

CALCULUS EARLY TRANSCENDENTALS EIGHTH EDITION

JAMES STEWART

McMASTER UNIVERSITY AND UNIVERSITY OF TORONTO



Australia • Brazil • Mexico • Singapore • United Kingdom • United States

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it.

This is an electronic version of the print textbook. Due to electronic rights restrictions, some third party content may be suppressed. Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. The publisher reserves the right to remove content from this title at any time if subsequent rights restrictions require it. For valuable information on pricing, previous editions, changes to current editions, and alternate formats, please visit <u>www.cengage.com/highered</u> to search by ISBN#, author, title, or keyword for materials in your areas of interest.

Important Notice: Media content referenced within the product description or the product text may not be available in the eBook version.



Calculus: Early Transcendentals, Eighth Edition James Stewart

Product Manager: Neha Taleja

- Senior Content Developer: Stacy Green
- Associate Content Developer: Samantha Lugtu Product Assistant: Stephanie Kreuz
- Media Developer: Lynh Pham
- Marketing Manager: Ryan Ahern
- Content Project Manager: Cheryll Linthicum
- Art Director: Vernon Boes

Manufacturing Planner: Becky Cross

- Production Service: TECHarts
- Photo and Text Researcher: Lumina Datamatics
- Copy Editor: Kathi Townes, TECHarts
- Illustrator: TECHarts
- Text Designer: Diane Beasley
- Cover Designer: Irene Morris, Morris Design
- Compositor: Stephanie Kuhns, Kristina Elliott,
- and Kira Abdallah, TECHarts
- Cover Image: elisanth/123RF; tharrison/Getty Images

© 2016, 2012 Cengage Learning

WCN: 02-200-203

ALL RIGHTS RESERVED. No part of this work covered by the copyright herein may be reproduced, transmitted, stored, or used in any form or by any means graphic, electronic, or mechanical, including but not limited to photocopying, recording, scanning, digitizing, taping, Web distribution, information networks, or information storage and retrieval systems, except as permitted under Section 107 or 108 of the 1976 United States Copyright Act, without the prior written permission of the publisher.

For product information and technology assistance, contact us at Cengage Learning Customer & Sales Support, 1-800-354-9706.

For permission to use material from this text or product, submit all requests online at **www.cengage.com/permissions**. Further permissions questions can be e-mailed to **permissionrequest@cengage.com**.

Library of Congress Control Number: 2014951195

Student Edition: ISBN: 978-1-285-74155-0

Loose-leaf Edition: ISBN: 978-1-305-27235-4

Cengage Learning

20 Channel Center Street Boston, MA 02210 USA

Cengage Learning is a leading provider of customized learning solutions with office locations around the globe, including Singapore, the United Kingdom, Australia, Mexico, Brazil, and Japan. Locate your local office at **www.cengage.com/global**.

Cengage Learning products are represented in Canada by Nelson Education, Ltd.

To learn more about Cengage Learning Solutions, visit **www.cengage.com**. **Purchase any of our products at your local college store or at our pre**ferred online store **www.cengagebrain.com**.

Windows is a registered trademark of the Microsoft Corporation and used herein under license.

Macintosh is a registered trademark of Apple Computer, Inc. Used herein under license.

Maple is a registered trademark of Waterloo Maple, Inc.

Mathematica is a registered trademark of Wolfram Research, Inc. Tools for Enriching Calculus is a trademark used herein under license.

Printed in the United States of America Print Number: 01 Print Year: 2014

Contents

PREFACE xi TO THE STUDENT xxiii CALCULATORS, COMPUTERS, AND OTHER GRAPHING DEVICES xxiv DIAGNOSTIC TESTS xxvi

A Preview of Calculus 1

Functions and Models

- **1.1** Four Ways to Represent a Function 10
- 1.2 Mathematical Models: A Catalog of Essential Functions 23
- **1.3** New Functions from Old Functions 36
- 1.4 Exponential Functions 45
- **1.5** Inverse Functions and Logarithms 55 Review 68

Principles of Problem Solving 71

2

Limits and Derivatives

- 2.1 The Tangent and Velocity Problems 78
- 2.2 The Limit of a Function 83
- 2.3 Calculating Limits Using the Limit Laws 95
- 2.4 The Precise Definition of a Limit 104
- 2.5 Continuity 114
- 2.6 Limits at Infinity; Horizontal Asymptotes 126

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it.

- 2.7 Derivatives and Rates of Change 140Writing Project Early Methods for Finding Tangents 152
- 2.8 The Derivative as a Function 152

Review 165

Problems Plus 169

9

77





Differentiation Rules

- **3.1** Derivatives of Polynomials and Exponential Functions 172 Applied Project • Building a Better Roller Coaster 182
- 3.2 The Product and Quotient Rules 183
- 3.3 Derivatives of Trigonometric Functions 190
- 3.4 The Chain Rule 197
 - Applied Project Where Should a Pilot Start Descent? 208
- 3.5 Implicit Differentiation 208

Laboratory Project • Families of Implicit Curves 217

- **3.6** Derivatives of Logarithmic Functions 218
- **3.7** Rates of Change in the Natural and Social Sciences 224
- **3.8** Exponential Growth and Decay 237 Applied Project • Controlling Red Blood Cell Loss During Surgery 244
- 3.9 Related Rates 245
- **3.10** Linear Approximations and Differentials 251 Laboratory Project • Taylor Polynomials 258
- **3.11** Hyperbolic Functions 259 Review 266

Problems Plus 270



Applications of Differentiation

- 4.1 Maximum and Minimum Values 276
 Applied Project The Calculus of Rainbows 285
 4.2 The Mark Value Theorem 202
 - 4.2 The Mean Value Theorem 287
 - 4.3 How Derivatives Affect the Shape of a Graph 293
 - Indeterminate Forms and l'Hospital's Rule 304
 Writing Project The Origins of l'Hospital's Rule 314
 - 4.5 Summary of Curve Sketching 315
 - 4.6 Graphing with Calculus and Calculators 323
 - **4.7** Optimization Problems 330

Applied Project • The Shape of a Can 343

Applied Project • Planes and Birds: Minimizing Energy 344

- 4.8 Newton's Method 345
- 4.9 Antiderivatives 350
 - Review 358

Problems Plus 363



275

365

427



Integrals

- 5.1 Areas and Distances 366
- 5.2 The Definite Integral 378
 - Discovery Project Area Functions 391
- 5.3 The Fundamental Theorem of Calculus 392
- **5.4** Indefinite Integrals and the Net Change Theorem 402

Writing Project • Newton, Leibniz, and the Invention of Calculus 411

5.5 The Substitution Rule 412

Review 421

Problems Plus 425

6

Applications of Integration

- 6.1 Areas Between Curves 428 Applied Project • The Gini Index 436
- **6.2** Volumes 438
- 6.3 Volumes by Cylindrical Shells 449
- 6.4 Work 455
- 6.5 Average Value of a Function 461

Applied Project • Calculus and Baseball 464

Applied Project • Where to Sit at the Movies 465

Review 466

Problems Plus 468

7

Techniques of Integration

471



- 7.1 Integration by Parts 472
- 7.2 Trigonometric Integrals 479
- 7.3 Trigonometric Substitution 486
- 7.4 Integration of Rational Functions by Partial Fractions 493
- 7.5 Strategy for Integration 503
- 7.6 Integration Using Tables and Computer Algebra Systems 508Discovery Project Patterns in Integrals 513
- 7.7 Approximate Integration 514
- 7.8 Improper Integrals 527
 - Review 537

Problems Plus 540



Further Applications of Integration

8.1 Arc Length 544

Discovery Project • Arc Length Contest 550

8.2 Area of a Surface of Revolution 551

Discovery Project • Rotating on a Slant 557

- 8.3 Applications to Physics and Engineering 558 Discovery Project • Complementary Coffee Cups 568
- 8.4 Applications to Economics and Biology 569
- 8.5 Probability 573

Review 581

Problems Plus 583

Differential Equations

Modeling with Differential Equations 586

- Direction Fields and Euler's Method 591
- 9.3 Separable Equations 599 Applied Project • How Fast Does a Tank Drain? 608 Applied Project • Which Is Faster, Going Up or Coming Down? 609
- 9.4 Models for Population Growth 610
- 9.5 Linear Equations 620
- 9.6 Predator-Prey Systems 627

Review 634

Problems Plus 637



Parametric Equations and Polar Coordinates

639



- 10.1 Curves Defined by Parametric Equations 640 Laboratory Project • Running Circles Around Circles 648 10.2
 - Calculus with Parametric Curves 649
 - Laboratory Project Bézier Curves 657
- 10.3 Polar Coordinates 658
 - Laboratory Project Families of Polar Curves 668
- 10.4 Areas and Lengths in Polar Coordinates 669

9.1 9.2

585

543

693

791

- 10.5 Conic Sections 674
- **10.6** Conic Sections in Polar Coordinates 682

Review 689

Problems Plus 692

11 Infinite Sequences and Series

- 11.1 Sequences 694
 - Laboratory Project Logistic Sequences 707
- 11.2 Series 707
- **11.3** The Integral Test and Estimates of Sums 719
- 11.4 The Comparison Tests 727
- **11.5** Alternating Series 732
- **11.6** Absolute Convergence and the Ratio and Root Tests 737
- **11.7** Strategy for Testing Series 744
- **11.8** Power Series 746
- **11.9** Representations of Functions as Power Series 752
- **11.10** Taylor and Maclaurin Series 759
 Laboratory Project An Elusive Limit 773
 Writing Project How Newton Discovered the Binomial Series 773
- 11.11 Applications of Taylor Polynomials 774Applied Project Radiation from the Stars 783Review 784

Problems Plus 787

12

Vectors and the Geometry of Space

- 12.1 Three-Dimensional Coordinate Systems 792
- 12.2 Vectors 798
- 12.3 The Dot Product 807
- **12.4** The Cross Product 814

Discovery Project • The Geometry of a Tetrahedron 823

- **12.5** Equations of Lines and Planes 823 Laboratory Project • Putting 3D in Perspective 833
- 12.6 Cylinders and Quadric Surfaces 834

Review 841

Problems Plus 844



Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it



13

14

- **Vector Functions**
 - 13.1 Vector Functions and Space Curves 848
 - 13.2 Derivatives and Integrals of Vector Functions 855
 - 13.3 Arc Length and Curvature 861
 - 13.4 Motion in Space: Velocity and Acceleration 870 Applied Project • Kepler's Laws 880

Review 881

Problems Plus 884



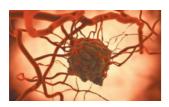
- **Partial Derivatives**
 - 14.1 Functions of Several Variables 888
 - 14.2 Limits and Continuity 903
 - 14.3 Partial Derivatives 911
 - 14.4 Tangent Planes and Linear Approximations 927
 - Applied Project The Speedo LZR Racer 936
 - 14.5 The Chain Rule 937
 - 14.6 Directional Derivatives and the Gradient Vector 946
- 14.7 Maximum and Minimum Values 959
 - Applied Project Designing a Dumpster 970
 - Discovery Project Quadratic Approximations and Critical Points 970
- 14.8 Lagrange Multipliers 971
 - Applied Project Rocket Science 979

Applied Project • Hydro-Turbine Optimization 980

Review 981

Problems Plus 985

Multiple Integrals



- 15.1 Double Integrals over Rectangles 988
- 15.2 Double Integrals over General Regions 1001
- 15.3 Double Integrals in Polar Coordinates 1010
- 15.4 Applications of Double Integrals 1016
- 15.5 Surface Area 1026

887

987

847

15.6 Triple Integrals 1029

Discovery Project • Volumes of Hyperspheres 1040

- **15.7** Triple Integrals in Cylindrical Coordinates 1040 Discovery Project • The Intersection of Three Cylinders 1044
- **15.8** Triple Integrals in Spherical Coordinates 1045 Applied Project • Roller Derby 1052
- **15.9** Change of Variables in Multiple Integrals 1052 Review 1061

Problems Plus 1065

16 Vector Calculus

1067



- 16.1 Vector Fields 1068
- 16.2 Line Integrals 1075
- 16.3 The Fundamental Theorem for Line Integrals 1087
- 16.4 Green's Theorem 1096
- 16.5 Curl and Divergence 1103
- 16.6 Parametric Surfaces and Their Areas 1111
- 16.7 Surface Integrals 1122
- **16.8** Stokes' Theorem 1134 Writing Project • Three Men and Two Theorems 1140
- 16.9 The Divergence Theorem 1141
- 16.10 Summary 1147

Review 1148

Problems Plus 1151

7 Second-Order Differential Equations

1153



- **17.1** Second-Order Linear Equations 1154
- 17.2 Nonhomogeneous Linear Equations 1160
- 17.3 Applications of Second-Order Differential Equations 1168
- 17.4 Series Solutions 1176 Review 1181

Х

Appendixes

- A Numbers, Inequalities, and Absolute Values A2
- **B** Coordinate Geometry and Lines A10
- **C** Graphs of Second-Degree Equations A16
- **D** Trigonometry A24
- E Sigma Notation A34
- F Proofs of Theorems A39
- **G** The Logarithm Defined as an Integral A50
- H Complex Numbers A57
- I Answers to Odd-Numbered Exercises A65

Index

A139

Preface

A great discovery solves a great problem but there is a grain of discovery in the solution of any problem. Your problem may be modest; but if it challenges your curiosity and brings into play your inventive faculties, and if you solve it by your own means, you may experience the tension and enjoy the triumph of discovery.

GEORGE POLYA

The art of teaching, Mark Van Doren said, is the art of assisting discovery. I have tried to write a book that assists students in discovering calculus—both for its practical power and its surprising beauty. In this edition, as in the first seven editions, I aim to convey to the student a sense of the utility of calculus and develop technical competence, but I also strive to give some appreciation for the intrinsic beauty of the subject. Newton undoubtedly experienced a sense of triumph when he made his great discoveries. I want students to share some of that excitement.

