its value increases by a factor of about $10^3 = 1\,000$.

Inaccuracies caused by guessing too low for one number are often canceled by other guesses that are too high. You will find that with practice your guesstimates become better and better. Estimation problems can be fun to work because you freely drop digits, venture reasonable approximations for unknown numbers, make simplifying assumptions, and turn the question around into something you can answer in your head or with minimal mathematical manipulation on paper. Because of the simplicity of these types of calculations, they can be performed on a *small* scrap of paper and are often called “back-of-the-envelope calculations.”

Example 1.4 Breaths in a Lifetime

Estimate the number of breaths taken during an average human lifetime.

SOLUTION

We start by guessing that the typical human lifetime is about 70 years. Think about the average number of breaths that a person takes in 1 min. This number varies depending on whether the person is exercising, sleeping, angry, serene, and so forth. To the nearest order of magnitude, we shall choose 10 breaths per minute as our estimate. (This estimate is certainly closer to the true average value than an estimate of 1 breath per minute or 100 breaths per minute.)

Find the approximate number of minutes in a year: $1 \text{ yr} \left(\frac{400 \text{ days}}{1 \text{ yr}} \right) \left(\frac{25 \text{ h}}{1 \text{ day}} \right) \left(\frac{60 \text{ min}}{1 \text{ h}} \right) = 6 \times 10^5 \text{ min}$

Find the approximate number of minutes in a 70-year lifetime: $\text{number of minutes} = (70 \text{ yr})(6 \times 10^5 \text{ min/yr}) = 4 \times 10^7 \text{ min}$

Find the approximate number of breaths in a lifetime: $\text{number of breaths} = (10 \text{ breaths/min})(4 \times 10^7 \text{ min}) = 4 \times 10^8 \text{ breaths}$

Therefore, a person takes on the order of 10^9 breaths in a lifetime. Notice how much simpler it is in the first calculation above to multiply 400×25 than it is to work with the more accurate 365×24 .

WHAT IF? What if the average lifetime were estimated as 80 years instead of 70? Would that change our final estimate?

Answer We could claim that $(80 \text{ yr})(6 \times 10^5 \text{ min/yr}) = 5 \times 10^7 \text{ min}$, so our final estimate should be 5×10^8 breaths. This answer is still on the order of 10^9 breaths, so an order-of-magnitude estimate would be unchanged.

1.6 Significant Figures

When certain quantities are measured, the measured values are known only to within the limits of the experimental uncertainty. The value of this uncertainty can depend on various factors, such as the quality of the apparatus, the skill of the experimenter, and the number of measurements performed. The number of **significant figures** in a measurement can be used to express something about the uncertainty. The number of significant figures is related to the number of numerical digits used to express the measurement, as we discuss below.

As an example of significant figures, suppose we are asked to measure the radius of a compact disc using a meterstick as a measuring instrument. Let us assume the accuracy to which we can measure the radius of the disc is $\pm 0.1 \text{ cm}$. Because of the uncertainty of $\pm 0.1 \text{ cm}$, if the radius is measured to be 6.0 cm , we can claim only that its radius lies somewhere between 5.9 cm and 6.1 cm . In this case, we say that the measured value of 6.0 cm has two significant figures. Note that *the*

significant figures include the first estimated digit. Therefore, we could write the radius as (6.0 ± 0.1) cm.

Zeros may or may not be significant figures. Those used to position the decimal point in such numbers as 0.03 and 0.007 5 are not significant. Therefore, there are one and two significant figures, respectively, in these two values. When the zeros come after other digits, however, there is the possibility of misinterpretation. For example, suppose the mass of an object is given as 1 500 g. This value is ambiguous because we do not know whether the last two zeros are being used to locate the decimal point or whether they represent significant figures in the measurement. To remove this ambiguity, it is common to use scientific notation to indicate the number of significant figures. In this case, we would express the mass as 1.5×10^3 g if there are two significant figures in the measured value, 1.50×10^3 g if there are three significant figures, and 1.500×10^3 g if there are four. The same rule holds for numbers less than 1, so 2.3×10^{-4} has two significant figures (and therefore could be written 0.000 23) and 2.30×10^{-4} has three significant figures (also written as 0.000 230).

In problem solving, we often combine quantities mathematically through multiplication, division, addition, subtraction, and so forth. When doing so, you must make sure that the result has the appropriate number of significant figures. A good rule of thumb to use in determining the number of significant figures that can be claimed in a multiplication or a division is as follows:

When multiplying several quantities, the number of significant figures in the final answer is the same as the number of significant figures in the quantity having the smallest number of significant figures. The same rule applies to division.