The emphasis is on understanding concepts. I think that nearly everybody agrees that this should be the primary goal of calculus instruction. In fact, the impetus for the current calculus reform movement came from the Tulane Conference in 1986, which formulated as their first recommendation:

Focus on conceptual understanding.

I have tried to implement this goal through the *Rule of Three:* "Topics should be presented geometrically, numerically, and algebraically." Visualization, numerical and graphical experimentation, and other approaches have changed how we teach conceptual reasoning in fundamental ways. More recently, the Rule of Three has been expanded to become the *Rule of Four* by emphasizing the verbal, or descriptive, point of view as well.

In writing the eighth edition my premise has been that it is possible to achieve conceptual understanding and still retain the best traditions of traditional calculus. The book contains elements of reform, but within the context of a traditional curriculum.

Alternate Versions

I have written several other calculus textbooks that might be preferable for some instructors. Most of them also come in single variable and multivariable versions.

- *Calculus*, Eighth Edition, is similar to the present textbook except that the exponential, logarithmic, and inverse trigonometric functions are covered in the second semester.
- *Essential Calculus*, Second Edition, is a much briefer book (840 pages), though it contains almost all of the topics in *Calculus*, Eighth Edition. The relative brevity is achieved through briefer exposition of some topics and putting some features on the website.
- *Essential Calculus: Early Transcendentals*, Second Edition, resembles *Essential Calculus*, but the exponential, logarithmic, and inverse trigonometric functions are covered in Chapter 3.

- *Calculus: Concepts and Contexts*, Fourth Edition, emphasizes conceptual understanding even more strongly than this book. The coverage of topics is not encyclopedic and the material on transcendental functions and on parametric equations is woven throughout the book instead of being treated in separate chapters.
- *Calculus: Early Vectors* introduces vectors and vector functions in the first semester and integrates them throughout the book. It is suitable for students taking engineering and physics courses concurrently with calculus.
- *Brief Applied Calculus* is intended for students in business, the social sciences, and the life sciences.
- *Biocalculus: Calculus for the Life Sciences* is intended to show students in the life sciences how calculus relates to biology.
- *Biocalculus: Calculus, Probability, and Statistics for the Life Sciences* contains all the content of *Biocalculus: Calculus for the Life Sciences* as well as three additional chapters covering probability and statistics.

What's New in the Eighth Edition?

The changes have resulted from talking with my colleagues and students at the University of Toronto and from reading journals, as well as suggestions from users and reviewers. Here are some of the many improvements that I've incorporated into this edition:

- The data in examples and exercises have been updated to be more timely.
- New examples have been added (see Examples 6.1.5, 11.2.5, and 14.3.3, for instance). And the solutions to some of the existing examples have been amplified.
- Three new projects have been added: The project *Controlling Red Blood Cell Loss During Surgery* (page 244) describes the ANH procedure, in which blood is extracted from the patient before an operation and is replaced by saline solution. This dilutes the patient's blood so that fewer red blood cells are lost during bleeding and the extracted blood is returned to the patient after surgery. The project *Planes and Birds: Minimizing Energy* (page 344) asks how birds can minimize power and energy by flapping their wings versus gliding. In the project *The Speedo LZR Racer* (page 936) it is explained that this suit reduces drag in the water and, as a result, many swimming records were broken. Students are asked why a small decrease in drag can have a big effect on performance.
- I have streamlined Chapter 15 (Multiple Integrals) by combining the first two sections so that iterated integrals are treated earlier.
- More than 20% of the exercises in each chapter are new. Here are some of my favorites: 2.7.61, 2.8.36–38, 3.1.79–80, 3.11.54, 4.1.69, 4.3.34, 4.3.66, 4.4.80, 4.7.39, 4.7.67, 5.1.19–20, 5.2.67–68, 5.4.70, 6.1.51, 8.1.39, 12.5.81, 12.6.29–30, 14.6.65–66. In addition, there are some good new Problems Plus. (See Problems 12–14 on page 272, Problem 13 on page 363, Problems 16–17 on page 426, and Problem 8 on page 986.)

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it

Features

Conceptual Exercises

The most important way to foster conceptual understanding is through the problems that we assign. To that end I have devised various types of problems. Some exercise sets begin with requests to explain the meanings of the basic concepts of the section. (See, for instance, the first few exercises in Sections 2.2, 2.5, 11.2, 14.2, and 14.3.) Similarly, all the review sections begin with a Concept Check and a True-False Quiz. Other exercises test conceptual understanding through graphs or tables (see Exercises 2.7.17, 2.8.35–38, 2.8.47–52, 9.1.11–13, 10.1.24–27, 11.10.2, 13.2.1–2, 13.3.33–39, 14.1.1–2, 14.1.32–38, 14.1.41–44, 14.3.3–10, 14.6.1–2, 14.7.3–4, 15.1.6–8, 16.1.11–18, 16.2.17–18, and 16.3.1–2).

Another type of exercise uses verbal description to test conceptual understanding (see Exercises 2.5.10, 2.8.66, 4.3.69–70, and 7.8.67). I particularly value problems that combine and compare graphical, numerical, and algebraic approaches (see Exercises 2.6.45–46, 3.7.27, and 9.4.4).

Graded Exercise Sets

Each exercise set is carefully graded, progressing from basic conceptual exercises and skill-development problems to more challenging problems involving applications and proofs.

Real-World Data

My assistants and I spent a great deal of time looking in libraries, contacting companies and government agencies, and searching the Internet for interesting real-world data to introduce, motivate, and illustrate the concepts of calculus. As a result, many of the examples and exercises deal with functions defined by such numerical data or graphs. See, for instance, Figure 1 in Section 1.1 (seismograms from the Northridge earthquake), Exercise 2.8.35 (unemployment rates), Exercise 5.1.16 (velocity of the space shuttle Endeavour), and Figure 4 in Section 5.4 (San Francisco power consumption). Functions of two variables are illustrated by a table of values of the wind-chill index as a function of air temperature and wind speed (Example 14.1.2). Partial derivatives are introduced in Section 14.3 by examining a column in a table of values of the heat index (perceived air temperature) as a function of the actual temperature and the relative humidity. This example is pursued further in connection with linear approximations (Example 14.4.3). Directional derivatives are introduced in Section 14.6 by using a temperature contour map to estimate the rate of change of temperature at Reno in the direction of Las Vegas. Double integrals are used to estimate the average snowfall in Colorado on December 20–21, 2006 (Example 15.1.9). Vector fields are introduced in Section 16.1 by depictions of actual velocity vector fields showing San Francisco Bay wind patterns.

Projects

One way of involving students and making them active learners is to have them work (perhaps in groups) on extended projects that give a feeling of substantial accomplishment when completed. I have included four kinds of projects: *Applied Projects* involve applications that are designed to appeal to the imagination of students. The project after Section 9.3 asks whether a ball thrown upward takes longer to reach its maximum height or to fall back to its original height. (The answer might surprise you.) The project after Section 14.8 uses Lagrange multipliers to determine the masses of the three stages of a rocket so as to minimize the total mass while enabling the rocket to reach a desired

velocity. *Laboratory Projects* involve technology; the one following Section 10.2 shows how to use Bézier curves to design shapes that represent letters for a laser printer. *Writing Projects* ask students to compare present-day methods with those of the founders of calculus—Fermat's method for finding tangents, for instance. Suggested references are supplied. *Discovery Projects* anticipate results to be discussed later or encourage discovery through pattern recognition (see the one following Section 7.6). Others explore aspects of geometry: tetrahedra (after Section 12.4), hyperspheres (after Section 15.6), and intersections of three cylinders (after Section 15.7). Additional projects can be found in the *Instructor's Guide* (see, for instance, Group Exercise 5.1: Position from Samples).

Problem Solving

Students usually have difficulties with problems for which there is no single well-defined procedure for obtaining the answer. I think nobody has improved very much on George Polya's four-stage problem-solving strategy and, accordingly, I have included a version of his problem-solving principles following Chapter 1. They are applied, both explicitly and implicitly, throughout the book. After the other chapters I have placed sections called *Problems Plus*, which feature examples of how to tackle challenging calculus problems. In selecting the varied problems for these sections I kept in mind the following advice from David Hilbert: "A mathematical problem should be difficult in order to entice us, yet not inaccessible lest it mock our efforts." When I put these challenging problems on assignments and tests I grade them in a different way. Here I reward a student significantly for ideas toward a solution and for recognizing which problem-solving principles are relevant.

Technology

The availability of technology makes it not less important but more important to clearly understand the concepts that underlie the images on the screen. But, when properly used, graphing calculators and computers are powerful tools for discovering and understanding those concepts. This textbook can be used either with or without technology and I use two special symbols to indicate clearly when a particular type of machine is required. The icon \bigwedge indicates an exercise that definitely requires the use of such technology, but that is not to say that it can't be used on the other exercises as well. The symbol \bowtie is reserved for problems in which the full resources of a computer algebra system (like Maple, Mathematica, or the TI-89) are required. But technology doesn't make pencil and paper obsolete. Hand calculation and sketches are often preferable to technology for illustrating and reinforcing some concepts. Both instructors and students need to develop the ability to decide where the hand or the machine is appropriate.

Tools for Enriching Calculus

TEC is a companion to the text and is intended to enrich and complement its contents. (It is now accessible in the eBook via CourseMate and Enhanced WebAssign. Selected Visuals and Modules are available at www.stewartcalculus.com.) Developed by Harvey Keynes, Dan Clegg, Hubert Hohn, and myself, TEC uses a discovery and exploratory approach. In sections of the book where technology is particularly appropriate, marginal icons direct students to TEC Modules that provide a laboratory environment in which they can explore the topic in different ways and at different levels. **Visuals are animations of figures in text; Modules are more elaborate activities and include exercises**. Instructors can choose to become involved at several different levels, ranging from simply encouraging students to use the Visuals and Modules for independent exploration, to assigning specific exercises from those included with each Module, or to creating additional exercises, labs, and projects that make use of the Visuals and Modules. TEC also includes Homework Hints for representative exercises (usually odd-numbered) in every section of the text, indicated by printing the exercise number in red. These hints are usually presented in the form of questions and try to imitate an effective teaching assistant by functioning as a silent tutor. They are constructed so as not to reveal any more of the actual solution than is minimally necessary to make further progress.

Enhanced WebAssign

Technology is having an impact on the way homework is assigned to students, particularly in large classes. The use of online homework is growing and its appeal depends on ease of use, grading precision, and reliability. With the Eighth Edition we have been working with the calculus community and WebAssign to develop an online homework system. Up to 70% of the exercises in each section are assignable as online homework, including free response, multiple choice, and multi-part formats.

The system also includes Active Examples, in which students are guided in step-bystep tutorials through text examples, with links to the textbook and to video solutions.

Website

Visit CengageBrain.com or stewartcalculus.com for these additional materials:

- Homework Hints
- Algebra Review
- · Lies My Calculator and Computer Told Me
- History of Mathematics, with links to the better historical websites
- Additional Topics (complete with exercise sets): Fourier Series, Formulas for the Remainder Term in Taylor Series, Rotation of Axes
- Archived Problems (Drill exercises that appeared in previous editions, together with their solutions)
- Challenge Problems (some from the Problems Plus sections from prior editions)
- Links, for particular topics, to outside Web resources
- Selected Visuals and Modules from Tools for Enriching Calculus (TEC)

Content

Diagnostic Tests	The book begins with four diagnostic tests, in Basic Algebra, Analytic Geometry, Func- tions, and Trigonometry.
A Preview of Calculus	This is an overview of the subject and includes a list of questions to motivate the study of calculus.
1 Functions and Models	From the beginning, multiple representations of functions are stressed: verbal, numeri- cal, visual, and algebraic. A discussion of mathematical models leads to a review of the standard functions, including exponential and logarithmic functions, from these four points of view.
2 Limits and Derivatives	The material on limits is motivated by a prior discussion of the tangent and velocity problems. Limits are treated from descriptive, graphical, numerical, and algebraic points of view. Section 2.4, on the precise definition of a limit, is an optional section. Sections

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it.

	2.7 and 2.8 deal with derivatives (especially with functions defined graphically and numerically) before the differentiation rules are covered in Chapter 3. Here the examples and exercises explore the meanings of derivatives in various contexts. Higher derivatives are introduced in Section 2.8.
3 Differentiation Rules	All the basic functions, including exponential, logarithmic, and inverse trigonometric functions, are differentiated here. When derivatives are computed in applied situations, students are asked to explain their meanings. Exponential growth and decay are now covered in this chapter.
4 Applications of Differentiation	The basic facts concerning extreme values and shapes of curves are deduced from the Mean Value Theorem. Graphing with technology emphasizes the interaction between calculus and calculators and the analysis of families of curves. Some substantial optimization problems are provided, including an explanation of why you need to raise your head 42° to see the top of a rainbow.
5 Integrals	The area problem and the distance problem serve to motivate the definite integral, with sigma notation introduced as needed. (Full coverage of sigma notation is provided in Appendix E.) Emphasis is placed on explaining the meanings of integrals in various contexts and on estimating their values from graphs and tables.
6 Applications of Integration	Here I present the applications of integration—area, volume, work, average value—that can reasonably be done without specialized techniques of integration. General methods are emphasized. The goal is for students to be able to divide a quantity into small pieces, estimate with Riemann sums, and recognize the limit as an integral.
7 Techniques of Integration	All the standard methods are covered but, of course, the real challenge is to be able to recognize which technique is best used in a given situation. Accordingly, in Section 7.5, I present a strategy for integration. The use of computer algebra systems is discussed in Section 7.6.
8 Further Applications of Integration	Here are the applications of integration—arc length and surface area—for which it is useful to have available all the techniques of integration, as well as applications to biol- ogy, economics, and physics (hydrostatic force and centers of mass). I have also included a section on probability. There are more applications here than can realistically be covered in a given course. Instructors should select applications suitable for their students and for which they themselves have enthusiasm.
9 Differential Equations	Modeling is the theme that unifies this introductory treatment of differential equations. Direction fields and Euler's method are studied before separable and linear equations are solved explicitly, so that qualitative, numerical, and analytic approaches are given equal consideration. These methods are applied to the exponential, logistic, and other models for population growth. The first four or five sections of this chapter serve as a good introduction to first-order differential equations. An optional final section uses predator-prey models to illustrate systems of differential equations.
10 Parametric Equations and Polar Coordinates	This chapter introduces parametric and polar curves and applies the methods of calculus to them. Parametric curves are well suited to laboratory projects; the two presented here involve families of curves and Bézier curves. A brief treatment of conic sections in polar coordinates prepares the way for Kepler's Laws in Chapter 13.

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it.

11 Infinite Sequences and Series	The convergence tests have intuitive justifications (see page 719) as well as formal proofs. Numerical estimates of sums of series are based on which test was used to prove convergence. The emphasis is on Taylor series and polynomials and their applications to physics. Error estimates include those from graphing devices.
12 Vectors and the Geometry of Space	The material on three-dimensional analytic geometry and vectors is divided into two chapters. Chapter 12 deals with vectors, the dot and cross products, lines, planes, and surfaces.
13 Vector Functions	This chapter covers vector-valued functions, their derivatives and integrals, the length and curvature of space curves, and velocity and acceleration along space curves, culmi- nating in Kepler's laws.
14 Partial Derivatives	Functions of two or more variables are studied from verbal, numerical, visual, and algebraic points of view. In particular, I introduce partial derivatives by looking at a specific column in a table of values of the heat index (perceived air temperature) as a function of the actual temperature and the relative humidity.
15 Multiple Integrals	Contour maps and the Midpoint Rule are used to estimate the average snowfall and average temperature in given regions. Double and triple integrals are used to compute probabilities, surface areas, and (in projects) volumes of hyperspheres and volumes of intersections of three cylinders. Cylindrical and spherical coordinates are introduced in the context of evaluating triple integrals.
16 Vector Calculus	Vector fields are introduced through pictures of velocity fields showing San Francisco Bay wind patterns. The similarities among the Fundamental Theorem for line integrals, Green's Theorem, Stokes' Theorem, and the Divergence Theorem are emphasized.
17 Second-Order Differential Equations	Since first-order differential equations are covered in Chapter 9, this final chapter deals with second-order linear differential equations, their application to vibrating springs and electric circuits, and series solutions.

Ancillaries

Calculus, Early Transcendentals, Eighth Edition, is supported by a complete set of ancillaries developed under my direction. Each piece has been designed to enhance student understanding and to facilitate creative instruction. The tables on pages xxi–xxii describe each of these ancillaries.

Acknowledgments

The preparation of this and previous editions has involved much time spent reading the reasoned (but sometimes contradictory) advice from a large number of astute reviewers. I greatly appreciate the time they spent to understand my motivation for the approach taken. I have learned something from each of them.

Eighth Edition Reviewers

Jay Abramson, *Arizona State University* Adam Bowers, *University of California San Diego* Neena Chopra, *The Pennsylvania State University* Edward Dobson, *Mississippi State University* Isaac Goldbring, *University of Illinois at Chicago* Lea Jenkins, *Clemson University* Rebecca Wahl, *Butler University*

Technology Reviewers

Maria Andersen, Muskegon Community College Eric Aurand, Eastfield College Joy Becker, University of Wisconsin-Stout Przemyslaw Bogacki, Old Dominion University Amy Elizabeth Bowman, University of Alabama in Huntsville Monica Brown, University of Missouri-St. Louis Roxanne Byrne, University of Colorado at Denver and Health Sciences Center Teri Christiansen, University of Missouri-Columbia Bobby Dale Daniel, Lamar University Jennifer Daniel, Lamar University Andras Domokos, California State University, Sacramento Timothy Flaherty, Carnegie Mellon University Lee Gibson, University of Louisville Jane Golden, Hillsborough Community College Semion Gutman, University of Oklahoma Diane Hoffoss, University of San Diego Lorraine Hughes, Mississippi State University Jay Jahangiri, Kent State University John Jernigan, Community College of Philadelphia

Brian Karasek, South Mountain Community College Jason Kozinski, University of Florida Carole Krueger, The University of Texas at Arlington Ken Kubota, University of Kentucky John Mitchell, Clark College Donald Paul, Tulsa Community College Chad Pierson, University of Minnesota, Duluth Lanita Presson, University of Alabama in Huntsville Karin Reinhold, State University of New York at Albany Thomas Riedel, University of Louisville Christopher Schroeder, Morehead State University Angela Sharp, University of Minnesota, Duluth Patricia Shaw, Mississippi State University Carl Spitznagel, John Carroll University Mohammad Tabanjeh, Virginia State University Capt. Koichi Takagi, United States Naval Academy Lorna TenEyck, Chemeketa Community College Roger Werbylo, Pima Community College David Williams, Clayton State University Zhuan Ye, Northern Illinois University

Previous Edition Reviewers

B. D. Aggarwala, University of Calgary John Alberghini, Manchester Community College Michael Albert, Carnegie-Mellon University Daniel Anderson, University of Iowa Amy Austin, Texas A&M University Donna J. Bailey, Northeast Missouri State University Wayne Barber, Chemeketa Community College Marilyn Belkin, Villanova University Neil Berger, University of Illinois, Chicago David Berman, University of New Orleans Anthony J. Bevelacqua, University of North Dakota Richard Biggs, University of Western Ontario Robert Blumenthal, Oglethorpe University Martina Bode, Northwestern University Barbara Bohannon, Hofstra University Jay Bourland, Colorado State University Philip L. Bowers, Florida State University Amy Elizabeth Bowman, University of Alabama in Huntsville Stephen W. Brady, Wichita State University Michael Breen, Tennessee Technological University Robert N. Bryan, University of Western Ontario

David Buchthal, University of Akron Jenna Carpenter, Louisiana Tech University Jorge Cassio, Miami-Dade Community College Jack Ceder, University of California, Santa Barbara Scott Chapman, Trinity University Zhen-Qing Chen, University of Washington—Seattle James Choike, Oklahoma State University Barbara Cortzen, DePaul University Carl Cowen, Purdue University Philip S. Crooke, Vanderbilt University Charles N. Curtis, Missouri Southern State College Daniel Cyphert, Armstrong State College Robert Dahlin M. Hilary Davies, University of Alaska Anchorage Gregory J. Davis, University of Wisconsin-Green Bay Elias Deeba, University of Houston-Downtown Daniel DiMaria, Suffolk Community College Seymour Ditor, University of Western Ontario Greg Dresden, Washington and Lee University Daniel Drucker, Wayne State University Kenn Dunn, Dalhousie University

Dennis Dunninger, Michigan State University Bruce Edwards, University of Florida David Ellis, San Francisco State University John Ellison, Grove City College Martin Erickson, Truman State University Garret Etgen, University of Houston Theodore G. Faticoni, Fordham University Laurene V. Fausett, Georgia Southern University Norman Feldman, Sonoma State University Le Baron O. Ferguson, University of California-Riverside Newman Fisher, San Francisco State University José D. Flores, The University of South Dakota William Francis, Michigan Technological University James T. Franklin, Valencia Community College, East Stanley Friedlander, Bronx Community College Patrick Gallagher, Columbia University-New York Paul Garrett, University of Minnesota-Minneapolis Frederick Gass, Miami University of Ohio Bruce Gilligan, University of Regina Matthias K. Gobbert, University of Maryland, Baltimore County Gerald Goff, Oklahoma State University Stuart Goldenberg, California Polytechnic State University John A. Graham, Buckingham Browne & Nichols School Richard Grassl, University of New Mexico Michael Gregory, University of North Dakota Charles Groetsch, University of Cincinnati Paul Triantafilos Hadavas, Armstrong Atlantic State University Salim M. Haïdar, Grand Valley State University D. W. Hall, Michigan State University Robert L. Hall, University of Wisconsin-Milwaukee Howard B. Hamilton, California State University, Sacramento Darel Hardy, Colorado State University Shari Harris, John Wood Community College Gary W. Harrison, College of Charleston Melvin Hausner, New York University/Courant Institute Curtis Herink, Mercer University Russell Herman, University of North Carolina at Wilmington Allen Hesse, Rochester Community College Randall R. Holmes, Auburn University James F. Hurley, University of Connecticut Amer Iqbal, University of Washington-Seattle Matthew A. Isom, Arizona State University Gerald Janusz, University of Illinois at Urbana-Champaign John H. Jenkins, Embry-Riddle Aeronautical University, Prescott Campus Clement Jeske, University of Wisconsin, Platteville Carl Jockusch, University of Illinois at Urbana-Champaign Jan E. H. Johansson, University of Vermont Jerry Johnson, Oklahoma State University Zsuzsanna M. Kadas, St. Michael's College Nets Katz, Indiana University Bloomington Matt Kaufman Matthias Kawski, Arizona State University Frederick W. Keene, Pasadena City College Robert L. Kelley, University of Miami Akhtar Khan, Rochester Institute of Technology

Marianne Korten, Kansas State University Virgil Kowalik, Texas A&I University Kevin Kreider, University of Akron Leonard Krop, DePaul University Mark Krusemeyer, Carleton College John C. Lawlor, University of Vermont Christopher C. Leary, State University of New York at Geneseo David Leeming, University of Victoria Sam Lesseig, Northeast Missouri State University Phil Locke, University of Maine Joyce Longman, Villanova University Joan McCarter, Arizona State University Phil McCartney, Northern Kentucky University Igor Malyshev, San Jose State University Larry Mansfield, Queens College Mary Martin, Colgate University Nathaniel F. G. Martin, University of Virginia Gerald Y. Matsumoto, American River College James McKinney, California State Polytechnic University, Pomona Tom Metzger, University of Pittsburgh Richard Millspaugh, University of North Dakota Lon H. Mitchell, Virginia Commonwealth University Michael Montaño, Riverside Community College Teri Jo Murphy, University of Oklahoma Martin Nakashima, California State Polytechnic University, Pomona Ho Kuen Ng, San Jose State University Richard Nowakowski, Dalhousie University Hussain S. Nur, California State University, Fresno Norma Ortiz-Robinson, Virginia Commonwealth University Wayne N. Palmer, Utica College Vincent Panico, University of the Pacific F. J. Papp, University of Michigan-Dearborn Mike Penna, Indiana University-Purdue University Indianapolis Mark Pinsky, Northwestern University Lothar Redlin, The Pennsylvania State University Joel W. Robbin, University of Wisconsin-Madison Lila Roberts, Georgia College and State University E. Arthur Robinson, Jr., The George Washington University Richard Rockwell, Pacific Union College Rob Root, Lafayette College Richard Ruedemann, Arizona State University David Ryeburn, Simon Fraser University Richard St. Andre, Central Michigan University Ricardo Salinas, San Antonio College Robert Schmidt, South Dakota State University Eric Schreiner, Western Michigan University Mihr J. Shah, Kent State University-Trumbull Qin Sheng, Baylor University Theodore Shifrin, University of Georgia Wayne Skrapek, University of Saskatchewan Larry Small, Los Angeles Pierce College Teresa Morgan Smith, Blinn College William Smith, University of North Carolina Donald W. Solomon, University of Wisconsin-Milwaukee Edward Spitznagel, Washington University

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it

Joseph Stampfli, Indiana University Kristin Stoley, Blinn College M. B. Tavakoli, Chaffey College Magdalena Toda, Texas Tech University Ruth Trygstad, Salt Lake Community College Paul Xavier Uhlig, St. Mary's University, San Antonio Stan Ver Nooy, University of Oregon Andrei Verona, California State University–Los Angeles Klaus Volpert, Villanova University Russell C. Walker, Carnegie Mellon University William L. Walton, McCallie School Peiyong Wang, Wayne State University Jack Weiner, University of Guelph Alan Weinstein, University of California, Berkeley Theodore W. Wilcox, Rochester Institute of Technology Steven Willard, University of Alberta Robert Wilson, University of Misconsin–Madison Jerome Wolbert, University of Michigan–Ann Arbor Dennis H. Wortman, University of Massachusetts, Boston Mary Wright, Southern Illinois University–Carbondale Paul M. Wright, Austin Community College Xian Wu, University of South Carolina

In addition, I would like to thank R. B. Burckel, Bruce Colletti, David Behrman, John Dersch, Gove Effinger, Bill Emerson, Dan Kalman, Quyan Khan, Alfonso Gracia-Saz, Allan MacIsaac, Tami Martin, Monica Nitsche, Lamia Raffo, Norton Starr, and Jim Trefzger for their suggestions; Al Shenk and Dennis Zill for permission to use exercises from their calculus texts; COMAP for permission to use project material; George Bergman, David Bleecker, Dan Clegg, Victor Kaftal, Anthony Lam, Jamie Lawson, Ira Rosenholtz, Paul Sally, Lowell Smylie, and Larry Wallen for ideas for exercises; Dan Drucker for the roller derby project; Thomas Banchoff, Tom Farmer, Fred Gass, John Ramsay, Larry Riddle, Philip Straffin, and Klaus Volpert for ideas for projects; Dan Anderson, Dan Clegg, Jeff Cole, Dan Drucker, and Barbara Frank for solving the new exercises and suggesting ways to improve them; Marv Riedesel and Mary Johnson for accuracy in proofreading; Andy Bulman-Fleming, Lothar Redlin, Gina Sanders, and Saleem Watson for additional proofreading; and Jeff Cole and Dan Clegg for their careful preparation and proofreading of the answer manuscript.