Let's apply this rule to find the area of the compact disc whose radius we measured above. Using the equation for the area of a circle,

$$A = \pi r^2 = \pi(6.0 \text{ cm})^2 = 1.1 \times 10^2 \text{ cm}^2$$

If you perform this calculation on your calculator, you will likely see 113.097 335 5. It should be clear that you don't want to keep all of these digits, but you might be tempted to report the result as 113 cm². This result is not justified because it has three significant figures, whereas the radius only has two. Therefore, we must report the result with only two significant figures as shown above.

For addition and subtraction, you must consider the number of decimal places when you are determining how many significant figures to report:

When numbers are added or subtracted, the number of decimal places in the result should equal the smallest number of decimal places of any term in the sum or difference.

Pitfall Prevention 1.4

Read Carefully Notice that the rule for addition and subtraction is different from that for multiplication and division. For addition and subtraction, the important consideration is the number of *decimal places*, not the number of *significant figures*.

As an example of this rule, consider the sum

$$23.2 + 5.174 = 28.4$$

Notice that we do not report the answer as 28.374 because the lowest number of decimal places is one, for 23.2. Therefore, our answer must have only one decimal place.

The rule for addition and subtraction can often result in answers that have a different number of significant figures than the quantities with which you start. For example, consider these operations that satisfy the rule:

$$1.000\ 1 + 0.000\ 3 = 1.000\ 4$$

$$1.002 - 0.998 = 0.004$$

In the first example, the result has five significant figures even though one of the terms, 0.000 3, has only one significant figure. Similarly, in the second calculation, the result has only one significant figure even though the numbers being subtracted have four and three, respectively.

In this book, most of the numerical examples and end-of-chapter problems will yield answers having three significant figures. When carrying out estimation calculations, we shall typically work with a single significant figure.

If the number of significant figures in the result of a calculation must be reduced, there is a general rule for rounding numbers: the last digit retained is increased by 1 if the last digit dropped is greater than 5. (For example, 1.346 becomes 1.35.) If the last digit dropped is less than 5, the last digit retained remains as it is. (For example, 1.343 becomes 1.34.) If the last digit dropped is equal to 5, the remaining digit should be rounded to the nearest even number. (This rule helps avoid accumulation of errors in long arithmetic processes.)

A technique for avoiding error accumulation is to delay the rounding of numbers in a long calculation until you have the final result. Wait until you are ready to copy the final answer from your calculator before rounding to the correct number of significant figures. In this book, we display numerical values rounded off to two or three significant figures. This occasionally makes some mathematical manipulations look odd or incorrect. For instance, looking ahead to Example 3.5 on page 69, you will see the operation $-17.7 \text{ km} + 34.6 \text{ km} = 17.0 \text{ km}$. This looks like an incorrect subtraction, but that is only because we have rounded the numbers 17.7 km and 34.6 km for display. If all digits in these two intermediate numbers are retained and the rounding is only performed on the final number, the correct three-digit result of 17.0 km is obtained.

◀ **Significant figure guidelines used in this book**

Pitfall Prevention 1.5

Symbolic Solutions When solving problems, it is very useful to perform the solution completely in algebraic form and wait until the very end to enter numerical values into the final symbolic expression. This method will save many calculator keystrokes, especially if some quantities cancel so that you never have to enter their values into your calculator! In addition, you will only need to round once, on the final result.

Example 1.5 Installing a Carpet

A carpet is to be installed in a rectangular room whose length is measured to be 12.71 m and whose width is measured to be 3.46 m. Find the area of the room.

SOLUTION

If you multiply 12.71 m by 3.46 m on your calculator, you will see an answer of 43.9766 m^2 . How many of these numbers should you claim? Our rule of thumb for multiplication tells us that you can claim only the number of significant figures in your answer as are present in the measured quantity having the lowest number of significant figures. In this example, the lowest number of significant figures is three in 3.46 m, so we should express our final answer as 44.0 m^2 .

Summary

Definitions

The three fundamental physical quantities of mechanics are **length**, **mass**, and **time**, which in the SI system have the units **meter** (m), **kilogram** (kg), and **second** (s), respectively. These fundamental quantities cannot be defined in terms of more basic quantities.

The **density** of a substance is defined as its *mass per unit volume*:

$$\rho \equiv \frac{m}{V} \quad (1.1)$$

continued

Concepts and Principles

The method of **dimensional analysis** is very powerful in solving physics problems. Dimensions can be treated as algebraic quantities. By making estimates and performing order-of-magnitude calculations, you should be able to approximate the answer to a problem when there is not enough information available to specify an exact solution completely.