In addition, I thank those who have contributed to past editions: Ed Barbeau, George Bergman, Fred Brauer, Andy Bulman-Fleming, Bob Burton, David Cusick, Tom DiCiccio, Garret Etgen, Chris Fisher, Leon Gerber, Stuart Goldenberg, Arnold Good, Gene Hecht, Harvey Keynes, E. L. Koh, Zdislav Kovarik, Kevin Kreider, Emile LeBlanc, David Leep, Gerald Leibowitz, Larry Peterson, Mary Pugh, Lothar Redlin, Carl Riehm, John Ringland, Peter Rosenthal, Dusty Sabo, Doug Shaw, Dan Silver, Simon Smith, Saleem Watson, Alan Weinstein, and Gail Wolkowicz.

I also thank Kathi Townes, Stephanie Kuhns, Kristina Elliott, and Kira Abdallah of TECHarts for their production services and the following Cengage Learning staff: Cheryll Linthicum, content project manager; Stacy Green, senior content developer; Samantha Lugtu, associate content developer; Stephanie Kreuz, product assistant; Lynh Pham, media developer; Ryan Ahern, marketing manager; and Vernon Boes, art director. They have all done an outstanding job.

I have been very fortunate to have worked with some of the best mathematics editors in the business over the past three decades: Ron Munro, Harry Campbell, Craig Barth, Jeremy Hayhurst, Gary Ostedt, Bob Pirtle, Richard Stratton, Liz Covello, and now Neha Taleja. All of them have contributed greatly to the success of this book.

JAMES STEWART

Ancillaries for Instructors

Instructor's Guide

by Douglas Shaw ISBN 978-1-305-39371-4

> Each section of the text is discussed from several viewpoints. The Instructor's Guide contains suggested time to allot, points to stress, text discussion topics, core materials for lecture, workshop/discussion suggestions, group work exercises in a form suitable for handout, and suggested homework assignments.

Complete Solutions Manual

Single Variable Early Transcendentals

By Daniel Anderson, Jeffery A. Cole, and Daniel Drucker ISBN 978-1-305-27239-2

Multivariable

By Dan Clegg and Barbara Frank ISBN 978-1-305-27611-6 Includes worked-out solutions to all exercises in the text.

Printed Test Bank

By William Steven Harmon ISBN 978-1-305-38722-5

Contains text-specific multiple-choice and free response test items.

Cengage Learning Testing Powered by Cognero

(login.cengage.com)

This flexible online system allows you to author, edit, and manage test bank content from multiple Cengage Learning solutions; create multiple test versions in an instant; and deliver tests from your LMS, your classroom, or wherever you want.

Ancillaries for Instructors and Students

Stewart Website

www.stewartcalculus.com

Contents: Homework Hints
Algebra Review
Additional Topics
Drill exercises
Challenge Problems
Web Links
History of Mathematics
Tools for Enriching Calculus (TEC)

TEC TOOLS FOR ENRICHING[™] CALCULUS

By James Stewart, Harvey Keynes, Dan Clegg, and developer Hubert Hohn

Tools for Enriching Calculus (TEC) functions as both a powerful tool for instructors and as a tutorial environment in which students can explore and review selected topics. The Flash simulation modules in TEC include instructions, written and audio explanations of the concepts, and exercises. TEC is accessible in the eBook via CourseMate and Enhanced WebAssign. Selected Visuals and Modules are available at www.stewartcalculus.com.

WebAssign Enhanced WebAssign®

www.webassign.net

Printed Access Code: ISBN 978-1-285-85826-5 Instant Access Code ISBN: 978-1-285-85825-8

Exclusively from Cengage Learning, Enhanced WebAssign offers an extensive online program for Stewart's Calculus to encourage the practice that is so critical for concept mastery. The meticulously crafted pedagogy and exercises in our proven texts become even more effective in Enhanced WebAssign, supplemented by multimedia tutorial support and immediate feedback as students complete their assignments. Key features include:

- Thousands of homework problems that match your textbook's end-of-section exercises
- Opportunities for students to review prerequisite skills and content both at the start of the course and at the beginning of each section
- Read It eBook pages, Watch It videos, Master It tutorials, and Chat About It links
- A customizable Cengage YouBook with highlighting, notetaking, and search features, as well as links to multimedia resources
- Personal Study Plans (based on diagnostic quizzing) that identify chapter topics that students will need to master
- A WebAssign Answer Evaluator that recognizes and accepts equivalent mathematical responses in the same way an instructor grades
- A Show My Work feature that gives instructors the option of seeing students' detailed solutions
- Visualizing Calculus Animations, Lecture Videos, and more

Electronic items Printed items

(Table continues on page xxii)

Cengage Customizable YouBook

YouBook is an eBook that is both interactive and customizable. Containing all the content from Stewart's Calculus, YouBook features a text edit tool that allows instructors to modify the textbook narrative as needed. With YouBook, instructors can quickly reorder entire sections and chapters or hide any content they don't teach to create an eBook that perfectly matches their syllabus. Instructors can further customize the text by adding instructor-created or YouTube video links. Additional media assets include animated figures, video clips, highlighting and note-taking features, and more. YouBook is available within Enhanced WebAssign.

CourseMate

CourseMate is a perfect self-study tool for students, and requires no set up from instructors. CourseMate brings course concepts to life with interactive learning, study, and exam preparation tools that support the printed textbook. Course-Mate for Stewart's Calculus includes an interactive eBook, Tools for Enriching Calculus, videos, quizzes, flashcards, and more. For instructors, CourseMate includes Engagement Tracker, a first-of-its-kind tool that monitors student engagement.

CengageBrain.com

To access additional course materials, please visit www.cengagebrain.com. At the CengageBrain.com home page, search for the ISBN of your title (from the back cover of your book) using the search box at the top of the page. This will take you to the product page where these resources can be found.

Ancillaries for Students

Student Solutions Manual

Single Variable Early Transcendentals

By Daniel Anderson, Jeffery A. Cole, and Daniel Drucker ISBN 978-1-305-27242-2

Multivariable

By Dan Clegg and Barbara Frank ISBN 978-1-305-27182-1

Provides completely worked-out solutions to all oddnumbered exercises in the text, giving students a chance to check their answer and ensure they took the correct steps to arrive at the answer. The Student Solutions Manual can be ordered or accessed online as an eBook at www.cengagebrain.com by searching the ISBN.

Study Guide

Single Variable Early Transcendentals

By Richard St. Andre ISBN 978-1-305-27914-8

Multivariable

By Richard St. Andre ISBN 978-1-305-27184-5

For each section of the text, the Study Guide provides students with a brief introduction, a short list of concepts to master, and summary and focus questions with explained answers. The Study Guide also contains "Technology Plus" questions and multiple-choice "On Your Own" exam-style questions. The Study Guide can be ordered or accessed online as an eBook at www.cengagebrain.com by searching the ISBN.

A Companion to Calculus

By Dennis Ebersole, Doris Schattschneider, Alicia Sevilla, and Kay Somers

ISBN 978-0-495-01124-8

Written to improve algebra and problem-solving skills of students taking a calculus course, every chapter in this companion is keyed to a calculus topic, providing conceptual background and specific algebra techniques needed to understand and solve calculus problems related to that topic. It is designed for calculus courses that integrate the review of precalculus concepts or for individual use. Order a copy of the text or access the eBook online at www.cengagebrain.com by searching the ISBN.

Linear Algebra for Calculus

by Konrad J. Heuvers, William P. Francis, John H. Kuisti, Deborah F. Lockhart, Daniel S. Moak, and Gene M. Ortner ISBN 978-0-534-25248-9

This comprehensive book, designed to supplement the calculus course, provides an introduction to and review of the basic ideas of linear algebra. Order a copy of the text or access the eBook online at www.cengagebrain.com by searching the ISBN.

Electronic items Printed items

To the Student

Reading a calculus textbook is different from reading a newspaper or a novel, or even a physics book. Don't be discouraged if you have to read a passage more than once in order to understand it. You should have pencil and paper and calculator at hand to sketch a diagram or make a calculation.

Some students start by trying their homework problems and read the text only if they get stuck on an exercise. I suggest that a far better plan is to read and understand a section of the text before attempting the exercises. In particular, you should look at the definitions to see the exact meanings of the terms. And before you read each example, I suggest that you cover up the solution and try solving the problem yourself. You'll get a lot more from looking at the solution if you do so.

Part of the aim of this course is to train you to think logically. Learn to write the solutions of the exercises in a connected, step-by-step fashion with explanatory sentences not just a string of disconnected equations or formulas.

The answers to the odd-numbered exercises appear at the back of the book, in Appendix I. Some exercises ask for a verbal explanation or interpretation or description. In such cases there is no single correct way of expressing the answer, so don't worry that you haven't found the definitive answer. In addition, there are often several different forms in which to express a numerical or algebraic answer, so if your answer differs from mine, don't immediately assume you're wrong. For example, if the answer given in the back of the book is $\sqrt{2} - 1$ and you obtain $1/(1 + \sqrt{2})$, then you're right and rationalizing the denominator will show that the answers are equivalent.

The icon \bigwedge indicates an exercise that definitely requires the use of either a graphing calculator or a computer with graphing software. But that doesn't mean that graphing devices can't be used to check your work on the other exercises as well. The symbol is reserved for problems in which the full resources of a computer algebra system (like Maple, Mathematica, or the TI-89) are required.

You will also encounter the symbol O, which warns you against committing an error. I have placed this symbol in the margin in situations where I have observed that a large proportion of my students tend to make the same mistake.

Tools for Enriching Calculus, which is a companion to this text, is referred to by means of the symbol **TEC** and can be accessed in the eBook via Enhanced WebAssign and CourseMate (selected Visuals and Modules are available at www.stewartcalculus.com). It directs you to modules in which you can explore aspects of calculus for which the computer is particularly useful.

You will notice that some exercise numbers are printed in red: **5**. This indicates that *Homework Hints* are available for the exercise. These hints can be found on stewartcalculus.com as well as Enhanced WebAssign and CourseMate. The homework hints ask you questions that allow you to make progress toward a solution without actually giving you the answer. You need to pursue each hint in an active manner with pencil and paper to work out the details. If a particular hint doesn't enable you to solve the problem, you can click to reveal the next hint.

I recommend that you keep this book for reference purposes after you finish the course. Because you will likely forget some of the specific details of calculus, the book will serve as a useful reminder when you need to use calculus in subsequent courses. And, because this book contains more material than can be covered in any one course, it can also serve as a valuable resource for a working scientist or engineer.

Calculus is an exciting subject, justly considered to be one of the greatest achievements of the human intellect. I hope you will discover that it is not only useful but also intrinsically beautiful.

JAMES STEWART

Calculators, Computers, and Other Graphing Devices



Advances in technology continue to bring a wider variety of tools for doing mathematics. Handheld calculators are becoming more powerful, as are software programs and Internet resources. In addition, many mathematical applications have been released for smartphones and tablets such as the iPad.

Some exercises in this text are marked with a graphing icon \bigcap , which indicates that the use of some technology is required. Often this means that we intend for a graphing device to be used in drawing the graph of a function or equation. You might also need technology to find the zeros of a graph or the points of intersection of two graphs. In some cases we will use a calculating device to solve an equation or evaluate a definite integral numerically. Many scientific and graphing calculators have these features built in, such as the Texas Instruments TI-84 or TI-Nspire CX. Similar calculators are made by Hewlett Packard, Casio, and Sharp.

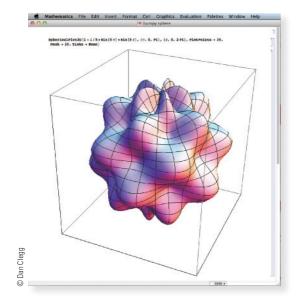




You can also use computer software such as *Graphing Calculator* by Pacific Tech (www.pacifict.com) to perform many of these functions, as well as apps for phones and tablets, like Quick Graph (Colombiamug) or Math-Studio (Pomegranate Apps). Similar functionality is available using a web interface at WolframAlpha.com.

xxiv

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it

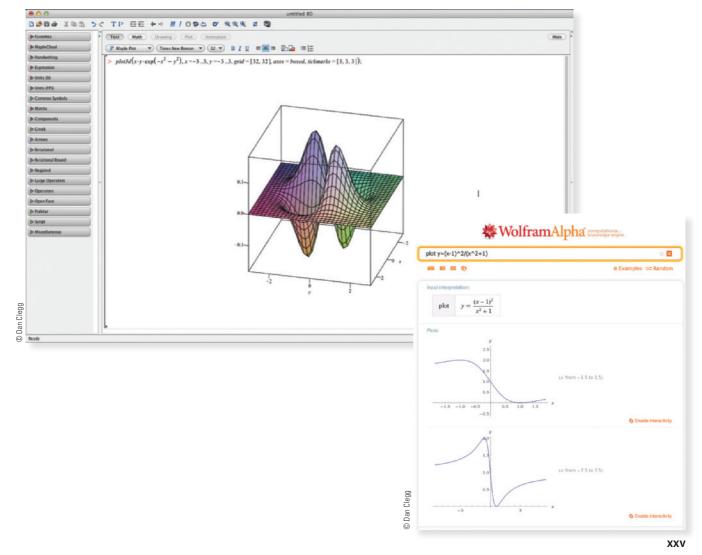


In general, when we use the term "calculator" in this book, we mean the use of any of the resources we have mentioned.

The cost icon is reserved for problems in which the full resources of a *computer algebra system* (CAS) are required. A CAS is capable of doing mathematics (like solving equations, computing derivatives or integrals) *symbolically* rather than just numerically.

Examples of well-established computer algebra systems are the computer software packages Maple and Mathematica. The WolframAlpha website uses the Mathematica engine to provide CAS functionality via the Web.

Many handheld graphing calculators have CAS capabilities, such as the TI-89 and TI-Nspire CX CAS from Texas Instruments. Some tablet and smartphone apps also provide these capabilities, such as the previously mentioned MathStudio.



Diagnostic Tests

Success in calculus depends to a large extent on knowledge of the mathematics that precedes calculus: algebra, analytic geometry, functions, and trigonometry. The following tests are intended to diagnose weaknesses that you might have in these areas. After taking each test you can check your answers against the given answers and, if necessary, refresh your skills by referring to the review materials that are provided.

A Diagnostic Test: Algebra

1. Evaluate each expression without using a calculator.

(a)	$(-3)^4$	(-)	-3^{4}	(c)	3^{-4}
(d)	$\frac{5^{23}}{5^{21}}$	(e)	$\left(\frac{2}{3}\right)^{-2}$	(f)	16 ^{-3/4}

2. Simplify each expression. Write your answer without negative exponents.

(a)
$$\sqrt{200} - \sqrt{32}$$

(b) $(3a^3b^3)(4ab^2)^2$
(c) $\left(\frac{3x^{3/2}y^3}{x^2y^{-1/2}}\right)^{-2}$

3. Expand and simplify.

(a)
$$3(x+6) + 4(2x-5)$$
 (b) $(x+3)(4x-5)$
(c) $(\sqrt{a} + \sqrt{b})(\sqrt{a} - \sqrt{b})$ (d) $(2x+3)^2$
(e) $(x+2)^3$

4. Factor each expression.

(a)
$$4x^2 - 25$$
 (b) $2x^2 + 5x - 12$
(c) $x^3 - 3x^2 - 4x + 12$ (d) $x^4 + 27x$
(e) $3x^{3/2} - 9x^{1/2} + 6x^{-1/2}$ (f) $x^3y - 4xy$

5. Simplify the rational expression.

(a)
$$\frac{x^2 + 3x + 2}{x^2 - x - 2}$$

(b) $\frac{2x^2 - x - 1}{x^2 - 9} \cdot \frac{x + 3}{2x + 1}$
(c) $\frac{x^2}{x^2 - 4} - \frac{x + 1}{x + 2}$
(d) $\frac{\frac{y}{x} - \frac{x}{y}}{\frac{1}{y} - \frac{1}{x}}$

6. Rationalize the expression and simplify.

(a)
$$\frac{\sqrt{10}}{\sqrt{5}-2}$$
 (b) $\frac{\sqrt{4+h}-2}{h}$

7. Rewrite by completing the square. (a) $x^2 + x + 1$ (b) $2x^2 - 12x + 11$

8. Solve the equation. (Find only the real solutions.)

(a) $x + 5 = 14 - \frac{1}{2}x$	(b) $\frac{2x}{x+1} = \frac{2x-1}{x}$
(c) $x^2 - x - 12 = 0$	(d) $2x^2 + 4x + 1 = 0$
(e) $x^4 - 3x^2 + 2 = 0$	(f) $3 x-4 = 10$
(g) $2x(4-x)^{-1/2} - 3\sqrt{4-x} = 0$	

9. Solve each inequality. Write your answer using interval notation.

(a) $-4 < 5 - 3x \le 17$ (b) $x^2 < 2x + 8$ (c) x(x-1)(x+2) > 0(d) |x-4| < 3(e) $\frac{2x-3}{x+1} \le 1$

10. State whether each equation is true or false.

(a) $(p+q)^2 = p^2 + q^2$	(b)	$\sqrt{ab} = \sqrt{a} \sqrt{b}$
(c) $\sqrt{a^2 + b^2} = a + b$	(d)	$\frac{1+TC}{C} = 1+T$
(e) $\frac{1}{x-y} = \frac{1}{x} - \frac{1}{y}$	(f)	$\frac{1/x}{a/x - b/x} = \frac{1}{a - b}$

ANSWERS TO DIAGNOSTIC TEST A: ALGEBRA

1. (a) 81 (d) 25	(b) -81 (e) $\frac{9}{4}$	(c) $\frac{1}{81}$ (f) $\frac{1}{8}$	6. (a) $5\sqrt{2} + 2\sqrt{10}$		(b) $\frac{1}{\sqrt{4+h}+2}$
2. (a) $6\sqrt{2}$	(b) $48a^5b^7$	(c) $\frac{x}{9y^7}$	7. (a) $(x + \frac{1}{2})^2 + \frac{3}{4}$		(b) $2(x-3)^2 - 7$
3. (a) $11x - 2$ (c) $a - b$ (e) $x^3 + 6x^2 + 12x$. ,		8. (a) 6 (d) $-1 \pm \frac{1}{2}\sqrt{2}$ (g) $\frac{12}{5}$	(b) 1 (e) $\pm 1, \pm \sqrt{2}$	
4. (a) $(2x - 5)(2x + 1)(2x - 3)(x - 2)(2x - 3)(x - 2)(2x - 3)(x - 2)(2x - 3)(2x - 3)$	(x + 2)	(b) $(2x - 3)(x + 4)$ (d) $x(x + 3)(x^2 - 3x + 9)$ (f) $xy(x - 2)(x + 2)$	9. (a) $[-4, 3)$ (c) $(-2, 0) \cup (1, 4)$ (e) $(-1, 4]$		(b) (-2, 4) (d) (1, 7)
5. (a) $\frac{x+2}{x-2}$ (c) $\frac{1}{x-2}$		(b) $\frac{x-1}{x-3}$ (d) $-(x+y)$	10. (a) False (d) False	(b) True(e) False	(c) False(f) True

If you had difficulty with these problems, you may wish to consult the Review of Algebra on the website **www.stewartcalculus.com**.

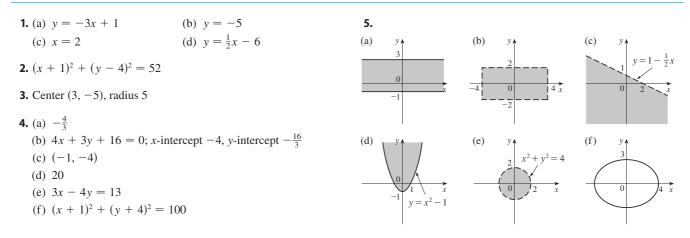
Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it.

B Diagnostic Test: Analytic Geometry

- Find an equation for the line that passes through the point (2, −5) and
 (a) has slope −3
 - (b) is parallel to the *x*-axis
 - (c) is parallel to the *y*-axis
 - (d) is parallel to the line 2x 4y = 3
- **2.** Find an equation for the circle that has center (-1, 4) and passes through the point (3, -2).
- **3.** Find the center and radius of the circle with equation $x^2 + y^2 6x + 10y + 9 = 0$.
- **4.** Let A(-7, 4) and B(5, -12) be points in the plane.
 - (a) Find the slope of the line that contains A and B.
 - (b) Find an equation of the line that passes through A and B. What are the intercepts?
 - (c) Find the midpoint of the segment AB.
 - (d) Find the length of the segment AB.
 - (e) Find an equation of the perpendicular bisector of AB.
 - (f) Find an equation of the circle for which AB is a diameter.
- 5. Sketch the region in the *xy*-plane defined by the equation or inequalities.

(a) $-1 \le y \le 3$	(b) $ x < 4$ and $ y < 2$
(c) $y < 1 - \frac{1}{2}x$	(d) $y \ge x^2 - 1$
(e) $x^2 + y^2 < 4$	(f) $9x^2 + 16y^2 = 144$

ANSWERS TO DIAGNOSTIC TEST B: ANALYTIC GEOMETRY



If you had difficulty with these problems, you may wish to consult the review of analytic geometry in Appendixes B and C.

Diagnostic Test: Functions

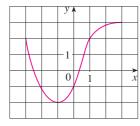


FIGURE FOR PROBLEM 1

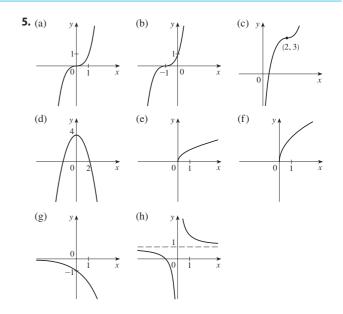
- **1.** The graph of a function f is given at the left.
 - (a) State the value of f(-1).
 - (b) Estimate the value of f(2).
 - (c) For what values of x is f(x) = 2?
 - (d) Estimate the values of x such that f(x) = 0.
 - (e) State the domain and range of f.
- **2.** If $f(x) = x^3$, evaluate the difference quotient $\frac{f(2+h) f(2)}{h}$ and simplify your answer.
- **3.** Find the domain of the function.

(a)
$$f(x) = \frac{2x+1}{x^2+x-2}$$
 (b) $g(x) = \frac{\sqrt[3]{x}}{x^2+1}$ (c) $h(x) = \sqrt{4-x} + \sqrt{x^2-1}$

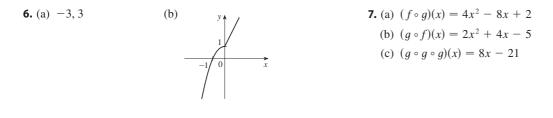
- 4. How are graphs of the functions obtained from the graph of f? (a) y = -f(x) (b) y = 2f(x) - 1 (c) y = f(x - 3) + 2
- 5. Without using a calculator, make a rough sketch of the graph.
- (a) $y = x^3$ (b) $y = (x + 1)^3$ (c) $y = (x 2)^3 + 3$ (d) $y = 4 - x^2$ (e) $y = \sqrt{x}$ (f) $y = 2\sqrt{x}$ (g) $y = -2^x$ (h) $y = 1 + x^{-1}$ 6. Let $f(x) = \begin{cases} 1 - x^2 & \text{if } x \le 0\\ 2x + 1 & \text{if } x > 0\\ (a) \text{ Evaluate } f(-2) \text{ and } f(1).$ (b) Sketch the graph of f.
- 7. If $f(x) = x^2 + 2x 1$ and g(x) = 2x 3, find each of the following functions. (a) $f \circ g$ (b) $g \circ f$ (c) $g \circ g \circ g$

ANSWERS TO DIAGNOSTIC TEST C: FUNCTIONS

- **1.** (a) -2 (b) 2.8 (c) -3, 1 (d) -2.5, 0.3(e) [-3, 3], [-2, 3]
- **2.** $12 + 6h + h^2$
- **3.** (a) $(-\infty, -2) \cup (-2, 1) \cup (1, \infty)$ (b) $(-\infty, \infty)$
 - (c) $(-\infty, -1] \cup [1, 4]$
- **4.** (a) Reflect about the *x*-axis
 - (b) Stretch vertically by a factor of 2, then shift 1 unit downward
 - (c) Shift 3 units to the right and 2 units upward



Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it



If you had difficulty with these problems, you should look at sections 1.1–1.3 of this book.

Diagnostic Test: Trigonometry

- **1.** Convert from degrees to radians. (a) 300° (b) -18°
- **2.** Convert from radians to degrees. (a) $5\pi/6$ (b) 2
- **3.** Find the length of an arc of a circle with radius 12 cm if the arc subtends a central angle of 30°.
- **4.** Find the exact values. (a) $\tan(\pi/3)$ (b) $\sin(7\pi/6)$ (c) $\sec(5\pi/3)$
- **5.** Express the lengths *a* and *b* in the figure in terms of θ .
- 6. If $\sin x = \frac{1}{3}$ and $\sec y = \frac{5}{4}$, where x and y lie between 0 and $\pi/2$, evaluate $\sin(x + y)$.
- 7. Prove the identities.

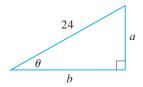
(a)
$$\tan\theta\sin\theta + \cos\theta = \sec\theta$$
 (b) $\frac{2\tan x}{1 + \tan^2 x} = \sin 2x$

- **8.** Find all values of x such that $\sin 2x = \sin x$ and $0 \le x \le 2\pi$.
- **9.** Sketch the graph of the function $y = 1 + \sin 2x$ without using a calculator.

ANSWERS TO DIAGNOSTIC TEST D: TRIGONOMETRY

1. (a) $5\pi/3$	(b) $-\pi/10$	6. $\frac{1}{15} (4 + 6\sqrt{2})$
2. (a) 150°	(b) $360^{\circ}/\pi \approx 114.6^{\circ}$	8. 0, $\pi/3$, π , $5\pi/3$, 2π
3. 2π cm		9. ^y ↑
4. (a) $\sqrt{3}$	(b) $-\frac{1}{2}$ (c) 2	
5. (a) $24 \sin \theta$	(b) $24\cos\theta$	$-\pi$ 0 π x

If you had difficulty with these problems, you should look at Appendix D of this book.





A Preview of Calculus

By the time you finish this course, you will be able to calculate the length of the curve used to design the Gateway Arch in St. Louis, determine where a pilot should start descent for a smooth landing, compute the force on a baseball bat when it strikes the ball, and measure the amount of light sensed by the human eye as the pupil changes size.



CALCULUS IS FUNDAMENTALLY DIFFERENT FROM the mathematics that you have studied previously: calculus is less static and more dynamic. It is concerned with change and motion; it deals with quantities that approach other quantities. For that reason it may be useful to have an overview of the subject before beginning its intensive study. Here we give a glimpse of some of the main ideas of calculus by showing how the concept of a limit arises when we attempt to solve a variety of problems.