When you compute a result from several measured numbers, each of which has a certain accuracy, you should give the result with the correct number of **significant figures**.

When **multiplying** several quantities, the number of significant figures in the final answer is the same as the number of significant figures in the quantity having the smallest number of significant figures. The same rule applies to **division**.

When numbers are **added** or **subtracted**, the number of decimal places in the result should equal the smallest number of decimal places of any term in the sum or difference.

Objective Questions

1. denotes answer available in *Student Solutions Manual/Study Guide*

- One student uses a meterstick to measure the thickness of a textbook and obtains $4.3 \text{ cm} \pm 0.1 \text{ cm}$. Other students measure the thickness with vernier calipers and obtain four different measurements: (a) $4.32 \text{ cm} \pm 0.01 \text{ cm}$, (b) $4.31 \text{ cm} \pm 0.01 \text{ cm}$, (c) $4.24 \text{ cm} \pm 0.01 \text{ cm}$, and (d) $4.43 \text{ cm} \pm 0.01 \text{ cm}$. Which of these four measurements, if any, agree with that obtained by the first student?
- A house is advertised as having 1 420 square feet under its roof. What is its area in square meters? (a) $4\,660 \text{ m}^2$ (b) 432 m^2 (c) 158 m^2 (d) 132 m^2 (e) 40.2 m^2
- Answer each question yes or no. Must two quantities have the same dimensions (a) if you are adding them? (b) If you are multiplying them? (c) If you are subtracting them? (d) If you are dividing them? (e) If you are equating them?
- The price of gasoline at a particular station is 1.5 euros per liter. An American student can use 33 euros to buy gasoline. Knowing that 4 quarts make a gallon and that 1 liter is close to 1 quart, she quickly reasons that she can buy how many gallons of gasoline? (a) less than 1 gallon (b) about 5 gallons (c) about 8 gallons (d) more than 10 gallons
- Rank the following five quantities in order from the largest to the smallest. If two of the quantities are equal, give them equal rank in your list. (a) 0.032 kg (b) 15 g (c) $2.7 \times 10^5 \text{ mg}$ (d) $4.1 \times 10^{-8} \text{ Gg}$ (e) $2.7 \times 10^8 \mu\text{g}$
- What is the sum of the measured values $21.4 \text{ s} + 15 \text{ s} + 17.17 \text{ s} + 4.00 \text{ s}$? (a) 57.573 s (b) 57.57 s (c) 57.6 s (d) 58 s (e) 60 s
- Which of the following is the best estimate for the mass of all the people living on the Earth? (a) $2 \times 10^8 \text{ kg}$ (b) $1 \times 10^9 \text{ kg}$ (c) $2 \times 10^{10} \text{ kg}$ (d) $3 \times 10^{11} \text{ kg}$ (e) $4 \times 10^{12} \text{ kg}$
- (a) If an equation is dimensionally correct, does that mean that the equation must be true? (b) If an equation is not dimensionally correct, does that mean that the equation cannot be true?
- Newton's second law of motion (Chapter 5) says that the mass of an object times its acceleration is equal to the net force on the object. Which of the following gives the correct units for force? (a) $\text{kg} \cdot \text{m}/\text{s}^2$ (b) $\text{kg} \cdot \text{m}^2/\text{s}^2$ (c) $\text{kg}/\text{m} \cdot \text{s}^2$ (d) $\text{kg} \cdot \text{m}^2/\text{s}$ (e) none of those answers
- A calculator displays a result as $1.365\,248\,0 \times 10^7 \text{ kg}$. The estimated uncertainty in the result is $\pm 2\%$. How many digits should be included as significant when the result is written down? (a) zero (b) one (c) two (d) three (e) four

Conceptual Questions

1. denotes answer available in *Student Solutions Manual/Study Guide*

- Suppose the three fundamental standards of the metric system were length, *density*, and time rather than length, *mass*, and time. The standard of density in this system is to be defined as that of water. What considerations about water would you need to address to make sure that the standard of density is as accurate as possible?
- Why is the metric system of units considered superior to most other systems of units?
- What natural phenomena could serve as alternative time standards?
- Express the following quantities using the prefixes given in Table 1.4. (a) $3 \times 10^{-4} \text{ m}$ (b) $5 \times 10^{-5} \text{ s}$ (c) $72 \times 10^2 \text{ g}$