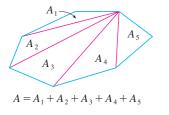
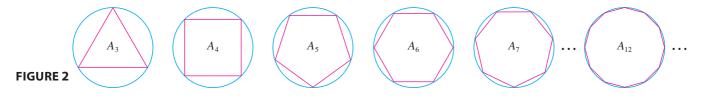


FIGURE 1

The Area Problem

The origins of calculus go back at least 2500 years to the ancient Greeks, who found areas using the "method of exhaustion." They knew how to find the area *A* of any polygon by dividing it into triangles as in Figure 1 and adding the areas of these triangles.

It is a much more difficult problem to find the area of a curved figure. The Greek method of exhaustion was to inscribe polygons in the figure and circumscribe polygons about the figure and then let the number of sides of the polygons increase. Figure 2 illustrates this process for the special case of a circle with inscribed regular polygons.



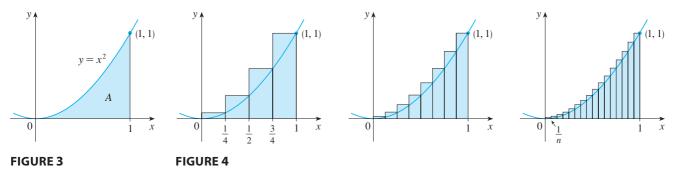
Let A_n be the area of the inscribed polygon with *n* sides. As *n* increases, it appears that A_n becomes closer and closer to the area of the circle. We say that the area of the circle is the limit of the areas of the inscribed polygons, and we write

TEC In the Preview Visual, you can see how areas of inscribed and circumscribed polygons approximate the area of a circle.

$$A = \lim_{n \to \infty} A_n$$

The Greeks themselves did not use limits explicitly. However, by indirect reasoning, Eudoxus (fifth century BC) used exhaustion to prove the familiar formula for the area of a circle: $A = \pi r^2$.

We will use a similar idea in Chapter 5 to find areas of regions of the type shown in Figure 3. We will approximate the desired area *A* by areas of rectangles (as in Figure 4), let the width of the rectangles decrease, and then calculate *A* as the limit of these sums of areas of rectangles.



The area problem is the central problem in the branch of calculus called *integral calculus*. The techniques that we will develop in Chapter 5 for finding areas will also enable us to compute the volume of a solid, the length of a curve, the force of water against a dam, the mass and center of gravity of a rod, and the work done in pumping water out of a tank.

The Tangent Problem

Consider the problem of trying to find an equation of the tangent line *t* to a curve with equation y = f(x) at a given point *P*. (We will give a precise definition of a tangent line in



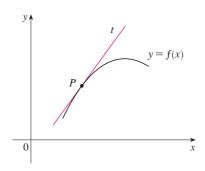


FIGURE 5 The tangent line at *P*

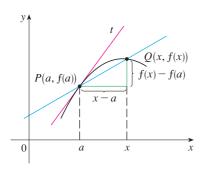


FIGURE 6 The secant line at *PQ*

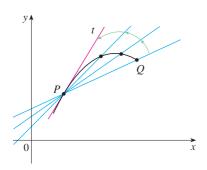


FIGURE 7 Secant lines approaching the tangent line

Chapter 2. For now you can think of it as a line that touches the curve at *P* as in Figure 5.) Since we know that the point *P* lies on the tangent line, we can find the equation of *t* if we know its slope *m*. The problem is that we need two points to compute the slope and we know only one point, *P*, on *t*. To get around the problem we first find an approximation to *m* by taking a nearby point *Q* on the curve and computing the slope m_{PQ} of the secant line *PQ*. From Figure 6 we see that

$$m_{PQ} = \frac{f(x) - f(a)}{x - a}$$

Now imagine that Q moves along the curve toward P as in Figure 7. You can see that the secant line rotates and approaches the tangent line as its limiting position. This means that the slope m_{PQ} of the secant line becomes closer and closer to the slope m of the tangent line. We write

$$m = \lim_{Q \to P} m_{PQ}$$

and we say that *m* is the limit of m_{PQ} as *Q* approaches *P* along the curve. Because *x* approaches *a* as *Q* approaches *P*, we could also use Equation 1 to write

$$m = \lim_{x \to a} \frac{f(x) - f(a)}{x - a}$$

Specific examples of this procedure will be given in Chapter 2.

The tangent problem has given rise to the branch of calculus called *differential calculus*, which was not invented until more than 2000 years after integral calculus. The main ideas behind differential calculus are due to the French mathematician Pierre Fermat (1601–1665) and were developed by the English mathematicians John Wallis (1616–1703), Isaac Barrow (1630–1677), and Isaac Newton (1642–1727) and the German mathematician Gottfried Leibniz (1646–1716).

The two branches of calculus and their chief problems, the area problem and the tangent problem, appear to be very different, but it turns out that there is a very close connection between them. The tangent problem and the area problem are inverse problems in a sense that will be described in Chapter 5.

Velocity

2

When we look at the speedometer of a car and read that the car is traveling at 48 mi/h, what does that information indicate to us? We know that if the velocity remains constant, then after an hour we will have traveled 48 mi. But if the velocity of the car varies, what does it mean to say that the velocity at a given instant is 48 mi/h?

In order to analyze this question, let's examine the motion of a car that travels along a straight road and assume that we can measure the distance traveled by the car (in feet) at 1-second intervals as in the following chart:

t = Time elapsed (s)	0	1	2	3	4	5
d = Distance (ft)	0	2	9	24	42	71

As a first step toward finding the velocity after 2 seconds have elapsed, we find the average velocity during the time interval $2 \le t \le 4$:

average velocity =
$$\frac{\text{change in position}}{\text{time elapsed}}$$

= $\frac{42 - 9}{4 - 2}$
= 16.5 ft/s

Similarly, the average velocity in the time interval $2 \le t \le 3$ is

average velocity
$$=$$
 $\frac{24 - 9}{3 - 2} = 15$ ft/s

We have the feeling that the velocity at the instant t = 2 can't be much different from the average velocity during a short time interval starting at t = 2. So let's imagine that the distance traveled has been measured at 0.1-second time intervals as in the following chart:

t	2.0	2.1	2.2	2.3	2.4	2.5
d	9.00	10.02	11.16	12.45	13.96	15.80

Then we can compute, for instance, the average velocity over the time interval [2, 2.5]:

average velocity
$$=$$
 $\frac{15.80 - 9.00}{2.5 - 2} = 13.6 \text{ ft/s}$

The results of such calculations are shown in the following chart:

Time interval	[2, 3]	[2, 2.5]	[2, 2.4]	[2, 2.3]	[2, 2.2]	[2, 2.1]
Average velocity (ft/s)	15.0	13.6	12.4	11.5	10.8	10.2

The average velocities over successively smaller intervals appear to be getting closer to a number near 10, and so we expect that the velocity at exactly t = 2 is about 10 ft/s. In Chapter 2 we will define the instantaneous velocity of a moving object as the limiting value of the average velocities over smaller and smaller time intervals.

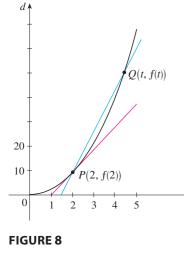
In Figure 8 we show a graphical representation of the motion of the car by plotting the distance traveled as a function of time. If we write d = f(t), then f(t) is the number of feet traveled after t seconds. The average velocity in the time interval [2, t] is

average velocity =
$$\frac{\text{change in position}}{\text{time elapsed}} = \frac{f(t) - f(2)}{t - 2}$$

which is the same as the slope of the secant line PQ in Figure 8. The velocity v when t = 2 is the limiting value of this average velocity as t approaches 2; that is,

$$v = \lim_{t \to 2} \frac{f(t) - f(2)}{t - 2}$$

and we recognize from Equation 2 that this is the same as the slope of the tangent line to the curve at P.



Thus, when we solve the tangent problem in differential calculus, we are also solving problems concerning velocities. The same techniques also enable us to solve problems involving rates of change in all of the natural and social sciences.

The Limit of a Sequence

In the fifth century BC the Greek philosopher Zeno of Elea posed four problems, now known as Zeno's paradoxes, that were intended to challenge some of the ideas concerning space and time that were held in his day. Zeno's second paradox concerns a race between the Greek hero Achilles and a tortoise that has been given a head start. Zeno argued, as follows, that Achilles could never pass the tortoise: Suppose that Achilles starts at position a_1 and the tortoise starts at position t_1 . (See Figure 9.) When Achilles reaches the point $a_2 = t_1$, the tortoise is farther ahead at position t_2 . When Achilles reaches $a_3 = t_2$, the torto is at t_3 . This process continues indefinitely and so it appears that the torto is will always be ahead! But this defies common sense.



One way of explaining this paradox is with the idea of a *sequence*. The successive positions of Achilles (a_1, a_2, a_3, \ldots) or the successive positions of the tortoise (t_1, t_2, t_3, \ldots) form what is known as a sequence.

In general, a sequence $\{a_n\}$ is a set of numbers written in a definite order. For instance, the sequence

$$\left\{1, \frac{1}{2}, \frac{1}{3}, \frac{1}{4}, \frac{1}{5}, \ldots\right\}$$

can be described by giving the following formula for the *n*th term:

$$a_n = \frac{1}{n}$$

 $a_1 a_3$ a a_1 0 1 (a) 23 56 7 (b) FIGURE 10

We can visualize this sequence by plotting its terms on a number line as in Figure 10(a) or by drawing its graph as in Figure 10(b). Observe from either picture that the terms of the sequence $a_n = 1/n$ are becoming closer and closer to 0 as n increases. In fact, we can find terms as small as we please by making *n* large enough. We say that the limit of the sequence is 0, and we indicate this by writing

$$\lim_{n \to \infty} \frac{1}{n} = 0$$

In general, the notation

 $\lim_{n\to\infty}a_n=L$

is used if the terms a_n approach the number L as n becomes large. This means that the numbers a_n can be made as close as we like to the number L by taking n sufficiently large.

5

The concept of the limit of a sequence occurs whenever we use the decimal representation of a real number. For instance, if

$a_1 = 3.1$
$a_2 = 3.14$
$a_3 = 3.141$
$a_4 = 3.1415$
$a_5 = 3.14159$
$a_6 = 3.141592$
$a_7 = 3.1415926$
• • •
$\lim_{n\to\infty} a_n = \pi$

The terms in this sequence are rational approximations to π .

Let's return to Zeno's paradox. The successive positions of Achilles and the tortoise form sequences $\{a_n\}$ and $\{t_n\}$, where $a_n < t_n$ for all n. It can be shown that both sequences have the same limit:

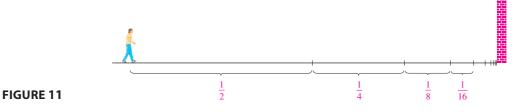
$$\lim_{n\to\infty}a_n=p=\lim_{n\to\infty}t_n$$

It is precisely at this point *p* that Achilles overtakes the tortoise.

The Sum of a Series

then

Another of Zeno's paradoxes, as passed on to us by Aristotle, is the following: "A man standing in a room cannot walk to the wall. In order to do so, he would first have to go half the distance, then half the remaining distance, and then again half of what still remains. This process can always be continued and can never be ended." (See Figure 11.)



Of course, we know that the man can actually reach the wall, so this suggests that perhaps the total distance can be expressed as the sum of infinitely many smaller distances as follows:

3 $1 = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \frac{1}{16} + \dots + \frac{1}{2^n} + \dots$

A PREVIEW OF CALCULUS 7

Zeno was arguing that it doesn't make sense to add infinitely many numbers together. But there are other situations in which we implicitly use infinite sums. For instance, in decimal notation, the symbol $0.\overline{3} = 0.3333...$ means

$$\frac{3}{10} + \frac{3}{100} + \frac{3}{1000} + \frac{3}{10,000} + \dots$$

and so, in some sense, it must be true that

$$\frac{3}{10} + \frac{3}{100} + \frac{3}{1000} + \frac{3}{10,000} + \dots = \frac{1}{3}$$

More generally, if d_n denotes the *n*th digit in the decimal representation of a number, then

$$0.d_1d_2d_3d_4\ldots = \frac{d_1}{10} + \frac{d_2}{10^2} + \frac{d_3}{10^3} + \ldots + \frac{d_n}{10^n} + \ldots$$

Therefore some infinite sums, or infinite series as they are called, have a meaning. But we must define carefully what the sum of an infinite series is.

Returning to the series in Equation 3, we denote by s_n the sum of the first *n* terms of the series. Thus

$$s_{1} = \frac{1}{2} = 0.5$$

$$s_{2} = \frac{1}{2} + \frac{1}{4} = 0.75$$

$$s_{3} = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} = 0.875$$

$$s_{4} = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \frac{1}{16} = 0.9375$$

$$s_{5} = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \frac{1}{16} + \frac{1}{32} = 0.96875$$

$$s_{6} = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \frac{1}{16} + \frac{1}{32} + \frac{1}{64} = 0.984375$$

$$s_{7} = \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \frac{1}{16} + \frac{1}{32} + \frac{1}{64} + \frac{1}{128} = 0.9921875$$

$$\vdots$$

$$s_{10} = \frac{1}{2} + \frac{1}{4} + \cdots + \frac{1}{1024} \approx 0.99902344$$

$$\vdots$$

$$s_{16} = \frac{1}{2} + \frac{1}{4} + \cdots + \frac{1}{2^{16}} \approx 0.99998474$$

Observe that as we add more and more terms, the partial sums become closer and closer to 1. In fact, it can be shown that by taking *n* large enough (that is, by adding sufficiently many terms of the series), we can make the partial sum s_n as close as we please to the number 1. It therefore seems reasonable to say that the sum of the infinite series is 1 and to write

$$\frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots + \frac{1}{2^n} + \dots = 1$$

8

In other words, the reason the sum of the series is 1 is that

 $\lim s_n = 1$

In Chapter 11 we will discuss these ideas further. We will then use Newton's idea of combining infinite series with differential and integral calculus.

Summary

We have seen that the concept of a limit arises in trying to find the area of a region, the slope of a tangent to a curve, the velocity of a car, or the sum of an infinite series. In each case the common theme is the calculation of a quantity as the limit of other, easily calculated quantities. It is this basic idea of a limit that sets calculus apart from other areas of mathematics. In fact, we could define calculus as the part of mathematics that deals with limits.

After Sir Isaac Newton invented his version of calculus, he used it to explain the motion of the planets around the sun. Today calculus is used in calculating the orbits of satellites and spacecraft, in predicting population sizes, in estimating how fast oil prices rise or fall, in forecasting weather, in measuring the cardiac output of the heart, in calculating life insurance premiums, and in a great variety of other areas. We will explore some of these uses of calculus in this book.

In order to convey a sense of the power of the subject, we end this preview with a list of some of the questions that you will be able to answer using calculus:

- **1.** How can we explain the fact, illustrated in Figure 12, that the angle of elevation from an observer up to the highest point in a rainbow is 42°? (See page 285.)
- 2. How can we explain the shapes of cans on supermarket shelves? (See page 343.)
- **3.** Where is the best place to sit in a movie theater? (See page 465.)
- 4. How can we design a roller coaster for a smooth ride? (See page 182.)
- 5. How far away from an airport should a pilot start descent? (See page 208.)
- **6.** How can we fit curves together to design shapes to represent letters on a laser printer? (See page 657.)
- **7.** How can we estimate the number of workers that were needed to build the Great Pyramid of Khufu in ancient Egypt? (See page 460.)
- **8.** Where should an infielder position himself to catch a baseball thrown by an outfielder and relay it to home plate? (See page 465.)
- **9.** Does a ball thrown upward take longer to reach its maximum height or to fall back to its original height? (See page 609.)
- **10.** How can we explain the fact that planets and satellites move in elliptical orbits? (See page 868.)
- **11.** How can we distribute water flow among turbines at a hydroelectric station so as to maximize the total energy production? (See page 980.)
- **12.** If a marble, a squash ball, a steel bar, and a lead pipe roll down a slope, which of them reaches the bottom first? (See page 1052.)

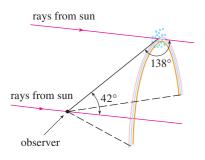
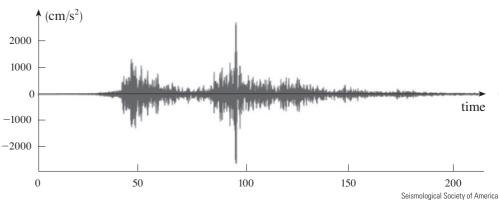


FIGURE 12

Functions and Models





THE FUNDAMENTAL OBJECTS THAT WE deal with in calculus are functions. This chapter prepares the way for calculus by discussing the basic ideas concerning functions, their graphs, and ways of transforming and combining them. We stress that a function can be represented in different ways: by an equation, in a table, by a graph, or in words. We look at the main types of functions that occur in calculus and describe the process of using these functions as mathematical models of real-world phenomena.

Often a graph is the best way to represent a function because it conveys so much information at a glance. Shown is a graph of the vertical ground acceleration created by the 2011 earthquake near Tohoku, Japan. The earthquake had a magnitude of 9.0 on the Richter scale and was so powerful that it moved northern Japan 8 feet closer to North America. Population

(millions)

1650

1750

1860

2070

2300

2560

3040

3710

4450

5280

6080

6870

Year

1900

1910

1920

1930

1940

1950

1960

1970

1980

1990

2000

2010

1.1 Four Ways to Represent a Function

Functions arise whenever one quantity depends on another. Consider the following four situations.

- A. The area A of a circle depends on the radius r of the circle. The rule that connects r and A is given by the equation $A = \pi r^2$. With each positive number r there is associated one value of A, and we say that A is a *function* of r.
- **B.** The human population of the world P depends on the time t. The table gives estimates of the world population P(t) at time t, for certain years. For instance,

$$P(1950) \approx 2,560,000,000$$

But for each value of the time t there is a corresponding value of P, and we say that P is a function of t.

- C. The cost C of mailing an envelope depends on its weight w. Although there is no simple formula that connects w and C, the post office has a rule for determining C when w is known.
- **D.** The vertical acceleration *a* of the ground as measured by a seismograph during an earthquake is a function of the elapsed time *t*. Figure 1 shows a graph generated by seismic activity during the Northridge earthquake that shook Los Angeles in 1994. For a given value of *t*, the graph provides a corresponding value of *a*.

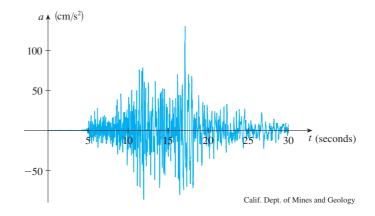


FIGURE 1 Vertical ground acceleration during the Northridge earthquake

Each of these examples describes a rule whereby, given a number (r, t, w, or t), another number (A, P, C, or a) is assigned. In each case we say that the second number is a function of the first number.

A **function** f is a rule that assigns to each element x in a set D exactly one element, called f(x), in a set E.

We usually consider functions for which the sets D and E are sets of real numbers. The set D is called the **domain** of the function. The number f(x) is the **value of** f at x and is read "f of x." The **range** of f is the set of all possible values of f(x) as x varies throughout the domain. A symbol that represents an arbitrary number in the *domain* of a function f is called an **independent variable**. A symbol that represents a number in the *range* of f is called a **dependent variable**. In Example A, for instance, r is the independent variable.

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it

11



FIGURE 2 Machine diagram for a function f

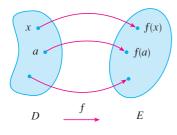


FIGURE 3 Arrow diagram for f

It's helpful to think of a function as a **machine** (see Figure 2). If x is in the domain of the function f, then when x enters the machine, it's accepted as an input and the machine produces an output f(x) according to the rule of the function. Thus we can think of the domain as the set of all possible inputs and the range as the set of all possible outputs.

The preprogrammed functions in a calculator are good examples of a function as a machine. For example, the square root key on your calculator computes such a function. You press the key labeled $\sqrt{(or \sqrt{x})}$ and enter the input x. If x < 0, then x is not in the domain of this function; that is, x is not an acceptable input, and the calculator will indicate an error. If $x \ge 0$, then an *approximation* to \sqrt{x} will appear in the display. Thus the \sqrt{x} key on your calculator is not quite the same as the exact mathematical function f defined by $f(x) = \sqrt{x}$.

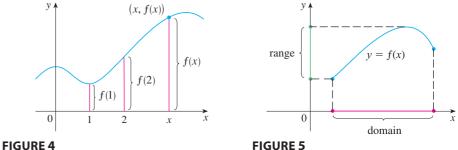
Another way to picture a function is by an arrow diagram as in Figure 3. Each arrow connects an element of D to an element of E. The arrow indicates that f(x) is associated with x, f(a) is associated with a, and so on.

The most common method for visualizing a function is its graph. If f is a function with domain D, then its graph is the set of ordered pairs

$$\{(x, f(x)) \mid x \in D\}$$

(Notice that these are input-output pairs.) In other words, the graph of f consists of all points (x, y) in the coordinate plane such that y = f(x) and x is in the domain of f.

The graph of a function f gives us a useful picture of the behavior or "life history" of a function. Since the y-coordinate of any point (x, y) on the graph is y = f(x), we can read the value of f(x) from the graph as being the height of the graph above the point x (see Figure 4). The graph of f also allows us to picture the domain of f on the x-axis and its range on the y-axis as in Figure 5.



EXAMPLE 1 The graph of a function *f* is shown in Figure 6.

(a) Find the values of f(1) and f(5).

(b) What are the domain and range of f?

SOLUTION

(a) We see from Figure 6 that the point (1, 3) lies on the graph of f, so the value of f at 1 is f(1) = 3. (In other words, the point on the graph that lies above x = 1 is 3 units above the x-axis.)

When x = 5, the graph lies about 0.7 units below the x-axis, so we estimate that $f(5) \approx -0.7.$

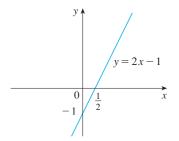
(b) We see that f(x) is defined when $0 \le x \le 7$, so the domain of f is the closed interval [0, 7]. Notice that f takes on all values from -2 to 4, so the range of f is

$$[y \mid -2 \le y \le 4] = [-2, 4]$$

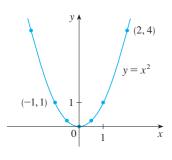
0 1

FIGURE 6

The notation for intervals is given in Appendix A.









EXAMPLE 2 Sketch the graph and find the domain and range of each function. (a) f(x) = 2x - 1 (b) $g(x) = x^2$

SOLUTION

(a) The equation of the graph is y = 2x - 1, and we recognize this as being the equation of a line with slope 2 and y-intercept -1. (Recall the slope-intercept form of the equation of a line: y = mx + b. See Appendix B.) This enables us to sketch a portion of the graph of f in Figure 7. The expression 2x - 1 is defined for all real numbers, so the domain of f is the set of all real numbers, which we denote by \mathbb{R} . The graph shows that the range is also \mathbb{R} .

(b) Since $g(2) = 2^2 = 4$ and $g(-1) = (-1)^2 = 1$, we could plot the points (2, 4) and (-1, 1), together with a few other points on the graph, and join them to produce the graph (Figure 8). The equation of the graph is $y = x^2$, which represents a parabola (see Appendix C). The domain of g is \mathbb{R} . The range of g consists of all values of g(x), that is, all numbers of the form x^2 . But $x^2 \ge 0$ for all numbers x and any positive number y is a square. So the range of g is $\{y \mid y \ge 0\} = [0, \infty)$. This can also be seen from Figure 8.

EXAMPLE 3 If
$$f(x) = 2x^2 - 5x + 1$$
 and $h \neq 0$, evaluate $\frac{f(a+h) - f(a)}{h}$

SOLUTION We first evaluate f(a + h) by replacing x by a + h in the expression for f(x):

$$f(a + h) = 2(a + h)^{2} - 5(a + h) + 1$$
$$= 2(a^{2} + 2ah + h^{2}) - 5(a + h) + 1$$
$$= 2a^{2} + 4ah + 2h^{2} - 5a - 5h + 1$$

Then we substitute into the given expression and simplify:

$$\frac{f(a+h) - f(a)}{h} = \frac{(2a^2 + 4ah + 2h^2 - 5a - 5h + 1) - (2a^2 - 5a + 1)}{h}$$
$$= \frac{2a^2 + 4ah + 2h^2 - 5a - 5h + 1 - 2a^2 + 5a - 1}{h}$$
$$= \frac{4ah + 2h^2 - 5h}{h} = 4a + 2h - 5$$

Representations of Functions

There are four possible ways to represent a function:

- verbally (by a description in words)
- numerically (by a table of values)
- visually (by a graph)
- algebraically (by an explicit formula)

If a single function can be represented in all four ways, it's often useful to go from one representation to another to gain additional insight into the function. (In Example 2, for instance, we started with algebraic formulas and then obtained the graphs.) But certain functions are described more naturally by one method than by another. With this in mind, let's reexamine the four situations that we considered at the beginning of this section.

The expression

$$\frac{f(a+h) - f(a)}{h}$$

in Example 3 is called a **difference quotient** and occurs frequently in calculus. As we will see in Chapter 2, it represents the average rate of change of f(x) between x = a and x = a + h.

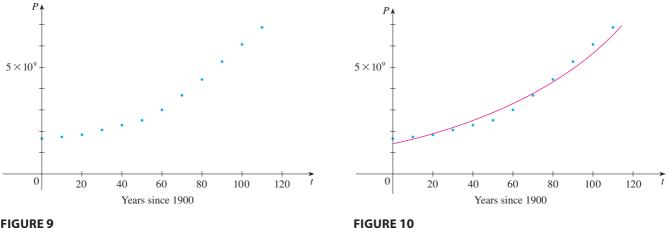
t (years since 1900)	Population (millions)
0	1650
10	1750
20	1860
30	2070
40	2300
50	2560
60	3040
70	3710
80	4450
90	5280
100	6080
110	6870

13

- **A.** The most useful representation of the area of a circle as a function of its radius is probably the algebraic formula $A(r) = \pi r^2$, though it is possible to compile a table of values or to sketch a graph (half a parabola). Because a circle has to have a positive radius, the domain is $\{r \mid r > 0\} = (0, \infty)$, and the range is also $(0, \infty)$.
- **B.** We are given a description of the function in words: P(t) is the human population of the world at time t. Let's measure t so that t = 0 corresponds to the year 1900. The table of values of world population provides a convenient representation of this function. If we plot these values, we get the graph (called a *scatter plot*) in Figure 9. It too is a useful representation; the graph allows us to absorb all the data at once. What about a formula? Of course, it's impossible to devise an explicit formula that gives the exact human population P(t) at any time t. But it is possible to find an expression for a function that *approximates* P(t). In fact, using methods explained in Section 1.2, we obtain the approximation

$$P(t) \approx f(t) = (1.43653 \times 10^9) \cdot (1.01395)^t$$

Figure 10 shows that it is a reasonably good "fit." The function f is called a mathe*matical model* for population growth. In other words, it is a function with an explicit formula that approximates the behavior of our given function. We will see, however, that the ideas of calculus can be applied to a table of values; an explicit formula is not necessary.





A function defined by a table of values is called a tabular function.

w (ounces)	C(w) (dollars)
$0 < w \le 1$	0.98
$1 < w \leq 2$	1.19
$2 < w \leq 3$	1.40
$3 < w \leq 4$	1.61
$4 < w \leq 5$	1.82
•	•

The function P is typical of the functions that arise whenever we attempt to apply calculus to the real world. We start with a verbal description of a function. Then we may be able to construct a table of values of the function, perhaps from instrument readings in a scientific experiment. Even though we don't have complete knowledge of the values of the function, we will see throughout the book that it is still possible to perform the operations of calculus on such a function.

- C. Again the function is described in words: Let C(w) be the cost of mailing a large envelope with weight w. The rule that the US Postal Service used as of 2015 is as follows: The cost is 98 cents for up to 1 oz, plus 21 cents for each additional ounce (or less) up to 13 oz. The table of values shown in the margin is the most convenient representation for this function, though it is possible to sketch a graph (see Example 10).
- **D.** The graph shown in Figure 1 is the most natural representation of the vertical acceleration function a(t). It's true that a table of values could be compiled, and it is even possible to devise an approximate formula. But everything a geologist needs to

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it know—amplitudes and patterns—can be seen easily from the graph. (The same is true for the patterns seen in electrocardiograms of heart patients and polygraphs for lie-detection.)

In the next example we sketch the graph of a function that is defined verbally.

EXAMPLE 4 When you turn on a hot-water faucet, the temperature T of the water depends on how long the water has been running. Draw a rough graph of T as a function of the time t that has elapsed since the faucet was turned on.

SOLUTION The initial temperature of the running water is close to room temperature because the water has been sitting in the pipes. When the water from the hot-water tank starts flowing from the faucet, T increases quickly. In the next phase, T is constant at the temperature of the heated water in the tank. When the tank is drained, T decreases to the temperature of the water supply. This enables us to make the rough sketch of T as a function of t in Figure 11.

In the following example we start with a verbal description of a function in a physical situation and obtain an explicit algebraic formula. The ability to do this is a useful skill in solving calculus problems that ask for the maximum or minimum values of quantities.

EXAMPLE 5 A rectangular storage container with an open top has a volume of 10 m³. The length of its base is twice its width. Material for the base costs \$10 per square meter; material for the sides costs \$6 per square meter. Express the cost of materials as a function of the width of the base.

SOLUTION We draw a diagram as in Figure 12 and introduce notation by letting w and 2w be the width and length of the base, respectively, and h be the height.

The area of the base is $(2w)w = 2w^2$, so the cost, in dollars, of the material for the base is $10(2w^2)$. Two of the sides have area *wh* and the other two have area 2wh, so the cost of the material for the sides is 6[2(wh) + 2(2wh)]. The total cost is therefore

$$C = 10(2w^2) + 6[2(wh) + 2(2wh)] = 20w^2 + 36wh$$

To express *C* as a function of *w* alone, we need to eliminate *h* and we do so by using the fact that the volume is 10 m^3 . Thus

w(2w)h = 10

 $h = \frac{10}{2w^2} = \frac{5}{w^2}$

which gives

Substituting this into the expression for C, we have

$$C = 20w^2 + 36w\left(\frac{5}{w^2}\right) = 20w^2 + \frac{180}{w}$$

100

Therefore the equation

$$C(w) = 20w^2 + \frac{180}{w} \qquad w > 0$$

expresses C as a function of w.

EXAMPLE 6 Find the domain of each function.

(a)
$$f(x) = \sqrt{x+2}$$
 (b) $g(x) = \frac{1}{x^2 - x}$

In setting up applied functions as in Example 5, it may be useful to review the principles of problem solving as discussed on page 71, particularly *Step 1: Understand the Problem.*

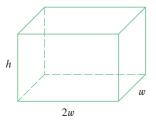
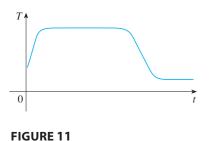
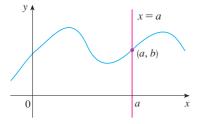


FIGURE 12

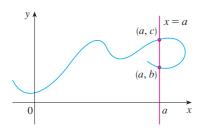


Domain Convention

If a function is given by a formula and the domain is not stated explicitly, the convention is that the domain is the set of all numbers for which the formula makes sense and defines a real number.



(a) This curve represents a function.



(b) This curve doesn't represent a function.



SOLUTION

(a) Because the square root of a negative number is not defined (as a real number), the domain of *f* consists of all values of *x* such that $x + 2 \ge 0$. This is equivalent to $x \ge -2$, so the domain is the interval $[-2, \infty)$.

(b) Since

$$g(x) = \frac{1}{x^2 - x} = \frac{1}{x(x - 1)}$$

and division by 0 is not allowed, we see that g(x) is not defined when x = 0 or x = 1. Thus the domain of g is

$$\{x \mid x \neq 0, x \neq 1\}$$

which could also be written in interval notation as

$$(-\infty, 0) \cup (0, 1) \cup (1, \infty)$$

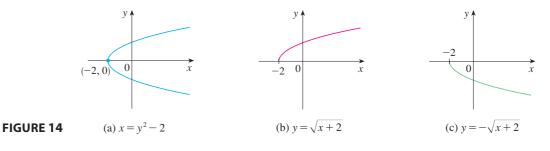
The graph of a function is a curve in the *xy*-plane. But the question arises: Which curves in the *xy*-plane are graphs of functions? This is answered by the following test.

The Vertical Line Test A curve in the *xy*-plane is the graph of a function of *x* if and only if no vertical line intersects the curve more than once.

The reason for the truth of the Vertical Line Test can be seen in Figure 13. If each vertical line x = a intersects a curve only once, at (a, b), then exactly one function value is defined by f(a) = b. But if a line x = a intersects the curve twice, at (a, b) and (a, c), then the curve can't represent a function because a function can't assign two different values to a.

For example, the parabola $x = y^2 - 2$ shown in Figure 14(a) is not the graph of a function of x because, as you can see, there are vertical lines that intersect the parabola twice. The parabola, however, does contain the graphs of *two* functions of x. Notice that the equation $x = y^2 - 2$ implies $y^2 = x + 2$, so $y = \pm \sqrt{x + 2}$. Thus the upper and lower halves of the parabola are the graphs of the functions $f(x) = \sqrt{x + 2}$ [from Example 6(a)] and $g(x) = -\sqrt{x + 2}$. [See Figures 14(b) and (c).]

We observe that if we reverse the roles of x and y, then the equation $x = h(y) = y^2 - 2$ does define x as a function of y (with y as the independent variable and x as the dependent variable) and the parabola now appears as the graph of the function h.



Piecewise Defined Functions

The functions in the following four examples are defined by different formulas in different parts of their domains. Such functions are called **piecewise defined functions**.

15

EXAMPLE 7 A function *f* is defined by

$$f(x) = \begin{cases} 1 - x & \text{if } x \le -1 \\ x^2 & \text{if } x > -1 \end{cases}$$

Evaluate f(-2), f(-1), and f(0) and sketch the graph.

SOLUTION Remember that a function is a rule. For this particular function the rule is the following: First look at the value of the input *x*. If it happens that $x \le -1$, then the value of f(x) is 1 - x. On the other hand, if x > -1, then the value of f(x) is x^2 .

```
Since -2 \le -1, we have f(-2) = 1 - (-2) = 3.
Since -1 \le -1, we have f(-1) = 1 - (-1) = 2.
Since 0 > -1, we have f(0) = 0^2 = 0.
```

How do we draw the graph of f? We observe that if $x \le -1$, then f(x) = 1 - x, so the part of the graph of f that lies to the left of the vertical line x = -1 must coincide with the line y = 1 - x, which has slope -1 and y-intercept 1. If x > -1, then $f(x) = x^2$, so the part of the graph of f that lies to the right of the line x = -1 must coincide with the graph of $y = x^2$, which is a parabola. This enables us to sketch the graph in Figure 15. The solid dot indicates that the point (-1, 2) is included on the graph; the open dot indicates that the point (-1, 1) is excluded from the graph.

The next example of a piecewise defined function is the absolute value function. Recall that the **absolute value** of a number *a*, denoted by |a|, is the distance from *a* to 0 on the real number line. Distances are always positive or 0, so we have

$$|a| \ge 0$$
 for every number a

For example,

$$|3| = 3$$
 $|-3| = 3$ $|0| = 0$ $|\sqrt{2} - 1| = \sqrt{2} - 1$ $|3 - \pi| = \pi - 3$

In general, we have

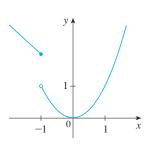
$$|a| = a$$
 if $a \ge 0$
 $|a| = -a$ if $a < 0$

(Remember that if *a* is negative, then -a is positive.)

EXAMPLE 8 Sketch the graph of the absolute value function f(x) = |x|. SOLUTION From the preceding discussion we know that

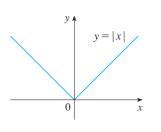
$$|x| = \begin{cases} x & \text{if } x \ge 0\\ -x & \text{if } x < 0 \end{cases}$$

Using the same method as in Example 7, we see that the graph of f coincides with the line y = x to the right of the y-axis and coincides with the line y = -x to the left of the y-axis (see Figure 16).

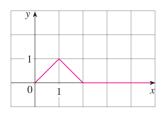




For a more extensive review of absolute values, see Appendix A.









Point-slope form of the equation of a line:

 $y - y_1 = m(x - x_1)$

See Appendix B.

17

EXAMPLE 9 Find a formula for the function *f* graphed in Figure 17.

SOLUTION The line through (0, 0) and (1, 1) has slope m = 1 and y-intercept b = 0, so its equation is y = x. Thus, for the part of the graph of f that joins (0, 0) to (1, 1), we have

$$f(x) = x$$
 if $0 \le x \le 1$

The line through (1, 1) and (2, 0) has slope m = -1, so its point-slope form is

$$y - 0 = (-1)(x - 2)$$
 or $y = 2 - x$

So we have

f(x) = 2 - x if $1 < x \le 2$

We also see that the graph of f coincides with the *x*-axis for x > 2. Putting this information together, we have the following three-piece formula for f:

$$f(x) = \begin{cases} x & \text{if } 0 \le x \le 1\\ 2 - x & \text{if } 1 < x \le 2\\ 0 & \text{if } x > 2 \end{cases}$$

EXAMPLE 10 In Example C at the beginning of this section we considered the cost C(w) of mailing a large envelope with weight w. In effect, this is a piecewise defined function because, from the table of values on page 13, we have

$$C(w) = \begin{cases} 0.98 & \text{if } 0 < w \le 1\\ 1.19 & \text{if } 1 < w \le 2\\ 1.40 & \text{if } 2 < w \le 3\\ 1.61 & \text{if } 3 < w \le 4\\ \vdots \end{cases}$$

The graph is shown in Figure 18. You can see why functions similar to this one are called **step functions**—they jump from one value to the next. Such functions will be studied in Chapter 2.

Symmetry

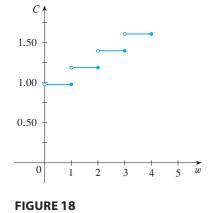
If a function f satisfies f(-x) = f(x) for every number x in its domain, then f is called an **even function**. For instance, the function $f(x) = x^2$ is even because

$$f(-x) = (-x)^2 = x^2 = f(x)$$

The geometric significance of an even function is that its graph is symmetric with respect to the *y*-axis (see Figure 19). This means that if we have plotted the graph of *f* for $x \ge 0$, we obtain the entire graph simply by reflecting this portion about the *y*-axis.

If f satisfies f(-x) = -f(x) for every number x in its domain, then f is called an **odd** function. For example, the function $f(x) = x^3$ is odd because

$$f(-x) = (-x)^3 = -x^3 = -f(x)$$



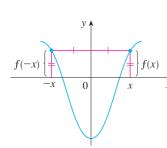


FIGURE 19 An even function

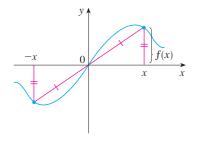


FIGURE 20 An odd function The graph of an odd function is symmetric about the origin (see Figure 20). If we already have the graph of f for $x \ge 0$, we can obtain the entire graph by rotating this portion through 180° about the origin.

EXAMPLE 11 Determine whether each of the following functions is even, odd, or neither even nor odd.

(a)
$$f(x) = x^5 + x$$
 (b) $g(x) = 1 - x^4$ (c) $h(x) = 2x - x^2$

SOLUTION

(a)

$$= -x^{5} - x = -(x^{5} + x)$$
$$= -f(x)$$

 $f(-x) = (-x)^5 + (-x) = (-1)^5 x^5 + (-x)$

Therefore f is an odd function.

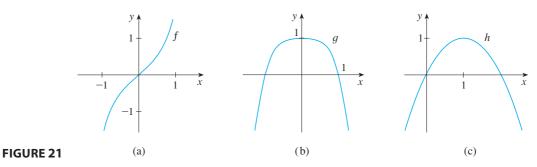
(b)
$$g(-x) = 1 - (-x)^4 = 1 - x^4 = g(x)$$

So g is even.

(c)
$$h(-x) = 2(-x) - (-x)^2 = -2x - x^2$$

Since $h(-x) \neq h(x)$ and $h(-x) \neq -h(x)$, we conclude that *h* is neither even nor odd.

The graphs of the functions in Example 11 are shown in Figure 21. Notice that the graph of h is symmetric neither about the *y*-axis nor about the origin.



Increasing and Decreasing Functions

The graph shown in Figure 22 rises from *A* to *B*, falls from *B* to *C*, and rises again from *C* to *D*. The function *f* is said to be increasing on the interval [a, b], decreasing on [b, c], and increasing again on [c, d]. Notice that if x_1 and x_2 are any two numbers between *a* and *b* with $x_1 < x_2$, then $f(x_1) < f(x_2)$. We use this as the defining property of an increasing function.

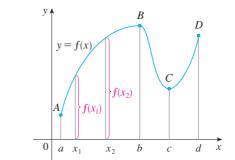


FIGURE 22

Copyright 2016 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it.